

Solid Earth Dynamics

Bill Menke, Instructor

Lecture 13

Today

Shear Stress

Earthquake Stresses

Normal stress

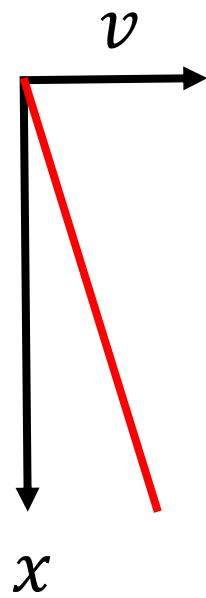
angular momentum and torque

plate flexure

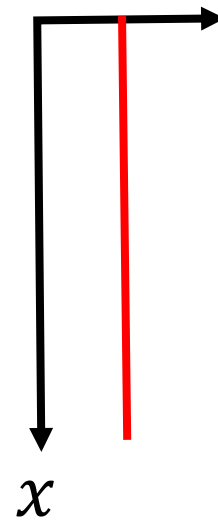
Shear Stress



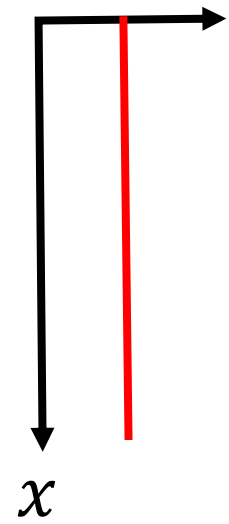
displacement



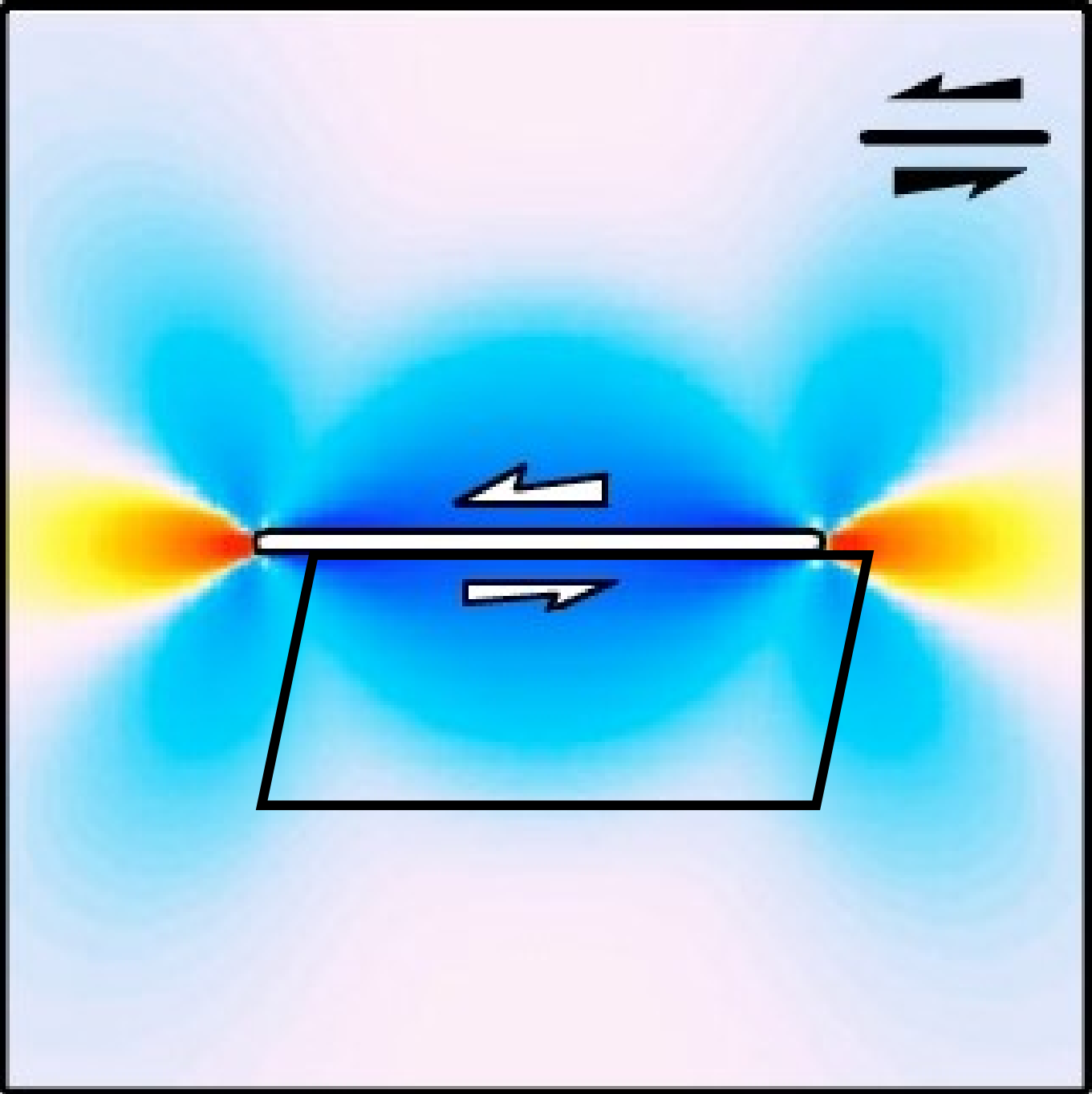
shear strain

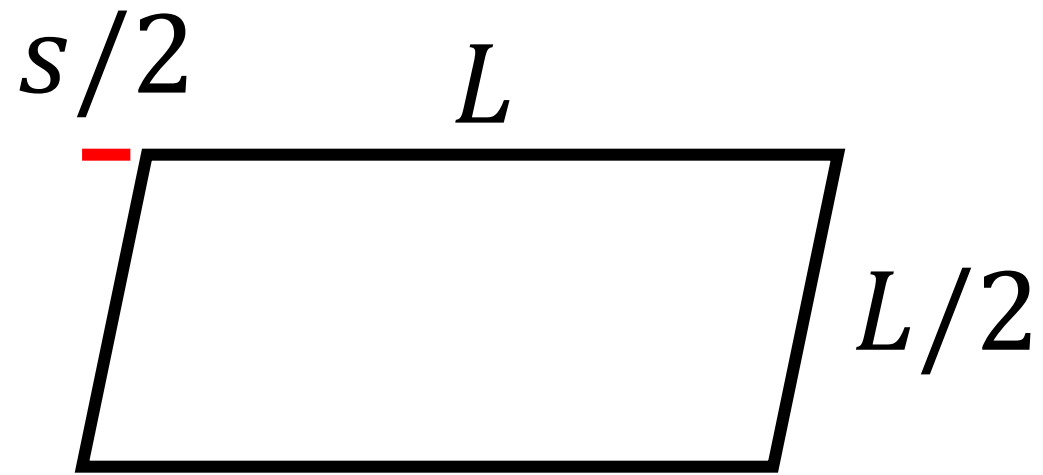


shear stress



Stress Change due to Earthquake

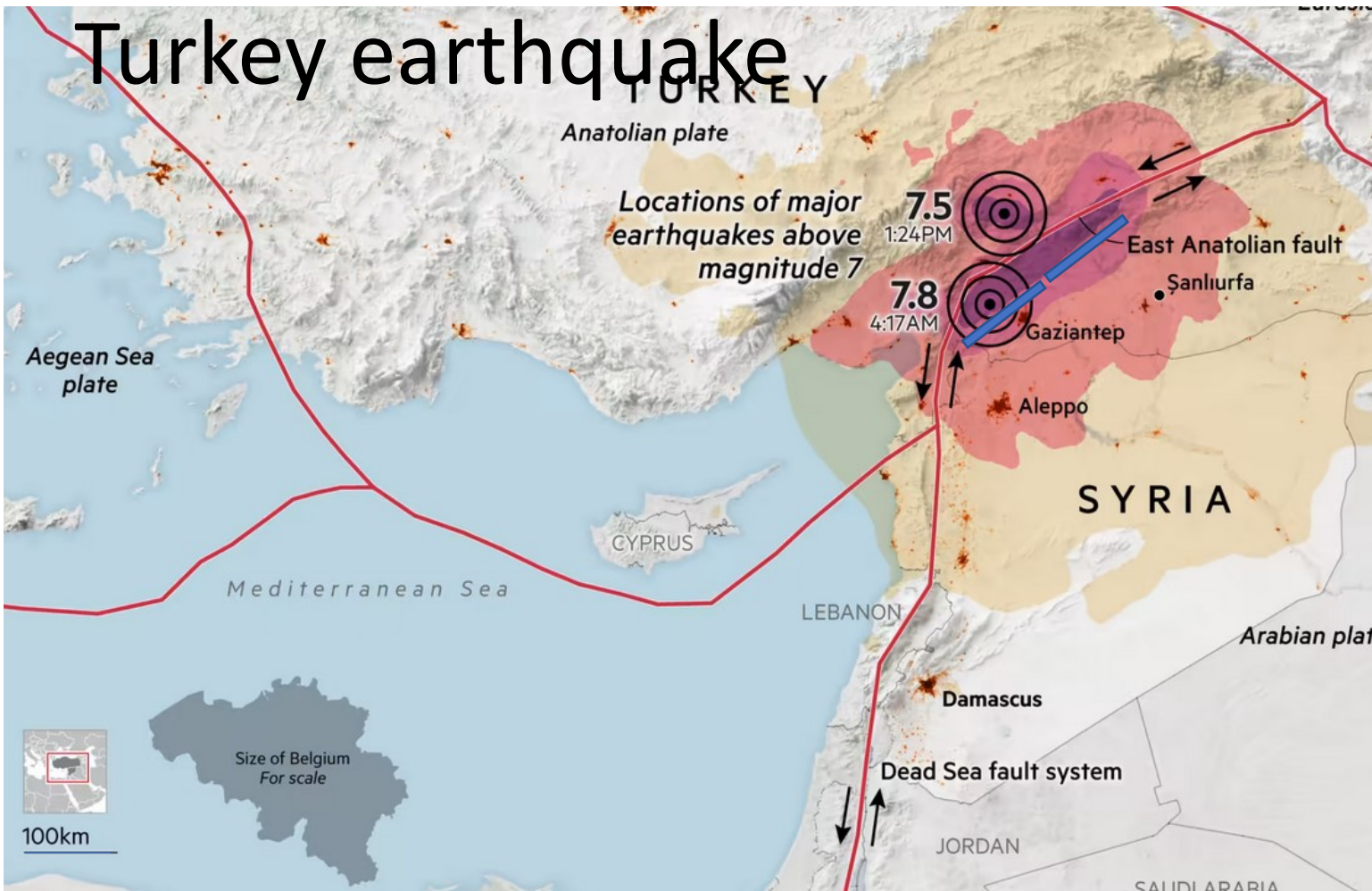




shear strain $\frac{s/2}{L/2} = \frac{s}{L}$

shear stress $\mu \frac{s}{L}$ μ shear modulus

Turkey earthquake



$$L = 200000 \text{ m}$$

$$s = 3 \text{ m}$$

maximum strain

$$s = 3/200000$$

*maximum stress
decrease*

$$\sigma = 0.4 \text{ Mpa}$$

$$= 4 \text{ bars} = 4 \text{ atmospheres}$$

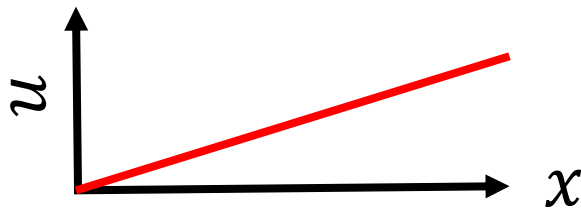
$$\mu = 27 \text{ Gpa (granite)}$$

failure = a few Mpa

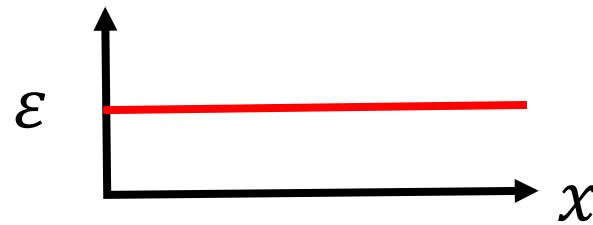
extensional stress



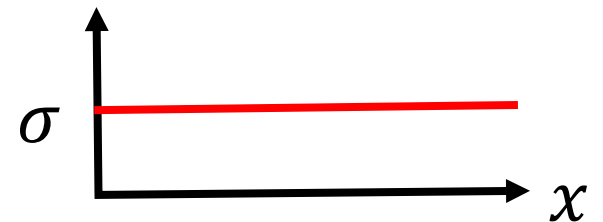
displacement



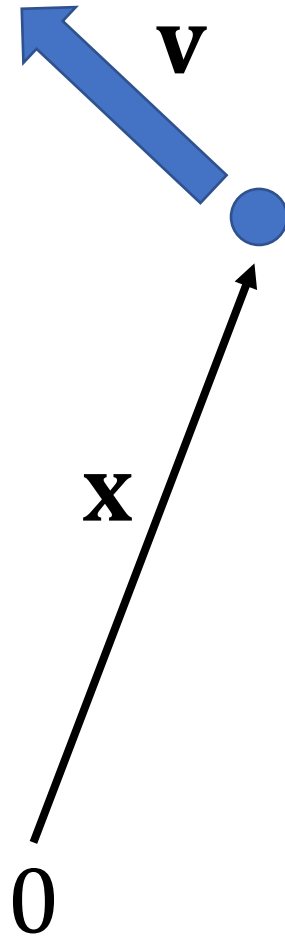
normal strain

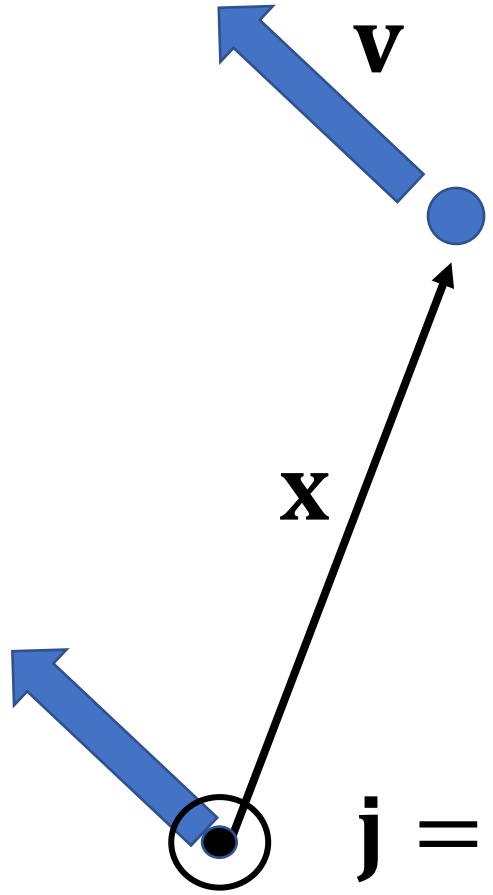


normal stress



Newton's Law applied to rotation

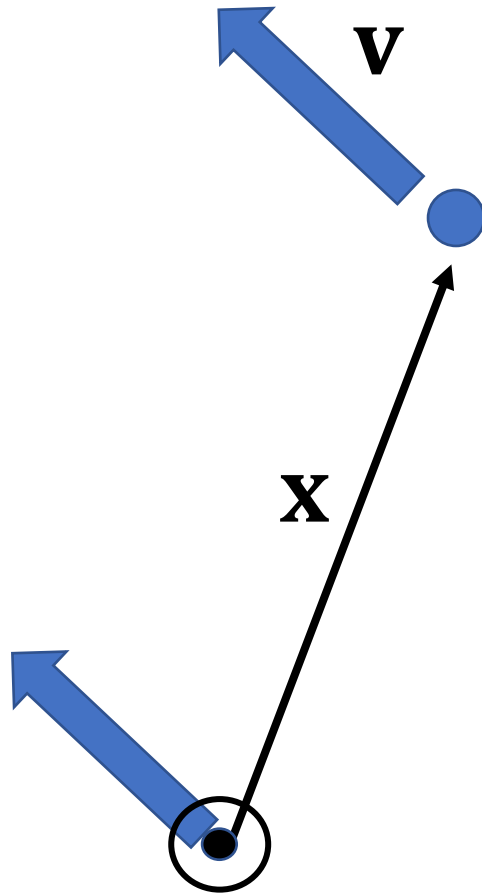


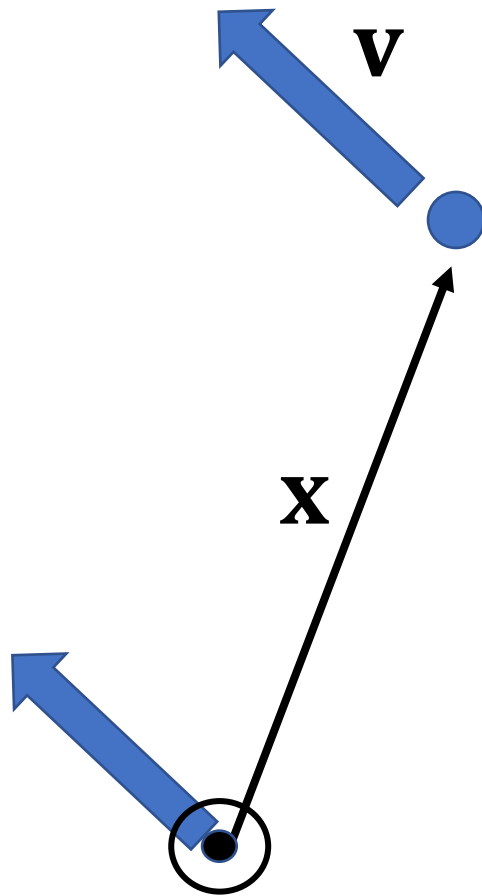


$$\mathbf{j} = \mathbf{x} \times m\mathbf{v}$$

vector parallel to rotation axis

$$\mathbf{j} = \mathbf{x} \times m\mathbf{v} = \mathbf{x} \times m \frac{d\mathbf{x}}{dt}$$





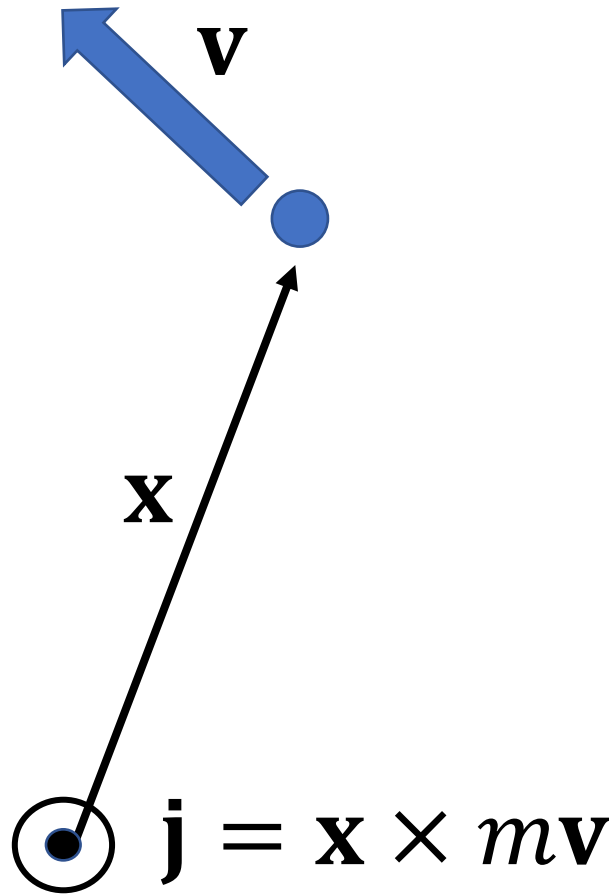
$$\frac{d\mathbf{j}}{dt} = \frac{d}{dt} \left(\mathbf{x} \times m \frac{d\mathbf{x}}{dt} \right)$$

$$\frac{d\mathbf{j}}{dt} = m \frac{d\mathbf{x}}{dt} \times \frac{d\mathbf{x}}{dt} + \mathbf{x} \times m \frac{d^2\mathbf{x}}{d^2t}$$

