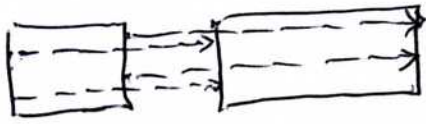


translation no deformation u_x and u_y constant

$$\frac{du_x}{dx} = \frac{du_y}{dy} = \frac{d^2u_x}{dy^2} = \frac{d^2u_y}{dx^2} = 0$$

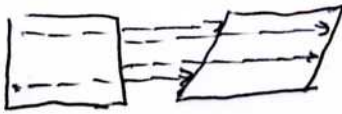
horizontal stretching



$$\frac{du_x}{dx} > 0 \quad \frac{du_x}{dy} = 0$$

$$u_y = 0 \quad \text{so} \quad \frac{du_y}{dx} = \frac{du_y}{dy} = 0$$

shearing (horizontal)



$$\frac{du_x}{dx} = 0 \quad \frac{du_x}{dy} > 0$$

$$u_y = 0 \quad \text{so} \quad \frac{du_y}{dx} = \frac{du_y}{dy} = 0$$

counterclockwise
rotation by 45°

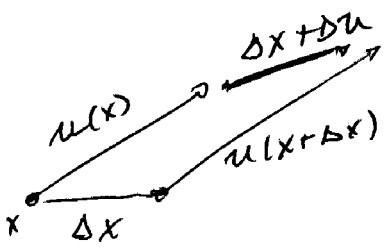


$$\frac{du_x}{dx} = 0 \quad \frac{du_x}{dy} = 0$$

$$\frac{du_y}{dx} > 0 \quad \frac{du_y}{dy} = 0$$

last case, rotation, not deformation,

so $\frac{du_i}{dx_j} \neq 0$ not limited to deformation



Has its length changed

before $l_1 = |\Delta x|$

after $l_2 = |\Delta x + \Delta u|$

$$l_2^2 = |\Delta x + \Delta u|^2 = \left| \Delta x + \frac{du}{dx} dx \right|^2$$

$$= \left(\Delta x_i + \frac{du_i}{dx_j} \Delta x_j \right) \left(\Delta x_i + \frac{du_i}{dx_j} \Delta x_j \right)$$

now let $\frac{du_i}{dx_j} = \epsilon_{ij} + \Omega_{ij}$

ϵ_{ij} = symmetric
 $= \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$

Ω = antisymmetric
 $= \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right)$

$$l_2^2 = \left(\Delta x_i + \epsilon_{ij} \Delta x_j + \Omega_{ij} \Delta x_j \right) \cdot \left(\Delta x_i + \epsilon_{ij} \Delta x_j + \Omega_{ij} \Delta x_j \right)$$

$$\approx \left(\Delta x_i + 2\epsilon_{ij} \Delta x_i \Delta x_j + 2\Omega_{ij} \Delta x_i \Delta x_j \right)$$

0 because Ω antisym while $\Delta x_i \Delta x_j$ sym

now let v_i = direction of Δx_i

$$\Delta x_i = l_1 v_i$$

$$l_2^2 = l_1^2 + 2l_1^2 \epsilon_{ij} v_i v_j = l_1^2 (1 + 2\epsilon_{ij} v_i v_j)$$

but $(1+\epsilon)^2 \approx 1+2\epsilon$ so

$$l_2 = l_1 (1 + \epsilon_{ij} v_i v_j)$$

$$\frac{l_2 - l_1}{l_1} = \frac{\delta l}{l} = \epsilon_{ij} v_i v_j$$

• Volumetric strain

Δx_2
 Δx_1

$\Delta x_2(1+\epsilon_{22})$
 $\Delta x_1(1+\epsilon_{11})$

~~$V_1 = \Delta x \Delta y \Delta z$~~
 $V_2 = \Delta x \Delta y \Delta z (1+\epsilon_{11})(1+\epsilon_{22})(1+\epsilon_{33})$
 $\frac{\delta V}{V} \approx \epsilon_{11} + \epsilon_{22} + \epsilon_{33} = \epsilon_{ii}$

stress induced by deformation

• E_{ij} analog of Hooke's law

$$f = kx$$

T_{ij} linear related to ϵ_{ij}

general case

$$T_{ij} = \sum_{pq} C_{ijpq} \epsilon_{pq}$$

every comp T depends on all 6 independent comp's of ϵ . 36 ^{independent} coefficients

$$C_{ijpq} = C_{ji pq} \quad T \text{ sym.}$$

$$C_{ijpq} = C_{ij qp} \quad \epsilon \text{ sym}$$

$$C_{ijpq} = C_{pqij} \quad \rightarrow 36 \rightarrow 21$$

21 elasticity components!

special case: isotropic material 2 constants

$$C_{ijpq} = \lambda \delta_{ij} \delta_{pq} + \mu (\delta_{ip} \delta_{jq} + \delta_{iq} \delta_{jp})$$

$$T_{ij} = \lambda \delta_{ij} \delta_{pq} \epsilon_{pq} + \mu \delta_{ip} \delta_{jq} \epsilon_{pq} + \mu \delta_{iq} \delta_{jp} \epsilon_{pq}$$

$$T_{ij} = \lambda \delta_{ij} \epsilon_{pp} + 2\mu \epsilon_{ij}$$

↑
volumetric
strain

Pressure: inward force per unit area acting normal to surface, independent on direction of surface

$$\mathbf{T}_i = \tau_{ij} \cdot \mathbf{n}_j$$

$$\tau_{ij} = -P \delta_{ij}$$

ideal gas law

Newton's law for solid

~~$$\mathbf{F} = m\mathbf{a} = \mathbf{f}$$~~

$$\int_{\text{volume}} \rho \ddot{u}_i dV = \int_{\text{surface}} T_i dA$$

$$= \int_{\text{surface}} \tau_{ij} n_j dA = \int_{\text{volume}} \text{div}(\tau_{ij}) dV$$

true for any volume

$$\rho \ddot{u}_i = \text{div}(\tau_{ij}) = \frac{d}{dx_j} \tau_{ij}$$

$$\rho \ddot{u}_i = \frac{d}{dx_j} \tau_{ij} = \frac{d}{dx_j} [C_{ijpq} \epsilon_{pq}] =$$

$$= \frac{d}{dx_j} [\lambda \delta_{ij} \epsilon_{pp} + 2\mu \epsilon_{ij}]$$

assumed, μ const.

$$= \frac{d}{dx_j} \left[\lambda \delta_{ij} \frac{du_p}{dx_p} + \mu \frac{\partial u_i}{\partial x_j} + \mu \frac{\partial u_j}{\partial x_i} \right]$$

$$\rho \ddot{u}_i = \lambda \frac{d}{dx_i} \frac{d}{dx_p} u_p + \mu \frac{d}{dx_j} \frac{d}{dx_j} u_i + \mu \frac{d}{dx_p} \frac{d}{dx_j} u_j$$

$$= \text{div} (\lambda + \mu) \frac{d}{dx_i} \frac{d}{dx_j} u_j + \mu \frac{d}{dx_p} \frac{d}{dx_j} u_i$$