

## Where the Delta Functions in the Adjoint Source Come From

Bill Menke, June 16, 2023

The  $L_2$  total wavefield error is defined as

$$E' \equiv \sum_i \left( e(\mathbf{x}^{(i)}, t), e(\mathbf{x}^{(i)}, t) \right)_t \quad \text{with} \quad e(\mathbf{x}^{(i)}, t) \equiv u^{obs}(\mathbf{x}^{(i)}, t) - u(\mathbf{x}^{(i)}, t, m) \quad (1)$$

Here the sum is over observation points,  $\mathbf{x}^{(i)}$ , the subscript on the inner product indicates the variable(s) of integration, and  $m$  is a model parameter. The goal is to determine a formula for  $\partial E / \partial m$  that can be used in the gradient method to determine the model parameter,  $m$ , that minimizes the error,  $E'$ .

The adjoint formulas require that the error be expressed as an inner product over  $(\mathbf{x}, t)$ , whereas (1) contains an inner product over  $t$ , only. This problem is handled by introducing a Dirac comb (sum of delta functions), with the spikes at the observer locations

$$E \equiv \left( e(\mathbf{x}, t), e(\mathbf{x}, t) \sum_i \delta(\mathbf{x} - \mathbf{x}^{(i)}) \right)_{\mathbf{x}, t} \quad (2)$$

Then,  $E = E'$ , as

$$\left( e(\mathbf{x}, t), e(\mathbf{x}, t) \sum_i \delta(\mathbf{x} - \mathbf{x}^{(i)}) \right)_{\mathbf{x}, t} = \sum_i \left( e(\mathbf{x}^{(i)}, t), e(\mathbf{x}^{(i)}, t) \right)_t \quad (3)$$

Differentiating (2) with respect to the model parameter,  $m$ , yields

$$\begin{aligned} \frac{\partial E}{\partial m} &= \frac{\partial}{\partial m} \left( e(\mathbf{x}, t), e(\mathbf{x}, t) \sum_i \delta(\mathbf{x} - \mathbf{x}^{(i)}) \right)_{\mathbf{x}, t} \\ &= -2 \left( \frac{\partial u}{\partial m}, e(\mathbf{x}, t) \sum_i \delta(\mathbf{x} - \mathbf{x}^{(i)}) \right)_{\mathbf{x}, t} \\ &= -2 \left( \frac{\partial u}{\partial m}, \sum_i e(\mathbf{x}^{(i)}, t) \delta(\mathbf{x} - \mathbf{x}^{(i)}) \right)_{\mathbf{x}, t} \\ &= -2 \left( \frac{\partial u}{\partial m}, s(\mathbf{x}, t) \right)_{\mathbf{x}, t} \quad \text{with} \quad s(\mathbf{x}, t) \equiv \sum_i e(\mathbf{x}^{(i)}, t) \delta(\mathbf{x} - \mathbf{x}^{(i)}) \end{aligned}$$

(4)

Presuming that the wavefield satisfies the linear partial differential equation,  $\mathcal{L}(m)u(m) = f$ , with the force,  $f$ , independent of  $m$ , the chain rule gives the wavefield derivative

$$\frac{\partial \mathcal{L}}{\partial m} u(m) + \mathcal{L}(m) \frac{\partial u}{\partial m} = 0 \quad \text{or} \quad \frac{\partial u}{\partial m} = -\mathcal{L}^{-1} \frac{\partial \mathcal{L}}{\partial m} u(m) \quad (5)$$

The error derivative evaluated at reference model,  $m_0$ , is

$$\left. \frac{\partial E}{\partial m} \right|_{m_0} = 2 \left( \mathcal{L}^{-1} \frac{\partial \mathcal{L}}{\partial m} u, s(\mathbf{x}, t) \right) \bigg|_{\mathbf{x}, t} \bigg|_{m_0} = 2 \left( \frac{\partial \mathcal{L}_0}{\partial m} u_0, \mathcal{L}_0^{\dagger-1} s(\mathbf{x}, t) \right)_{\mathbf{x}, t} \quad (6)$$

Here we have used the shorthand,  $u_0 = u(m_0)$ ,  $\mathcal{L}_0 = \mathcal{L}(m_0)$ , and  $\partial \mathcal{L}_0 / \partial m \equiv \partial \mathcal{L} / \partial m|_{m_0}$  and the fact that  $\mathcal{L}^{-1\dagger} = \mathcal{L}^{\dagger-1}$ . This result can be simplified by introducing an adjoint field,  $\lambda$ , and a function,  $\xi$ , defined as

$$\xi \equiv 2 \frac{\partial \mathcal{L}_0}{\partial m} u_0 \quad \text{and} \quad \lambda = \mathcal{L}_0^{\dagger-1} s(\mathbf{x}, t) \quad (7)$$

From whence it follows that

$$\left. \frac{\partial E}{\partial m} \right|_{m_0} = (\xi, \lambda)_{\mathbf{x}, t} \quad \text{with} \quad \mathcal{L}_0^{\dagger} \lambda = s(\mathbf{x}, t) \quad (8)$$

Note that the adjoint field satisfies a differential equation with a source,  $s(\mathbf{x}, t)$ , that contains a Dirac comb (sum of delta functions).

So, the upshot is that the delta functions in the adjoint source arise due to a mathematical manipulation that adapts the case of sparse observations (observations only at points,  $\mathbf{x}^{(i)}$ ) to a method based on inner products over spatial coordinates.