$$= m \quad 0 + \mathbf{x} \times m \frac{d^2\mathbf{x}}{d^2t}$$

$$= \mathbf{x} \times \mathbf{f}$$

$$= \mathbf{T} \quad \text{torque}$$

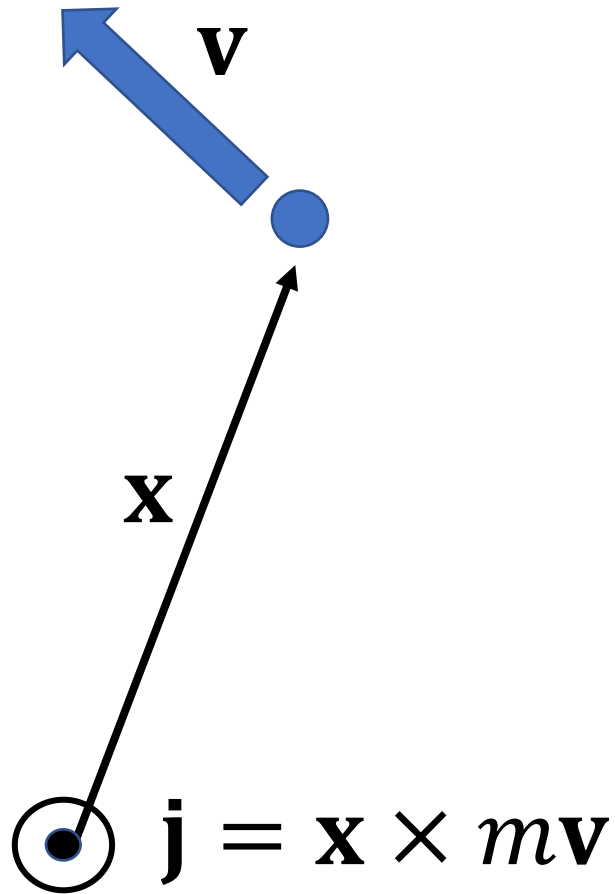


$\mathbf{j} = \mathbf{x} \times m\mathbf{v}$ angular momentum

$\mathbf{T} = \mathbf{x} \times \mathbf{f}$ torque

newton's Law

$$\frac{d\mathbf{j}}{dt} = \mathbf{T}$$



$\mathbf{j} = \mathbf{x} \times m\mathbf{v}$ angular momentum

$\mathbf{T} = \mathbf{x} \times \mathbf{f}$ torque

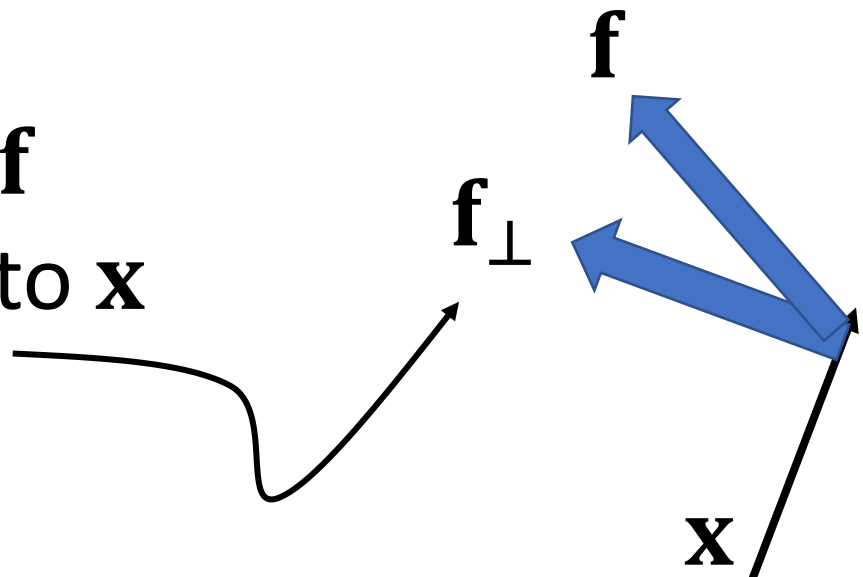
newton's Law

$$\frac{d\mathbf{j}}{dt} = \mathbf{T}$$

no rotation
balance of torques

$$0 = \mathbf{T}$$

component of \mathbf{f}
perpendicular to \mathbf{x}

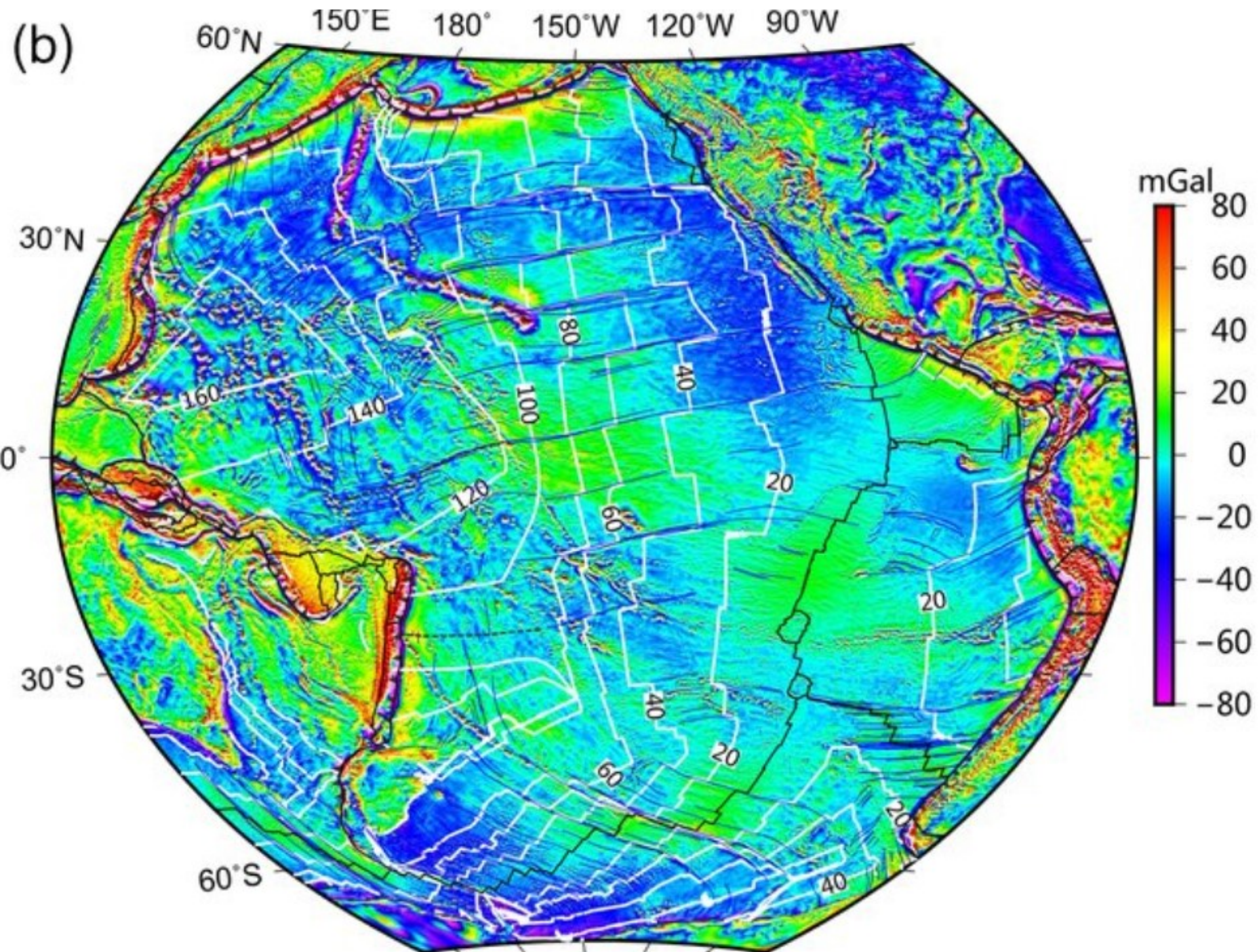


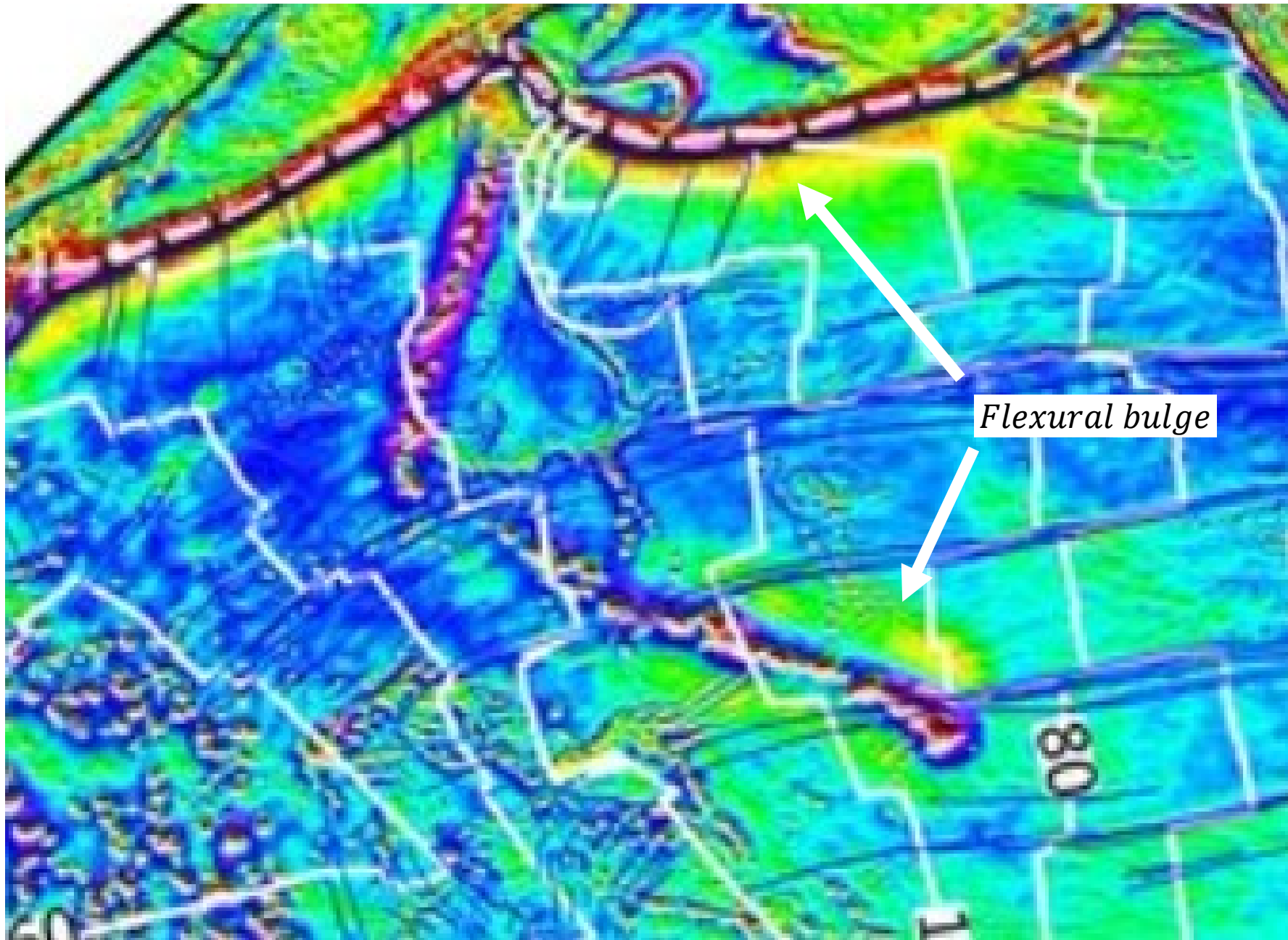
$\odot \mathbf{T} = \mathbf{x} \times \mathbf{f}$

has magnitude

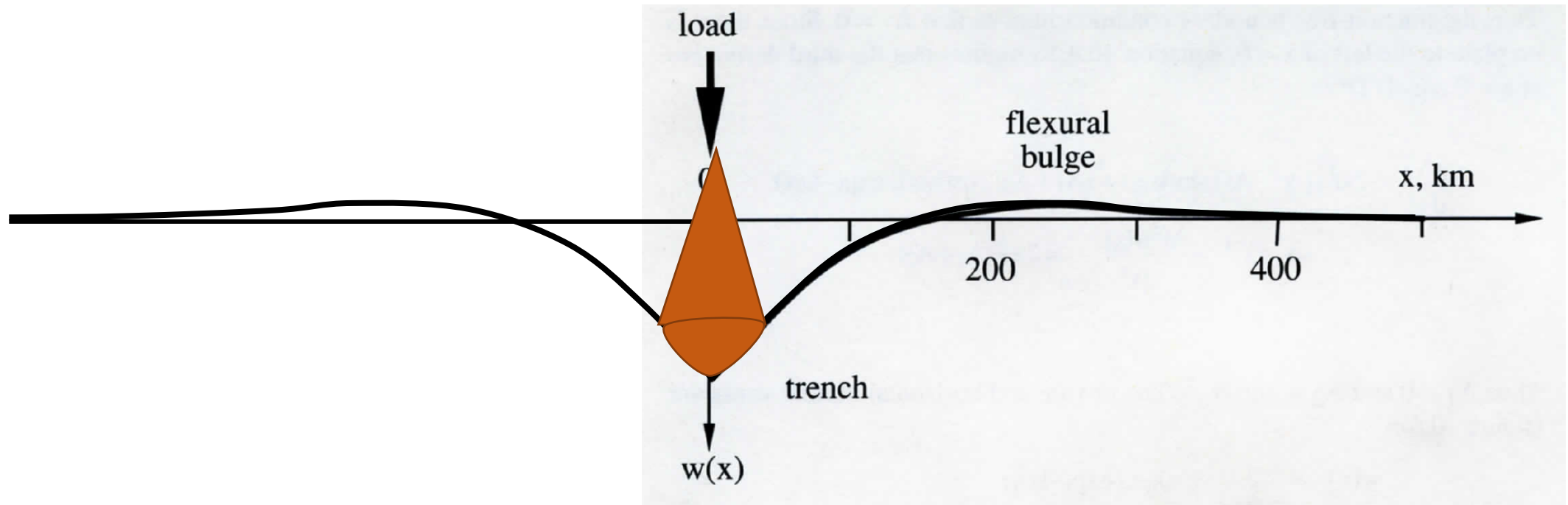
$$|\mathbf{T}| = |\mathbf{x}| |\mathbf{f}_\perp|$$

