Geophysical Data: "Real data has real warts"

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Columbia University Department of Earth and Environmental Science (DEES) Noon

Balloon Tuesday November 9th

12:15-1:00pm

Room 417 Schermerhorn Hall

http://eesc.columbia.edu/news-events/news/tuesday-noon-balloon-dale-chayes

What is Geophysics?

application applied areas dates detect earth earthquake electrical electromagnetic etc exploit exploration field form generated geologic geophysics gravitation gravity heat human including instrumentation involves known list magnetism measurements method million mineral per petroleum physical plate problem processes progress properties resources seismic seismology sense solid sometimes Study tectonics theory vibrators water

What is Geophysics?

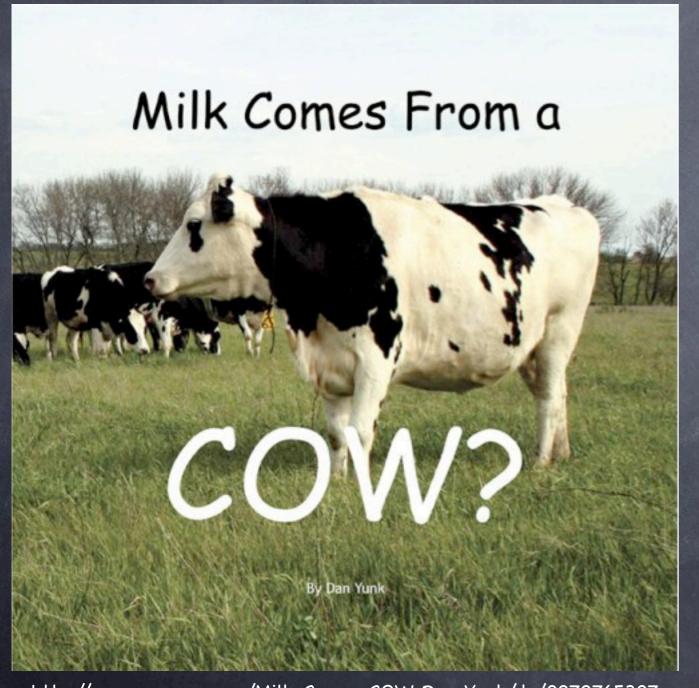
analysis atmosphere change chemistry climate composition continental cycles data dust dynamics earth fields general geochemistry geochronology ice instruments interactions ionosphere magnetic magnetosphere mantle marine methods miscellaneous modeling ocean particles phenomena physics planetary plasma Drocesses properties remote rheology satellites sciences sensing solar structure surface systems techniques tectonics transport volcanism water waves

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What is Geophysics?

Gravity Heat flow Vibrations Radioactivity Electricity Electromagnetic waves Magnetism Fluid dynamics Condensed matter physics

