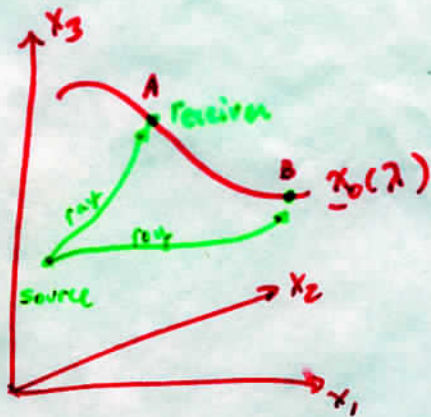


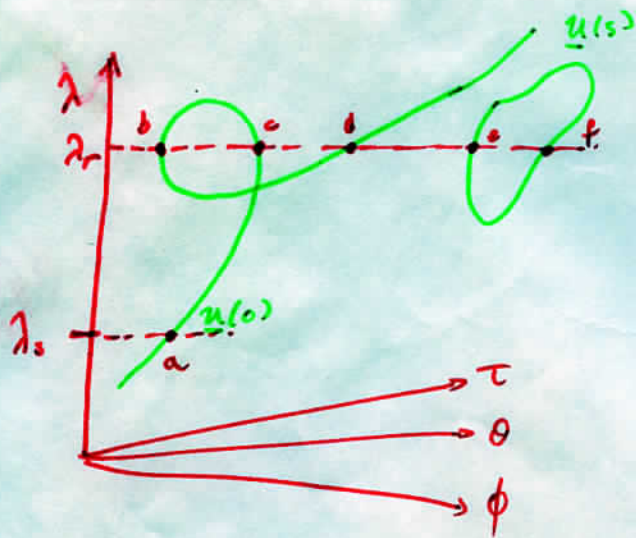
Ray tracing



A: receiver point at $\underline{x}_0(\lambda_r)$
has ray $\underline{x}_0(\theta, \phi, \tau, \lambda_r)$

B: starting point $\underline{x}_0(\lambda_s)$

$\underline{x}_0(\lambda)$ is some curve connecting starting point and receiver point.



$\underline{x}(\theta, \phi, \tau) \leftarrow \underline{x}_0(\lambda) = 0 \equiv \underline{g}(\underline{u})$
3 eqns in 4 unknowns defines a curve

$$\underline{u}(s) = [\theta(s), \phi(s), \tau(s), \lambda(s)]^T$$

a: starting point, $s=0$, is known.
eg. $\underline{u}(0) = [\theta_s, \phi_s, \tau_s, \lambda_s]^T$

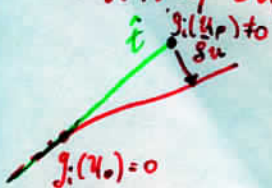
b-f: rays that connect source and receiver, solve $\lambda(s) = \lambda_r$

Step 1

Track curve $\underline{u}(s)$ with predictor-corrector method. Predictor uses tangent

$$g_i(\underline{u}_0 + \delta \underline{u}) = 0 \approx g_i(\underline{u}_0) + \frac{\partial g_i}{\partial u_j} \delta u_j \quad \text{so tangent solves}$$

$\frac{\partial g_i}{\partial u_j} \delta u_j = 0$ (3 eqns in 4 unknowns give direction). Corrector



$$g_i(\underline{u}_p + \delta \underline{u}) = 0 = g_i(\underline{u}_p) + \frac{\partial g_i}{\partial u_j} \delta u_j = 0. \quad \text{Again, slopes}$$

These are 3 eqns in 4 unknowns, so find shortest δu_j , which gives minimum length soln. if $A_{ij} = \frac{\partial g_i}{\partial u_j}$,

$$\text{then } \delta \underline{u} = -A^T(AA^T)^{-1} g_i(\underline{u}_p).$$

Step 2 locate all extrema along curve $\lambda(s) - \lambda_r = 0$

Step 3 find roots between extrema by Newton search procedure.

$\xi(\lambda)$ is parabola in $z=0$ plane
 symmetric about radial line
 just touching cusp boundary