Lithospheric Flexure

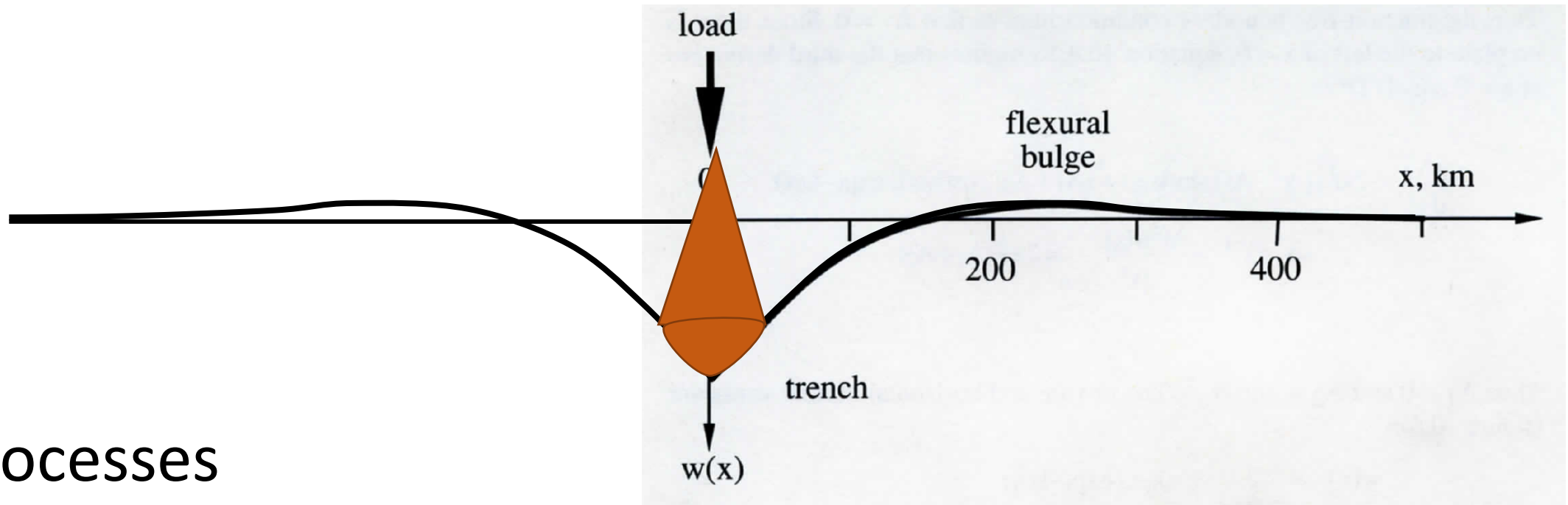




Ocean Island



Ocean Island



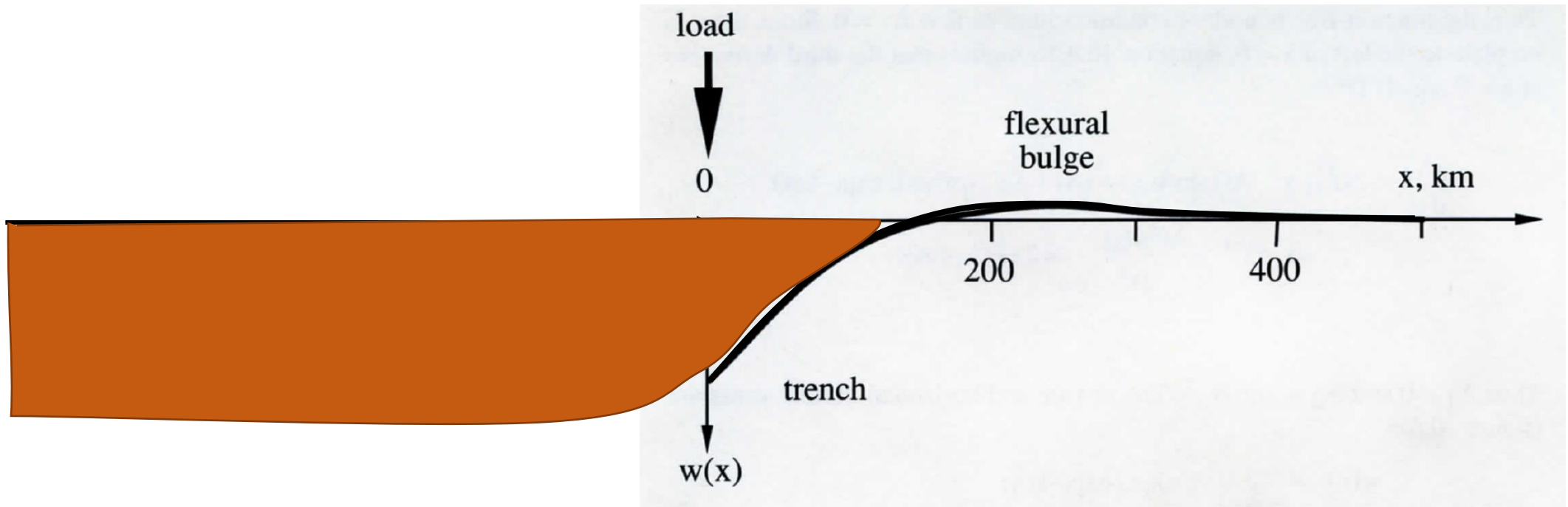
processes

surface forces in plate

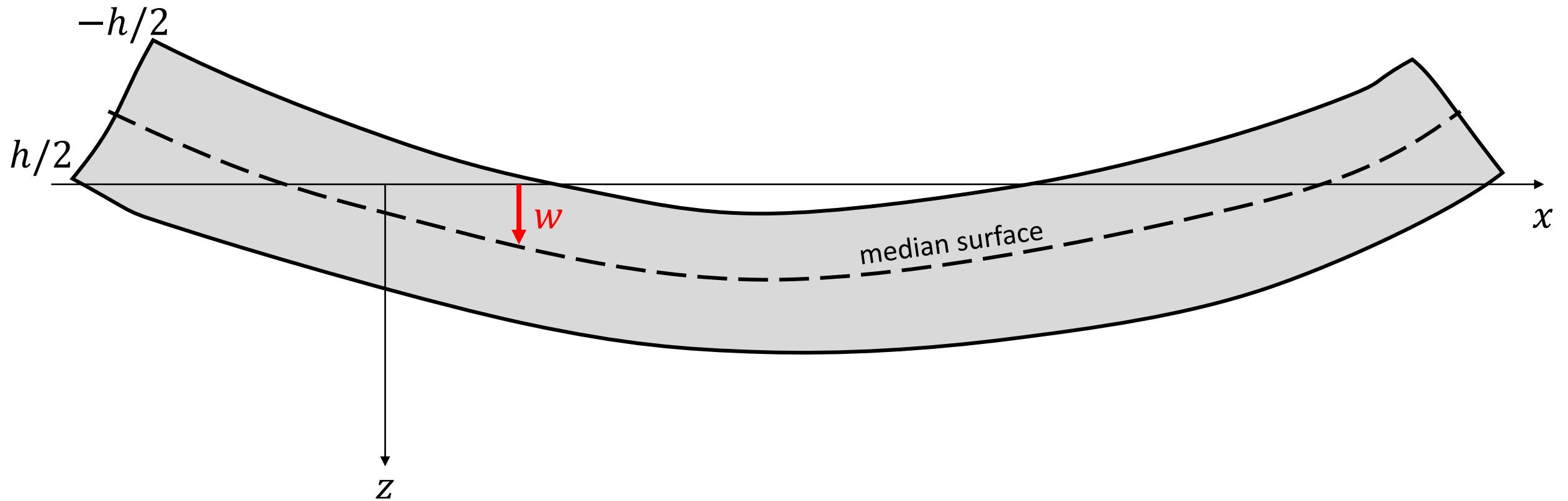
isostasy

gravitational loading (island)

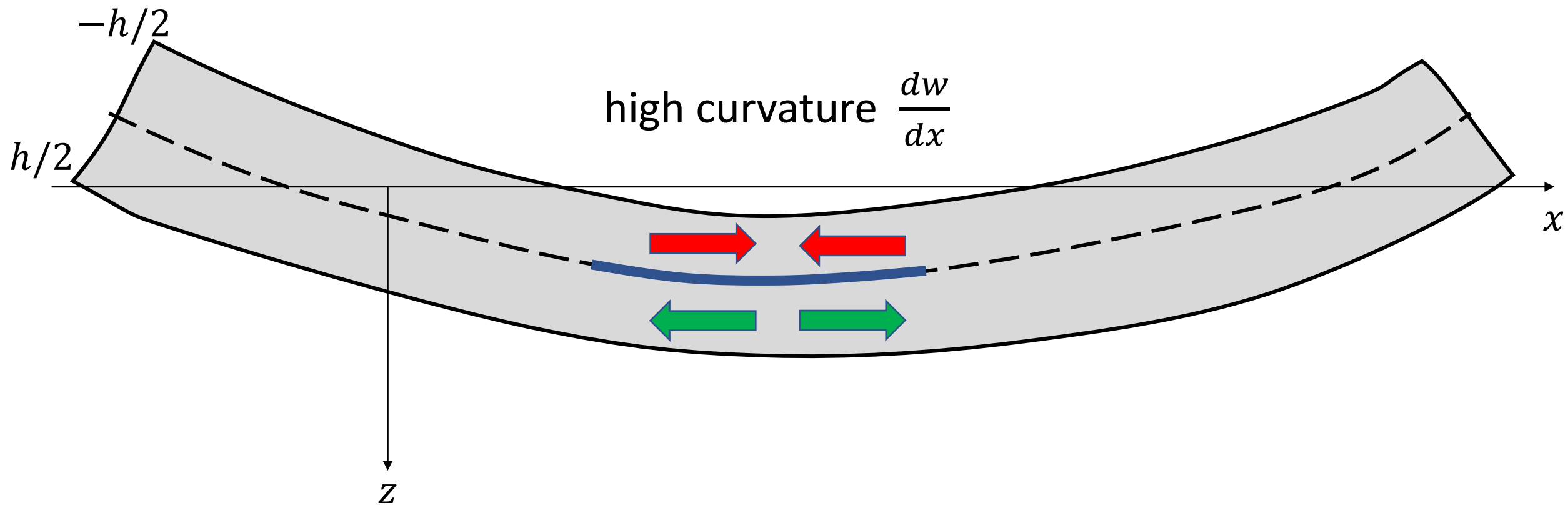
Subduction zone



Flexure $w(x)$ of the median surface



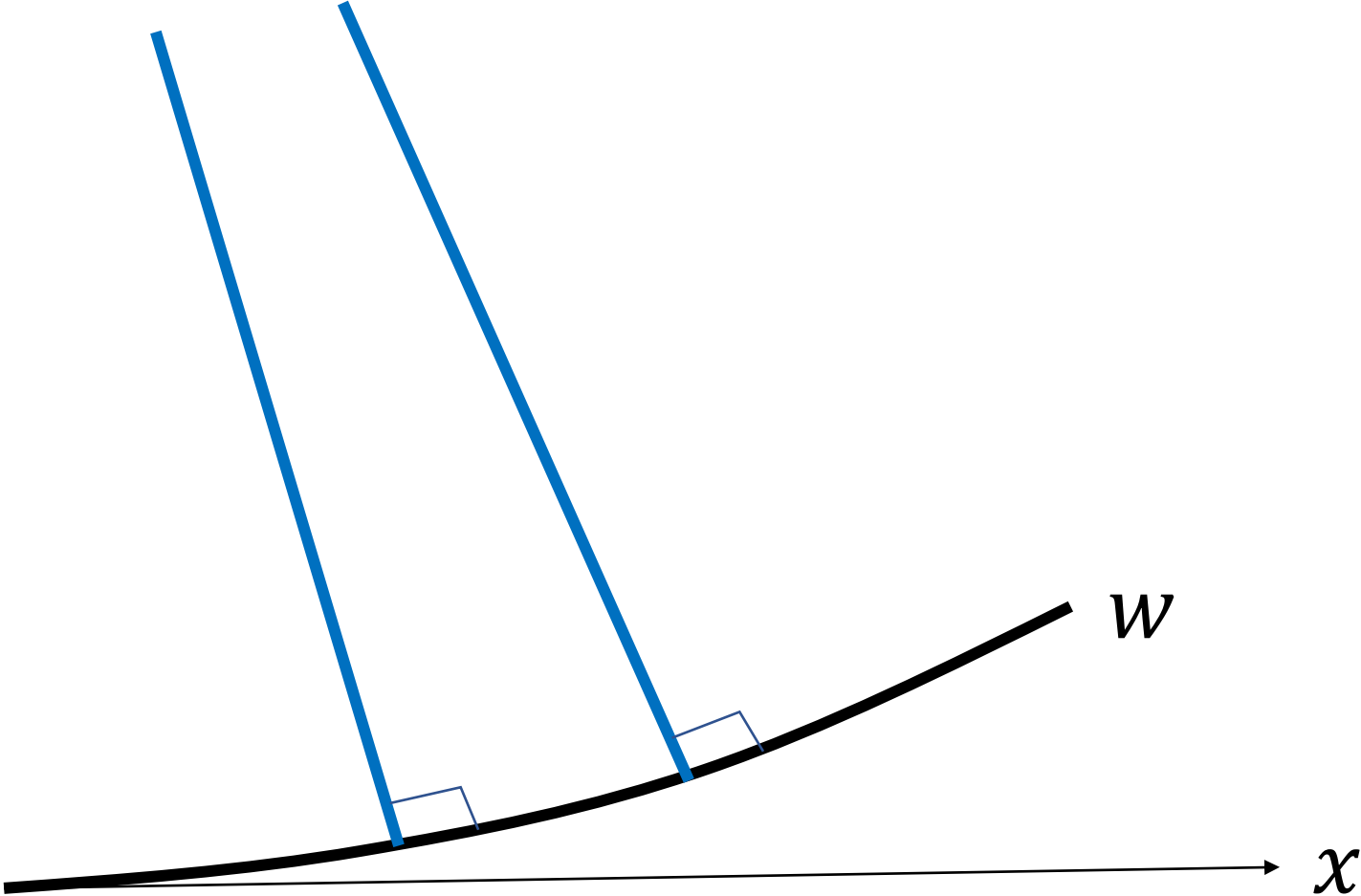
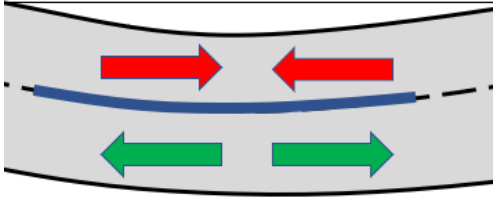
extension and compression related to curvature



Step 1: relating normal stress to flexure

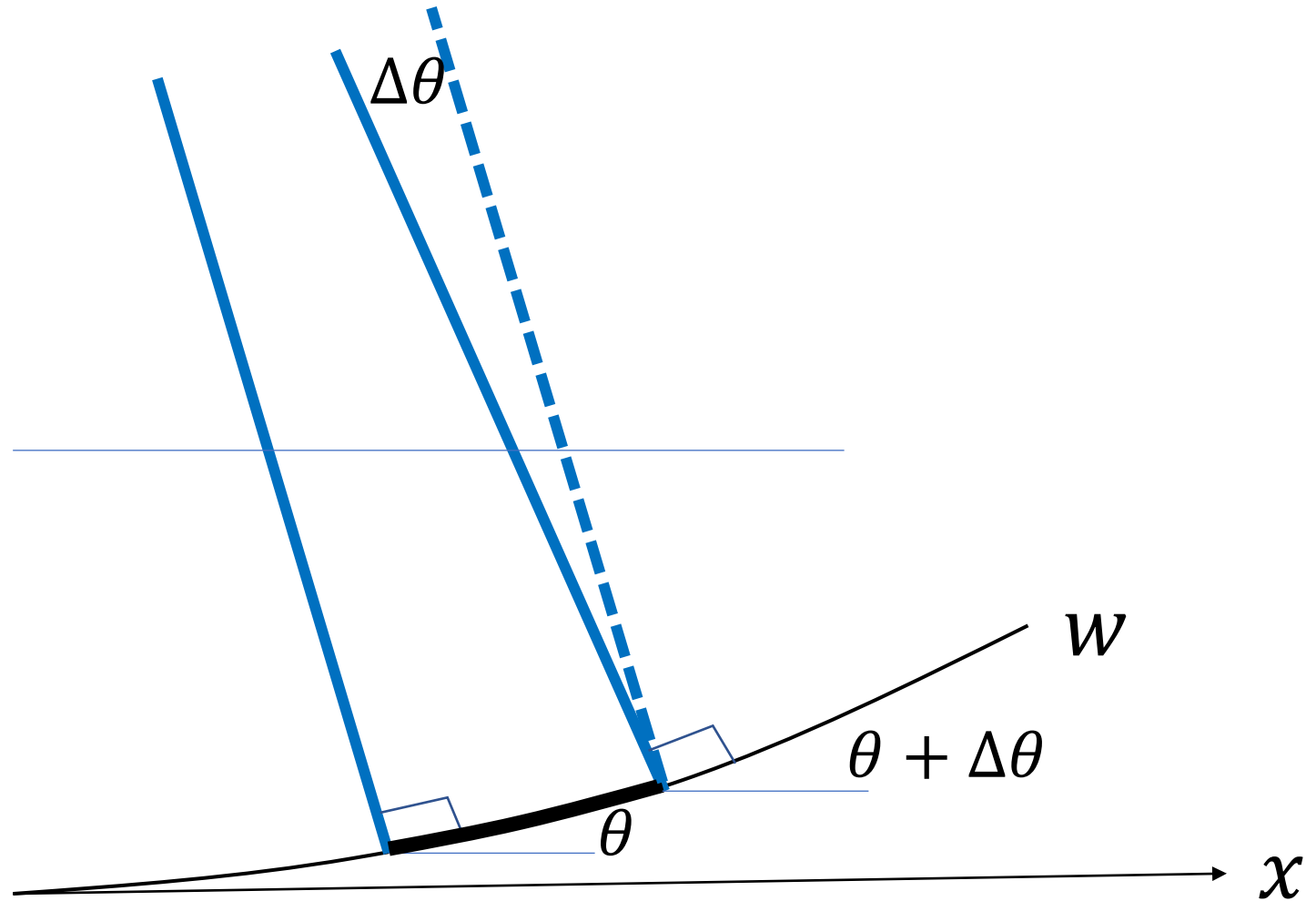
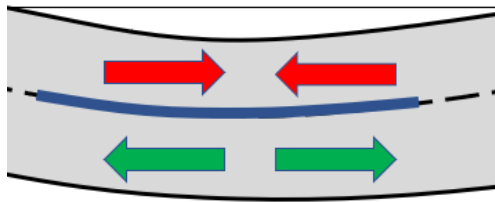
extension and compression related to curvature