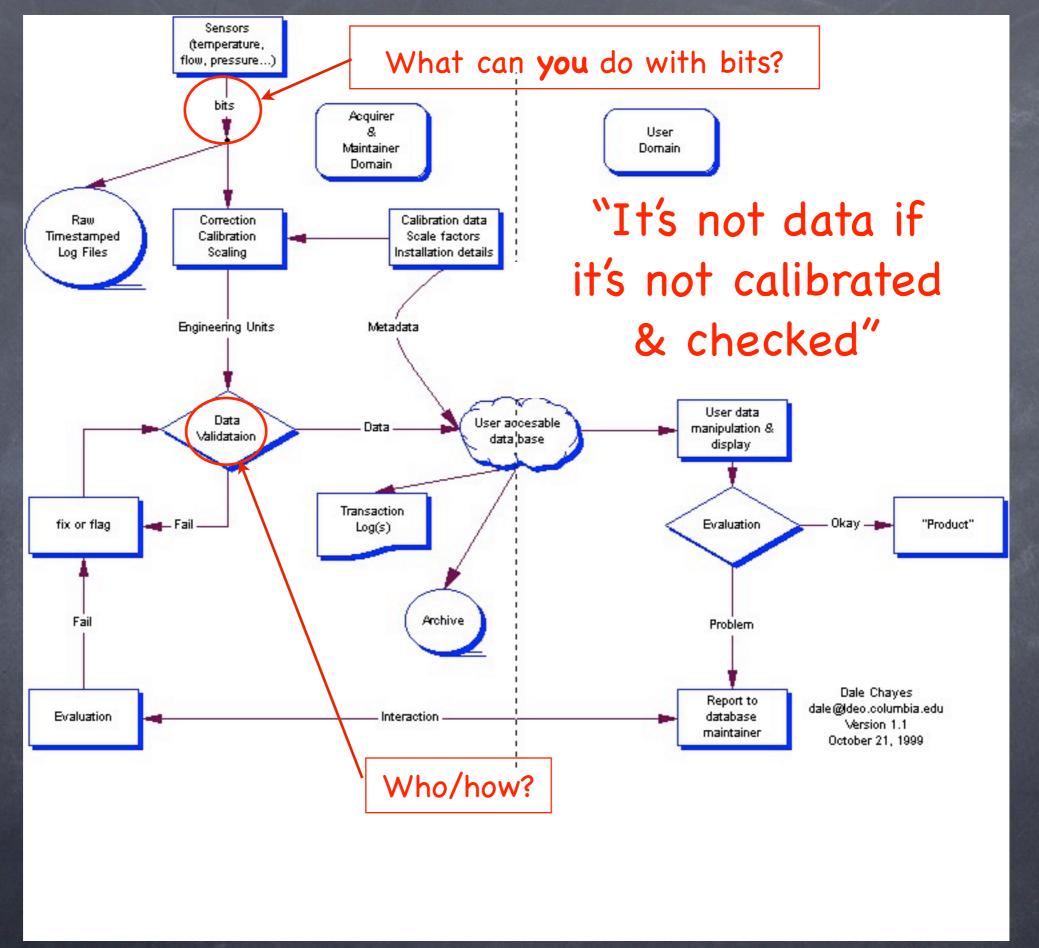
And Data?



If milk really comes from animals (cows, mares, goats, camels ...) and not from the store,

What about data?

http://www.amazon.com/Milk-Comes-COW-Dan-Yunk/dp/0979765307



Design, development and operation of a Through-ice CTDs (from a fixed wing aircraft)



Science Objectives

- Real-time data from the CTD
- Precision located (depth) water samples
- Samples for chemical analysis to:
 - Track fresh water sources
 - Investigate temporal variability (composition and circulation)
 - Estimate "age" using trace gas techniques

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Design Goals

- -Transect from Alert to the Pole
- -Trace gas tight (to the lab at 1ppb) samples
- -2 liter (useable) samples
- -12 bottles per station
- -3 stations per day
- -Depth: 600m minimum, 1km desirable

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-Cheap, quick, with inexperienced operators...

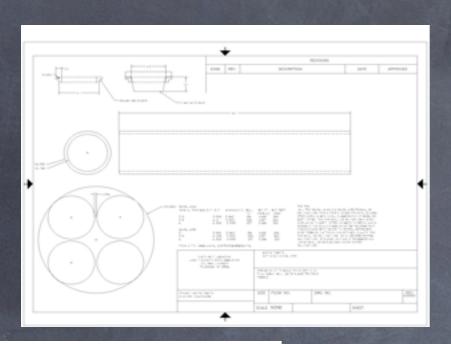




- Can't reliably get there w/ icebreakers (even nukes)
- Submarines aren't available (and can't sample deep)
- Hoover craft can't get the samples back fast enough
- So we fly.....