high curvature $\frac{dw}{dx}$

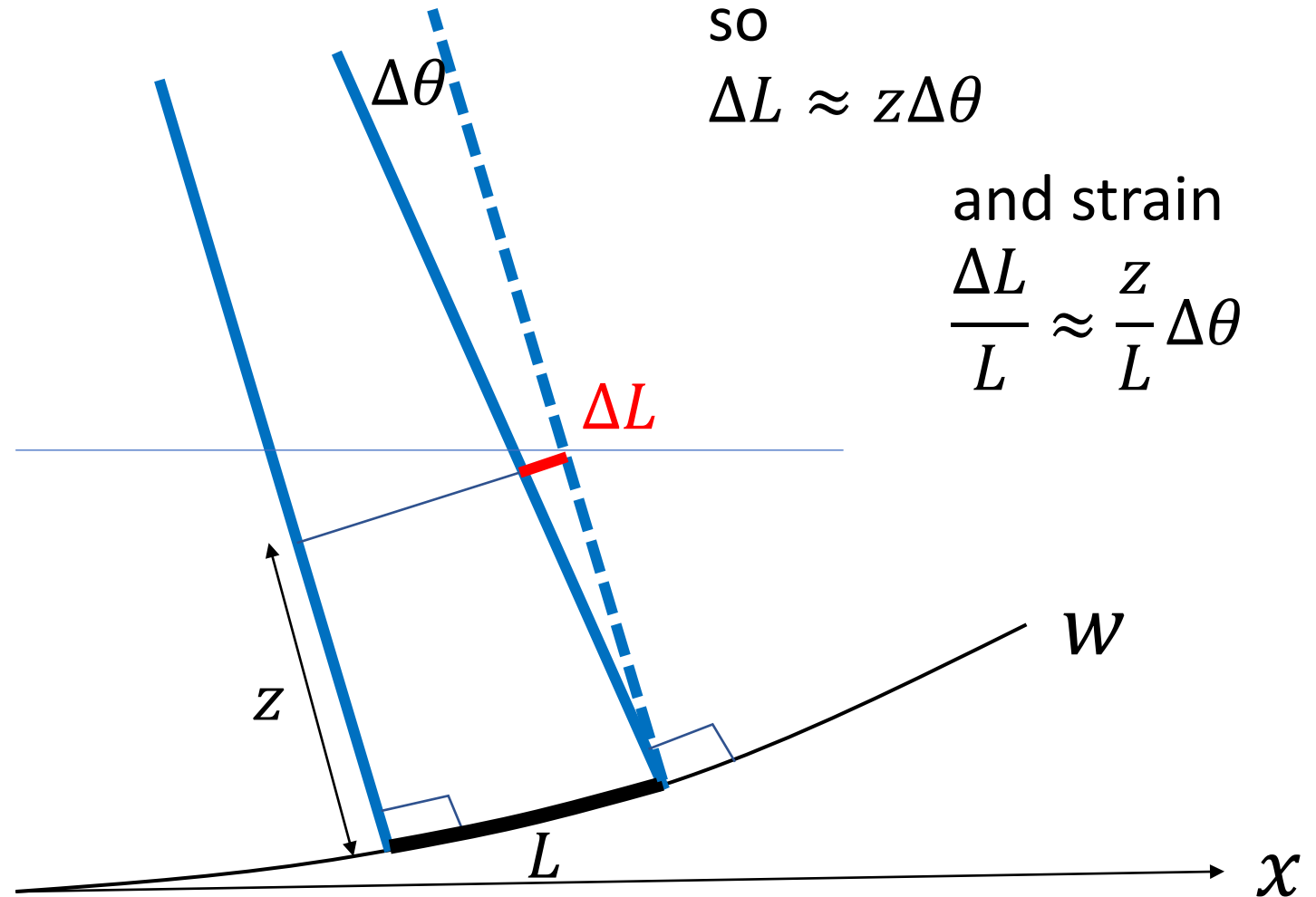
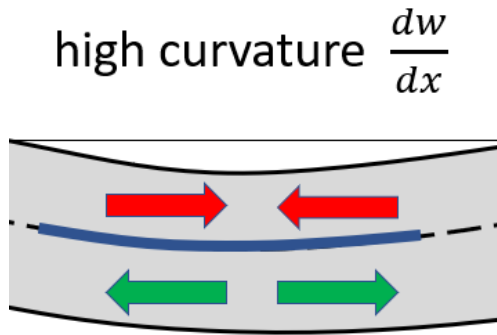


extension and compression related to curvature

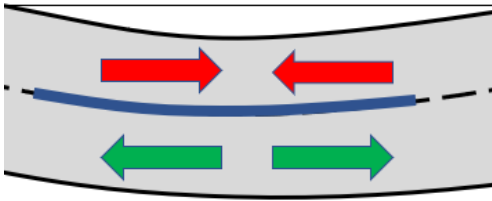
high curvature $\frac{dw}{dx}$



for small angles
 $\sin \Delta\theta \approx \tan \Delta\theta \approx \Delta\theta$



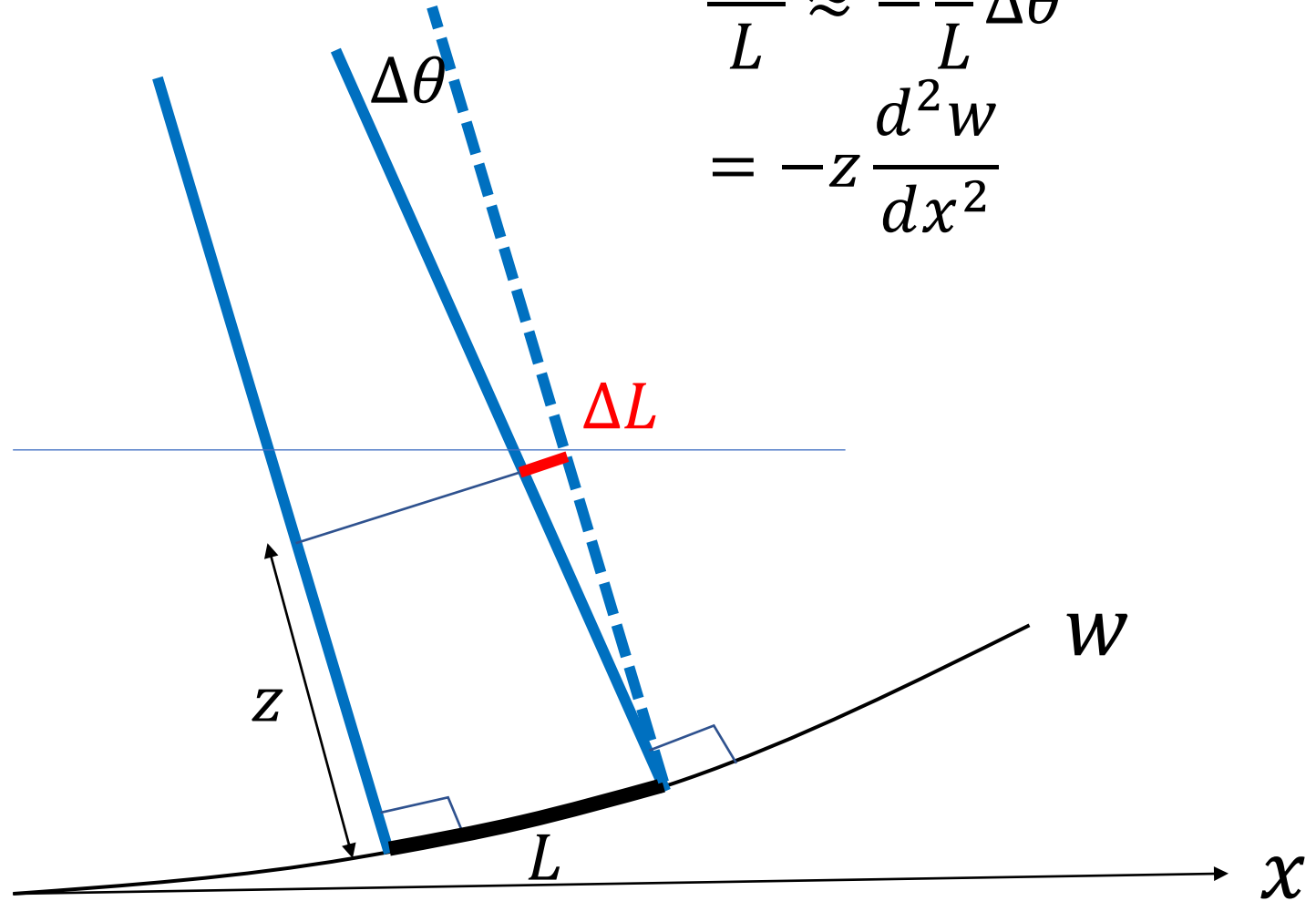
high curvature $\frac{dw}{dx}$



slope of curve

$$\frac{dw}{dx} \approx \tan \theta \approx \theta$$

$$\Delta\theta = \frac{d\theta}{dx} L = \frac{d^2w}{dx^2} L$$



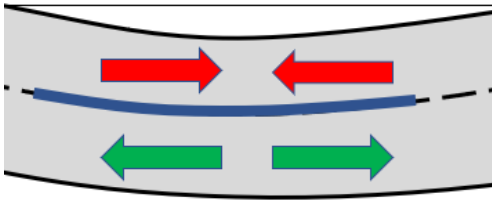
so strain

$$\frac{\Delta L}{L} \approx -\frac{z}{L} \Delta\theta$$

$$= -z \frac{d^2w}{dx^2}$$

Assume linear elasticity

high curvature $\frac{dw}{dx}$

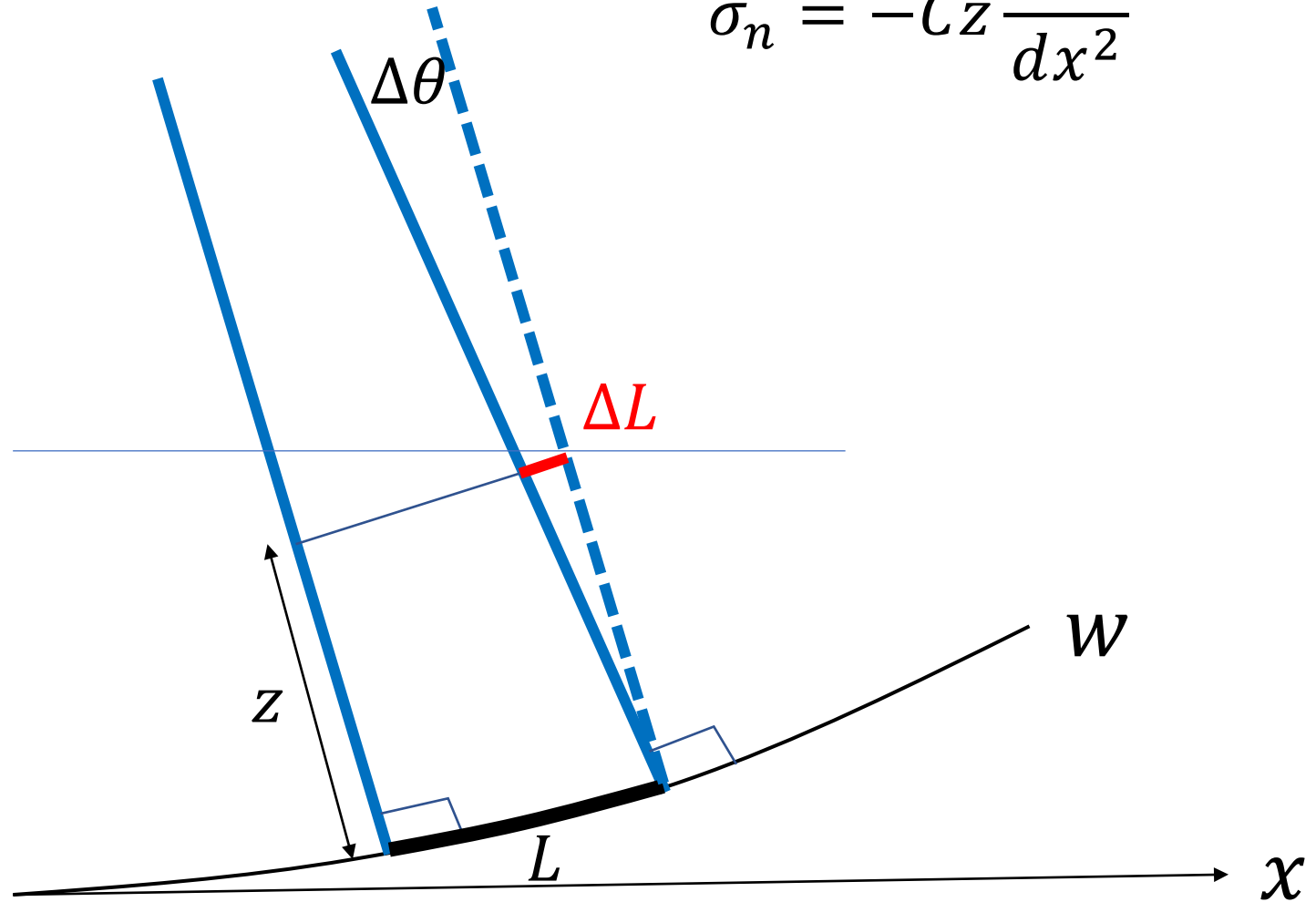


stress proportional to strain

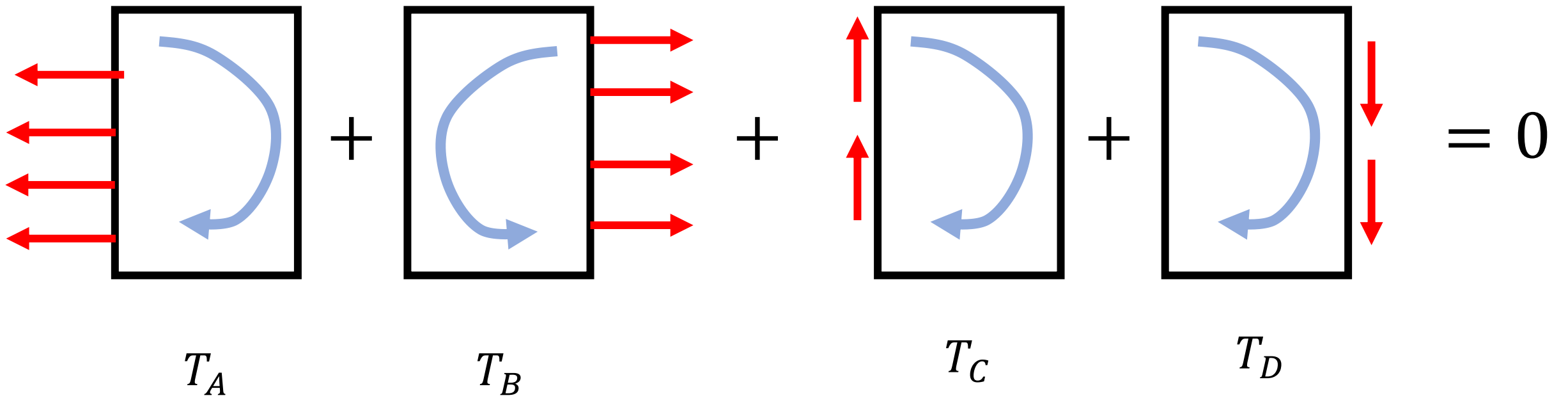
stress = C times strain

so horizontal stress

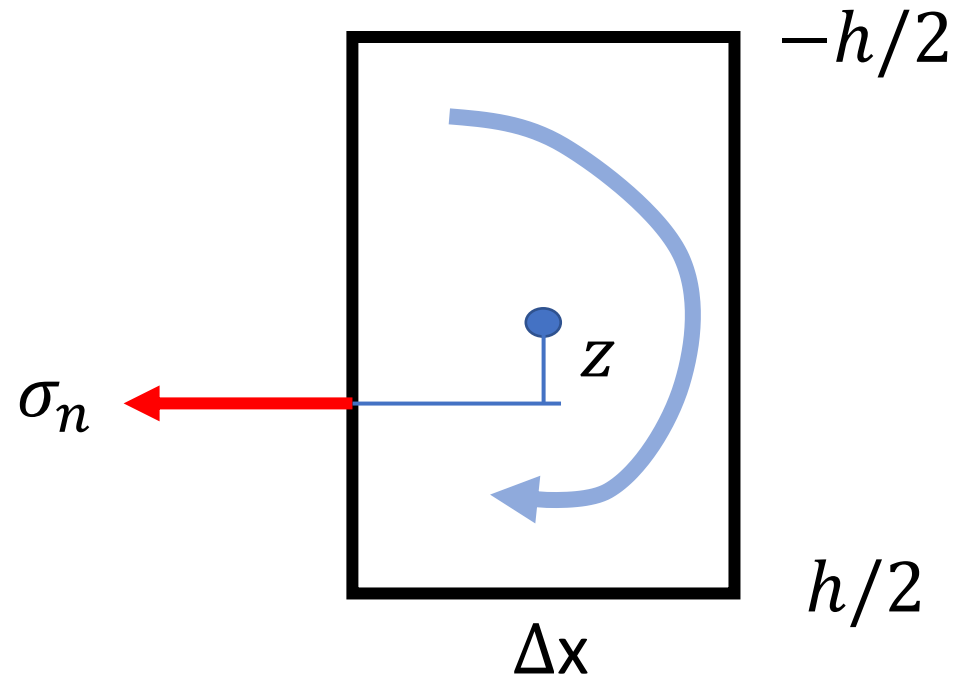
$$\sigma_n = -Cz \frac{d^2w}{dx^2}$$



Step 2: Balance of vertical forces

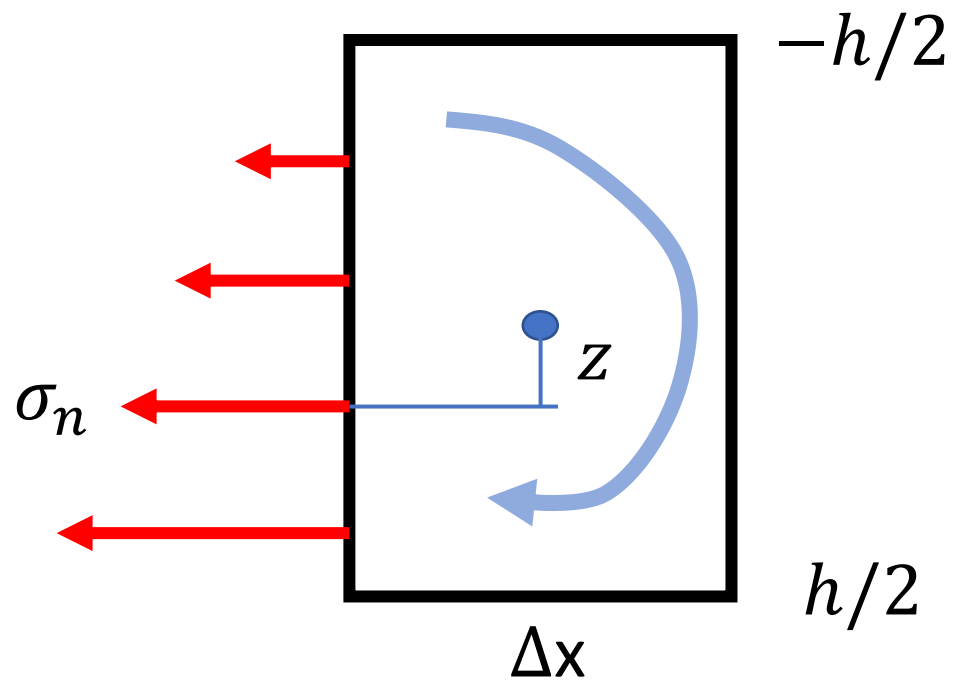


Torque T_A on left surface from normal stress $\sigma_n(x)$



$$\text{Torque: } T_A = -z\sigma_n Y$$

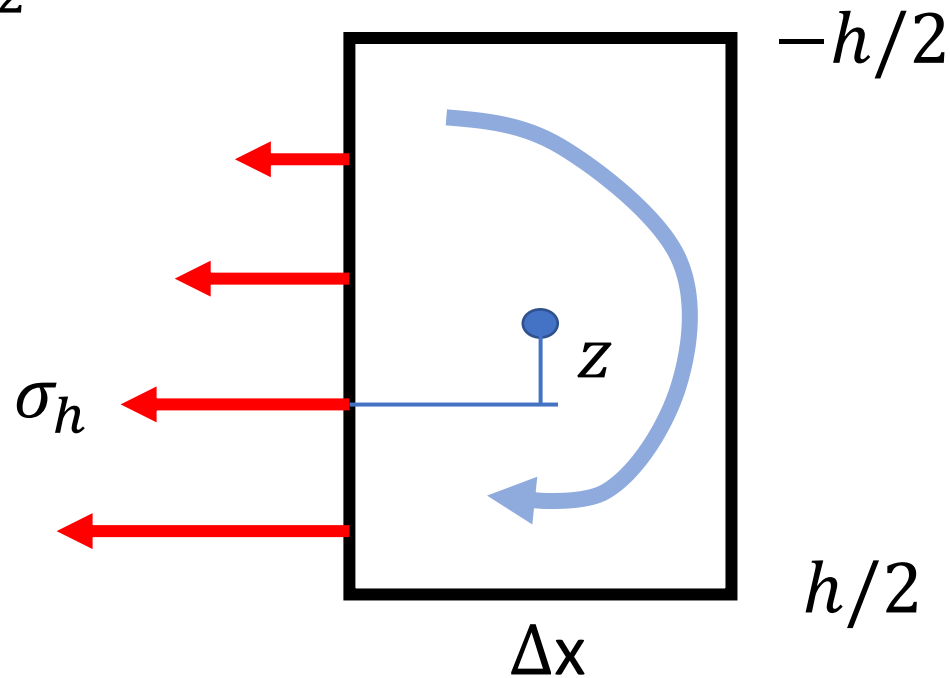
Y : distance into plane of drawing



Torque: hY time average value of $-(z\sigma_n)$
 $T_A(x) = -hY \text{ avg}[z\sigma_n(x)]$

but

$$\sigma_n = -Cz \frac{d^2 w}{dx^2}$$



Flexural rigidity

$$D = \frac{Ch^3}{12}$$

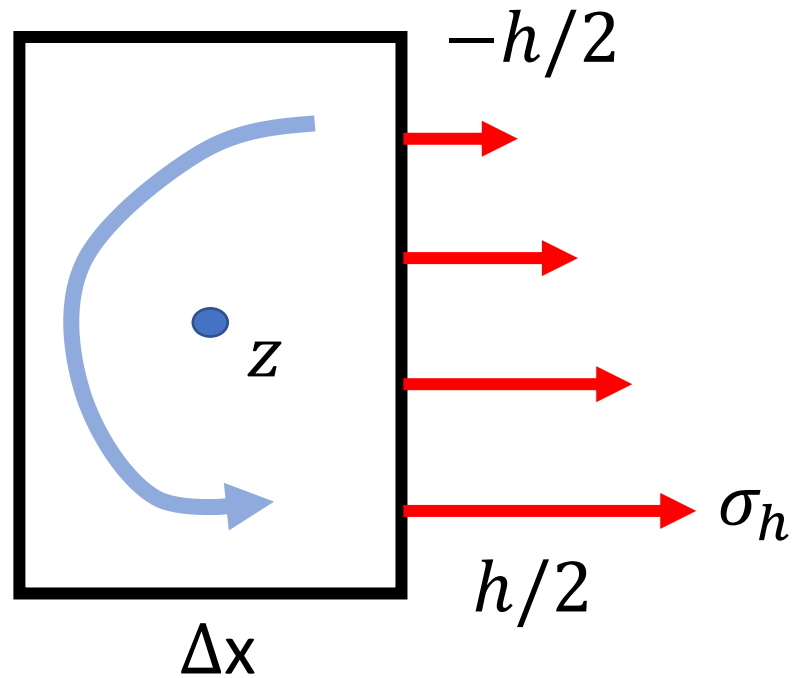
$$T_A(x) = -hY \text{ avg}[z\sigma_n(x)] = -ChY \frac{d^2 w}{dx^2} \text{ avg } z^2 = -\frac{Ch^3}{12} Y \frac{d^2 w}{dx^2} = -DY \left[\frac{d^2 w}{dx^2} \right]_x$$

You're not responsible for this, but here's how to compute the average

$$\text{avg } z^2 = \frac{1}{h} \int_{-h/2}^{h/2} z^2 dz = \frac{2}{h} \int_0^{h/2} z^2 dz = \frac{2}{3h} z^3 \Big|_0^{h/2} =$$

$$\frac{2}{3h} \left(\frac{h}{2} \right)^3 = \frac{h^2}{12}$$

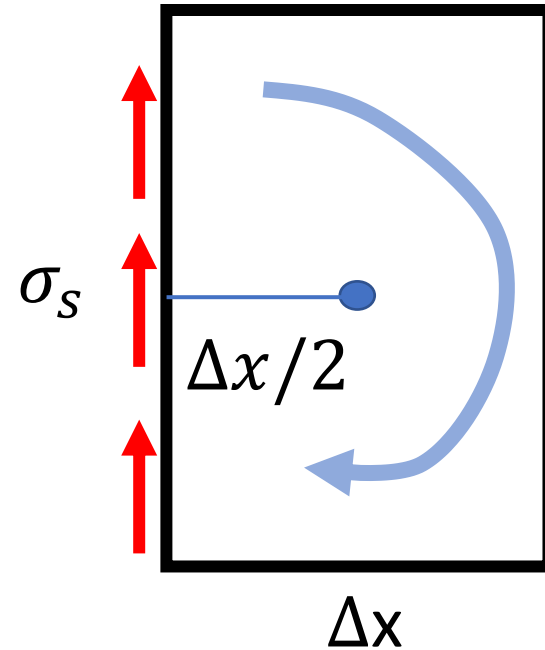
Torque T_B on right surface due to σ_h



Torque:

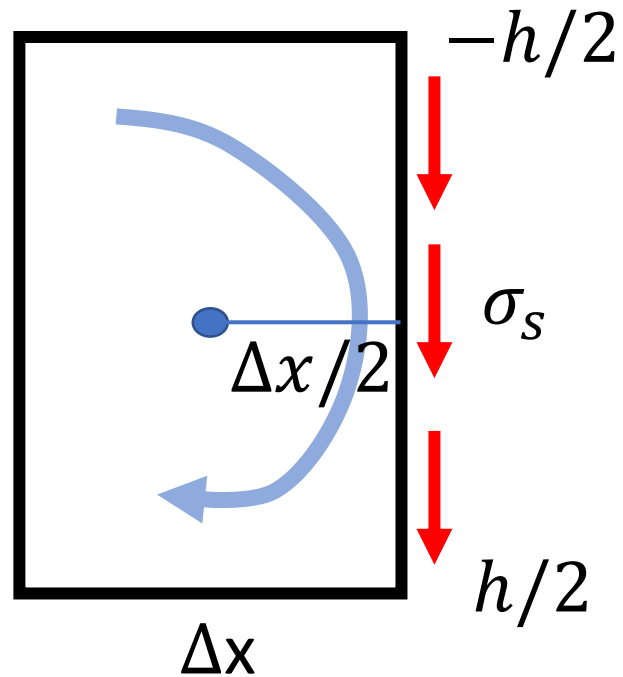
$$T_h(x) = DY \left[\frac{d^2 w}{dx^2} \right]_{x+\Delta x}$$

Torque T_C on left surface from shear stress $\sigma_s(x)$



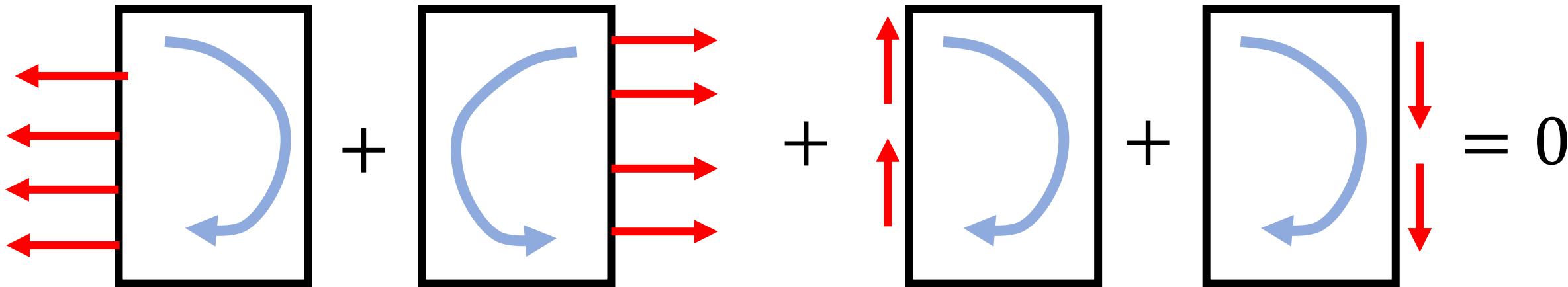
$$\text{Torque: } T_C = -\frac{\Delta x}{2} h Y \sigma_s(x)$$

Torque T_D on right surface from shear stress $\sigma_s(x + \Delta x)$



$$\text{Torque: } T_D = -\frac{\Delta x}{2} h Y \sigma_s(x + \Delta x)$$

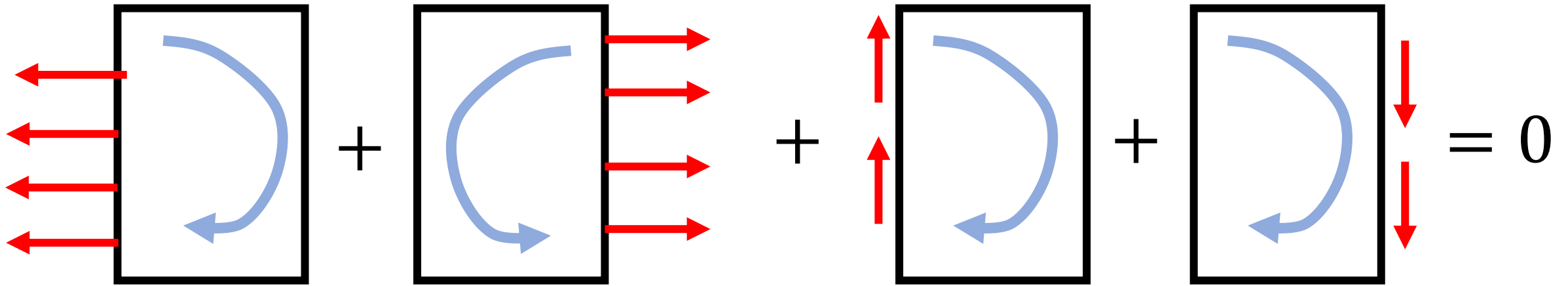
Balance of Torques



$$\begin{aligned}
 & T_A \quad T_B \quad T_C \quad T_D \\
 & -DA \left[\frac{d^2w}{dx^2} \right]_x + DA \left[\frac{d^2w}{dx^2} \right]_{x+\Delta x} - \frac{\Delta x}{2} hY \sigma_s(x) + - \frac{\Delta x}{2} hY \sigma_s(x + \Delta x) = 0
 \end{aligned}$$

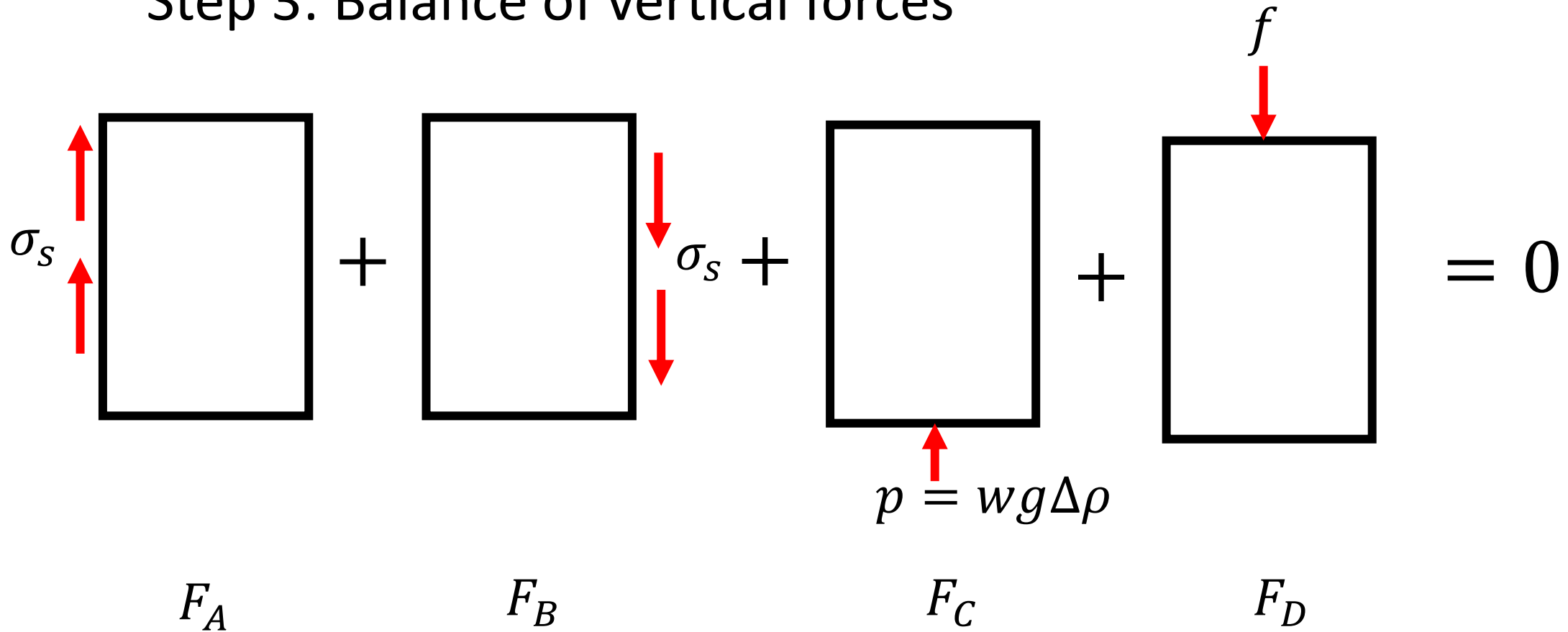
$$D \frac{d^3w}{dx^3} - h\sigma_s(x) = 0$$

Balance of Torques

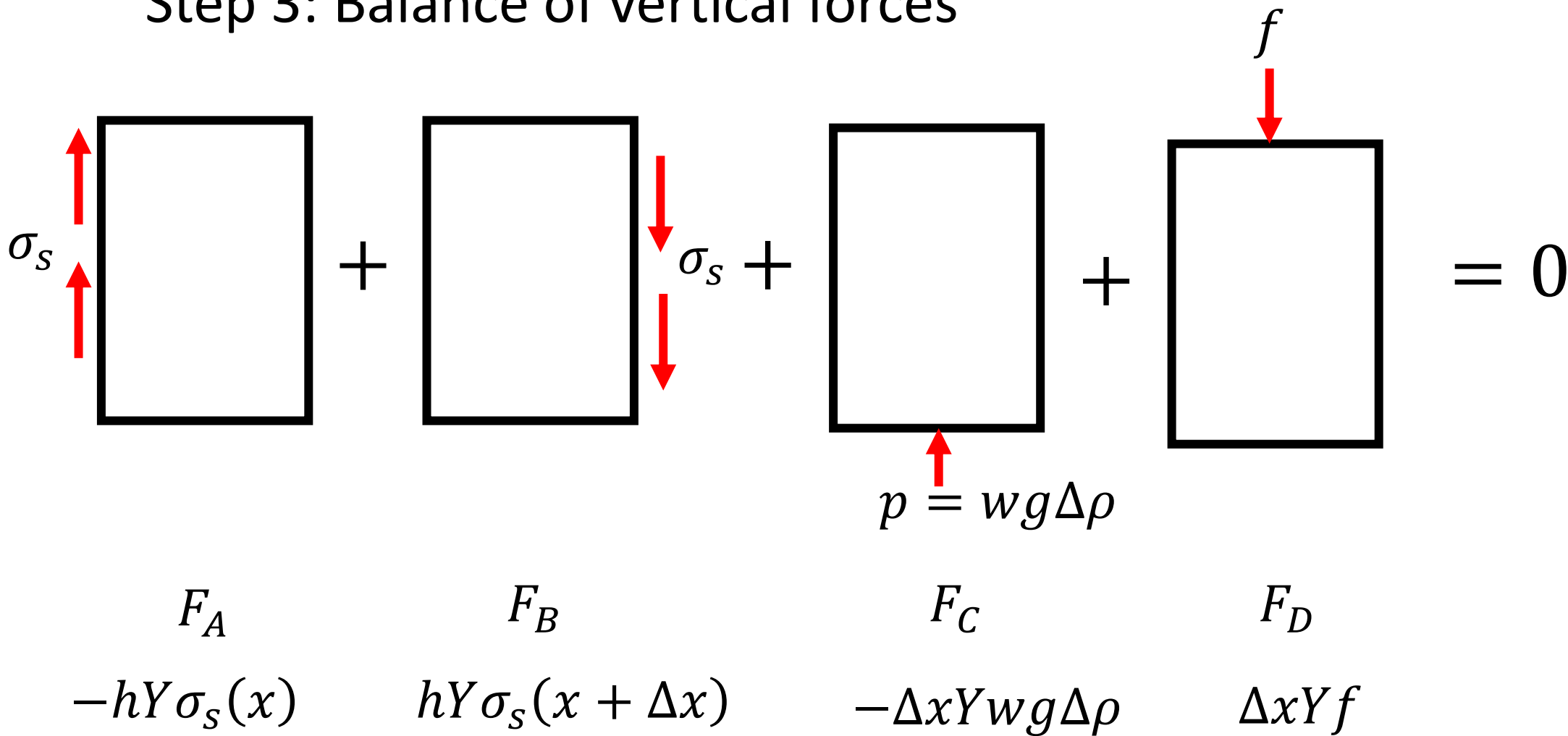


$$\begin{aligned}
 & T_A \quad T_B \quad T_C \quad T_D \\
 & -DA \left[\frac{d^2 w}{dx^2} \right]_x + DA \left[\frac{d^2 w}{dx^2} \right]_{x+\Delta x} - \frac{\Delta x}{2} hY \sigma_s(x) + - \frac{\Delta x}{2} hY \sigma_s(x + \Delta x) = 0 \\
 & D \frac{d^3 w}{dx^3} - h \sigma_s(x) = 0 \quad \Rightarrow \quad D \frac{d^4 w}{dx^4} - h \frac{d\sigma_s}{dx} = 0
 \end{aligned}$$

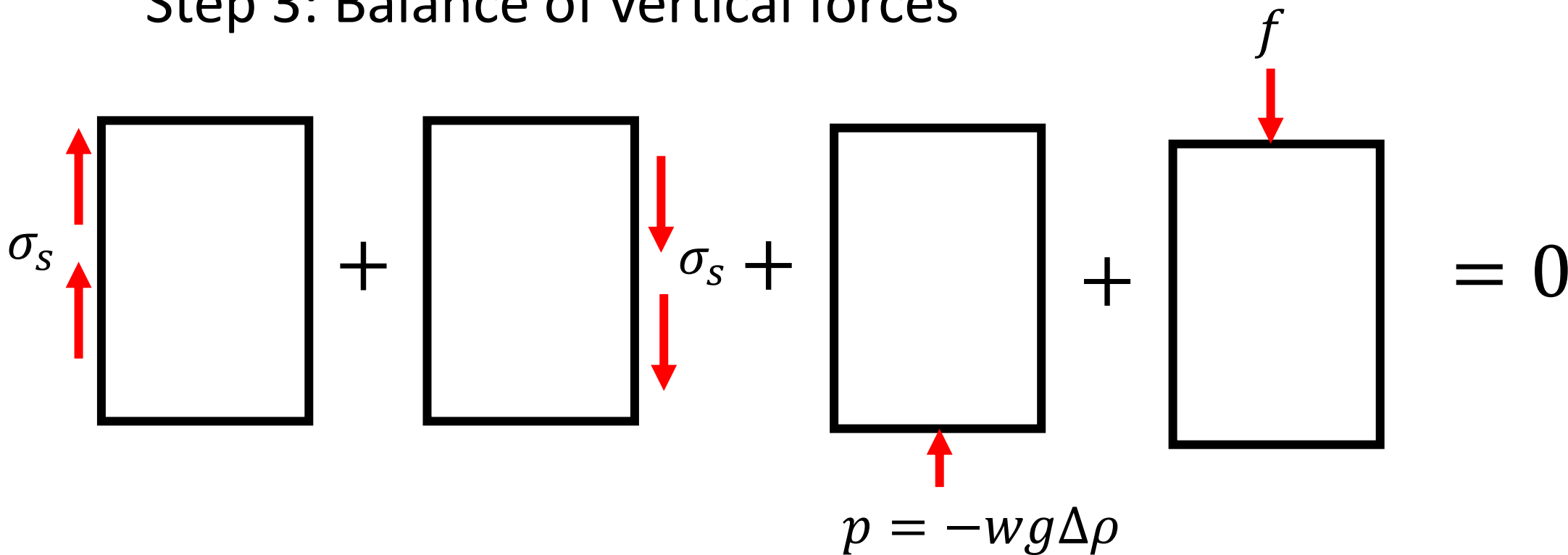
Step 3: Balance of vertical forces



Step 3: Balance of vertical forces

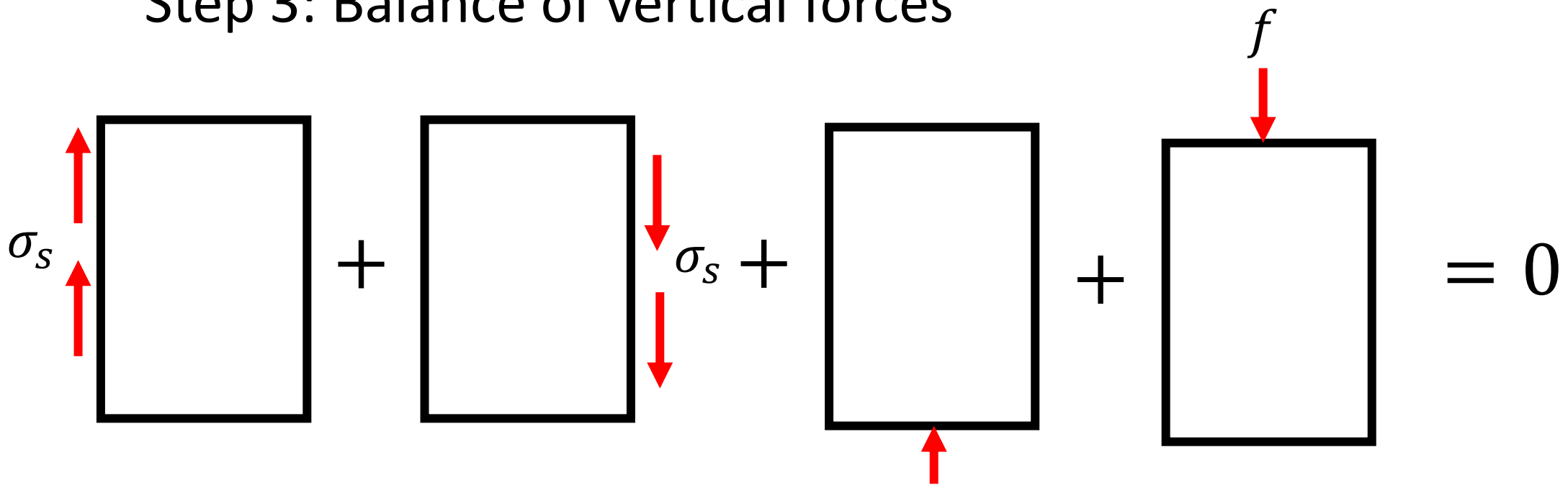


Step 3: Balance of vertical forces



$$\begin{aligned}
 & F_A & F_B & F_C & F_D \\
 & -hY\sigma_s(x) & +hY\sigma_s(x + \Delta x) & -\Delta xYwg\Delta\rho & +\Delta xYf = 0 \\
 & & h \frac{d\sigma_s}{dx} + wg\Delta\rho + f = 0 & & h \frac{d\sigma_s}{dx} = +wg\Delta\rho - f
 \end{aligned}$$

Step 3: Balance of vertical forces



$$h \frac{d\sigma_s}{dx} = +wg\Delta\rho - f$$

$$D \frac{d^4w}{dx^4} - h \frac{d\sigma_s}{dx} = 0$$

$$p = -wg\Delta\rho$$

$$D \frac{d^4w}{dx^4} + g\Delta\rho w = f$$

Equation of flexure

Equation of flexure

$$D \frac{d^4 w}{dx^4} + g \Delta \rho w = f$$

Solution for $f=0$

$$w(x) = A \cos\left(\frac{2\pi}{\lambda} x\right) \exp\left(-\frac{2\pi}{\lambda} x\right)$$

Flexural wavelength

$$\lambda = \frac{1}{2\pi} \left(\frac{D}{g \Delta \rho} \right)^{1/4}$$

Flexural wavelength

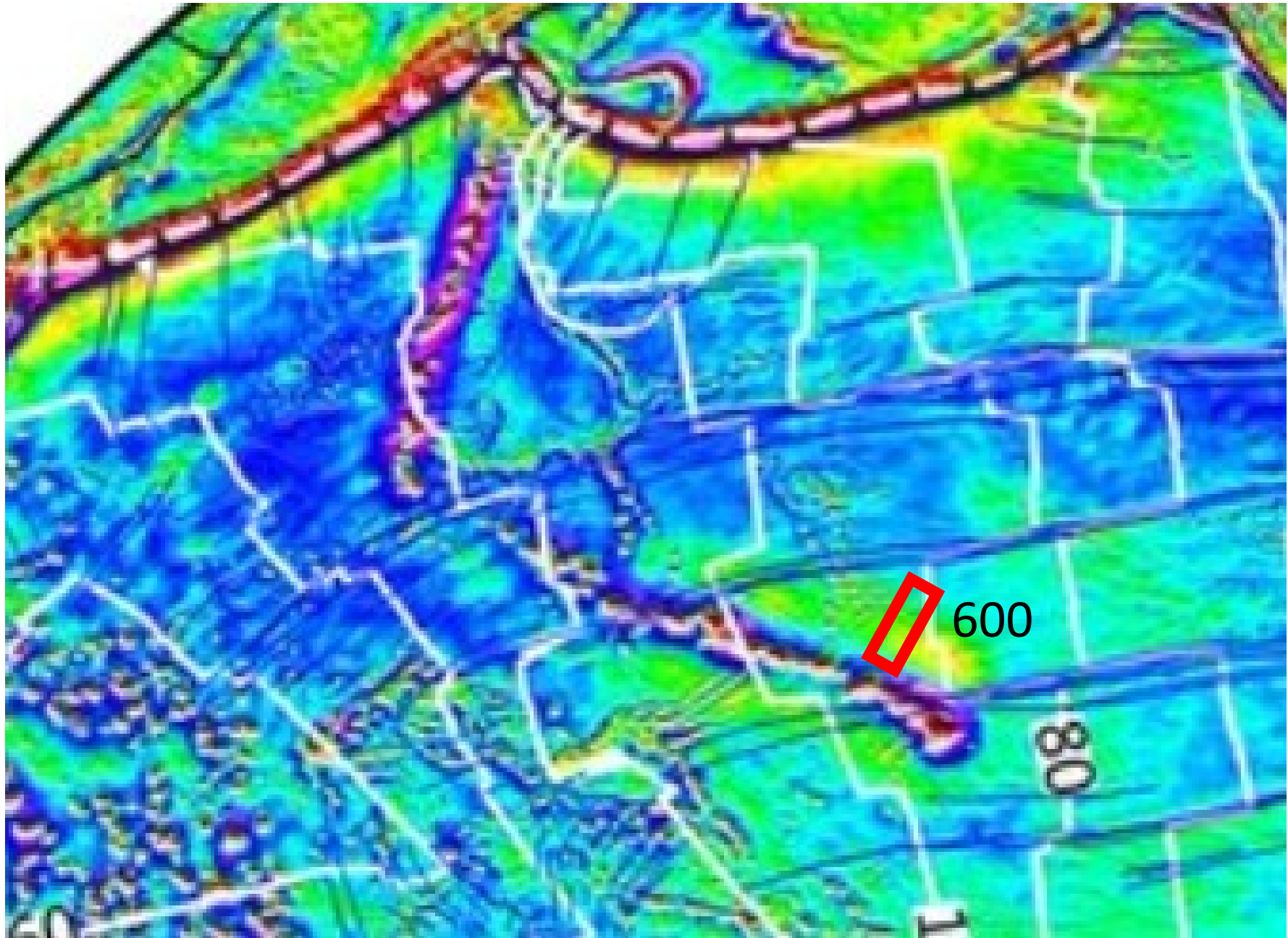
$$\lambda = \frac{1}{2\pi} \left(\frac{D}{g\Delta\rho} \right)^{\frac{1}{4}} = \frac{1}{2\pi} \left(\frac{Ch^3}{12g\Delta\rho} \right)^{\frac{1}{4}}$$

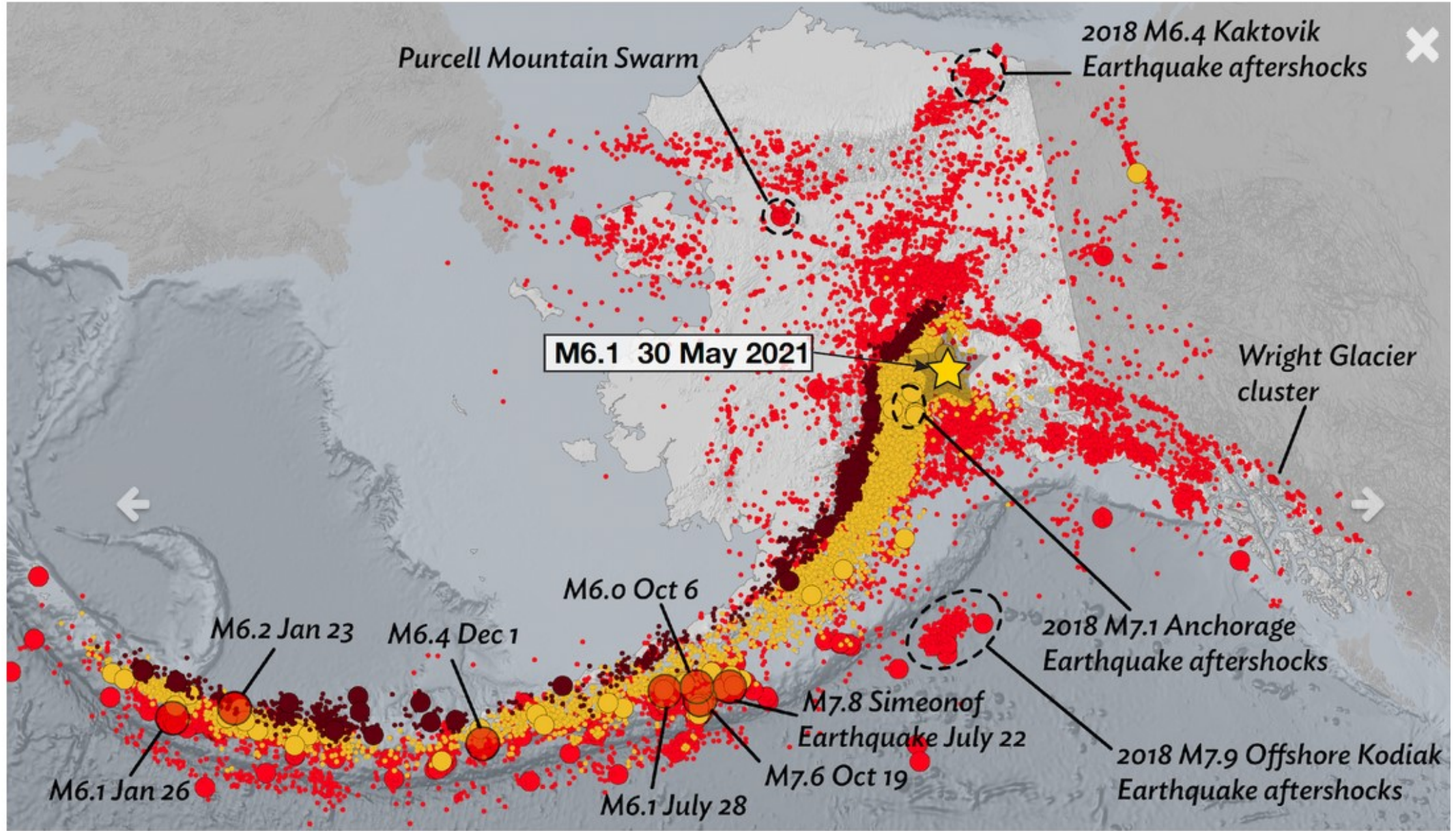
typical $\lambda = 600 \text{ km}$

$$D = \frac{Ch^3}{12}$$

$$h = \left(\frac{24\pi g\Delta\rho}{C} \right)^{1/3} \lambda^{4/3}$$

use measurements of λ
to determine thickness h
of lithosphere





2020 Seismicity