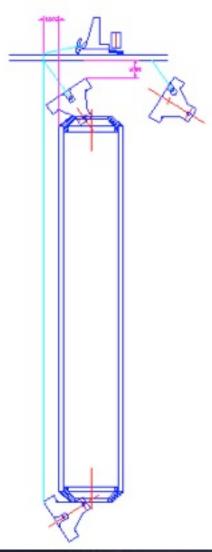


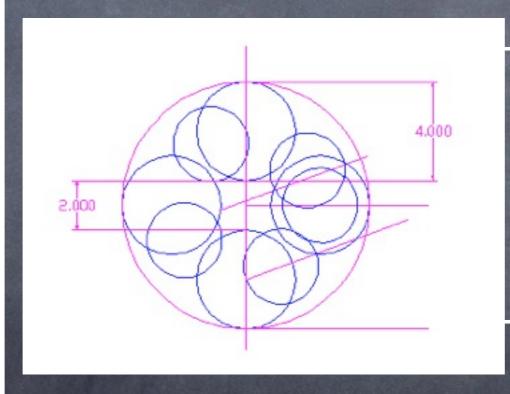
November 9, 2010 10



Concept #1

(With a standard (COTS) SBE release)





- -No chance in a 10" hole without radical redesign
 - No time for re-design
 - Concerns about mixing of water
- -Very long release wires w/ a standard release mechanism



Project: Arctic Rosette Subject: Water bottle sizes Date: November 23, 2002 Eng: Dale Chayes

Station holes will be drilled with a 12" auger in a Jiffy Drill or perhaps with an electric drill powered from the same (diesel) generator used to run the winch. Some allowance for non-straight holes and for ice chips and junk in the hole will be allowed.

 $Diameter_{DSAX} = 10 \cdot in$

 $Bottle_{OD} := \frac{\left(Diameter_{max} - 0.25 \cdot in\right) \cdot 9}{2}$

 $Bottle_{OD} = 0.111 \, m$

 $Bottle_{wall} := 0.3 \cdot in$

 $Bottle_{ID} := Bottle_{OD} - 2 \cdot Bottle_{wall}$

 $Bottle_{ID} = 3.788 in$

 $Volume_{required} := 4 \cdot L$

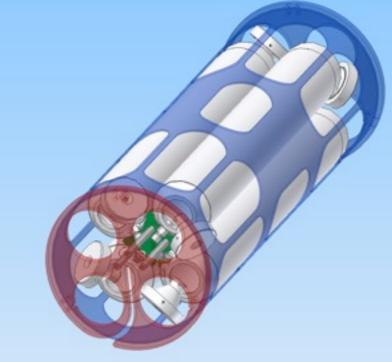
The mimimum acceptable sample volume seems to be three liters. The range goes up to four liters.

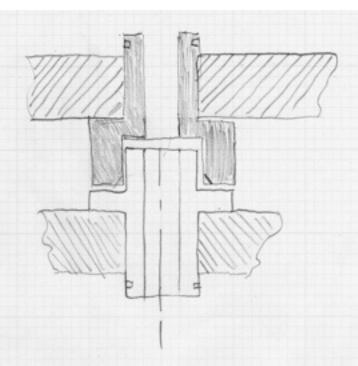
We have to allow some material around the outside of the bottle circumfrence for support. The exact amount depends on the design and the materials. The current estimate allows 1/8" for material and has a 10%

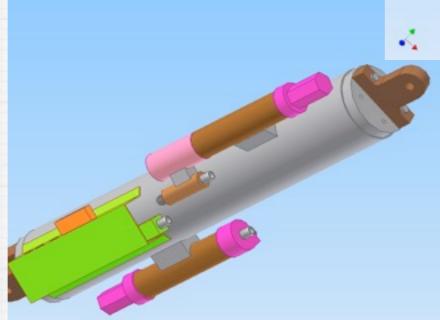
 $Bottlelength = \frac{Volume_{required}}{\pi \cdot \left(\frac{Bottle_{ID}}{2}\right)^2}$

Bottletength = 21.665 in

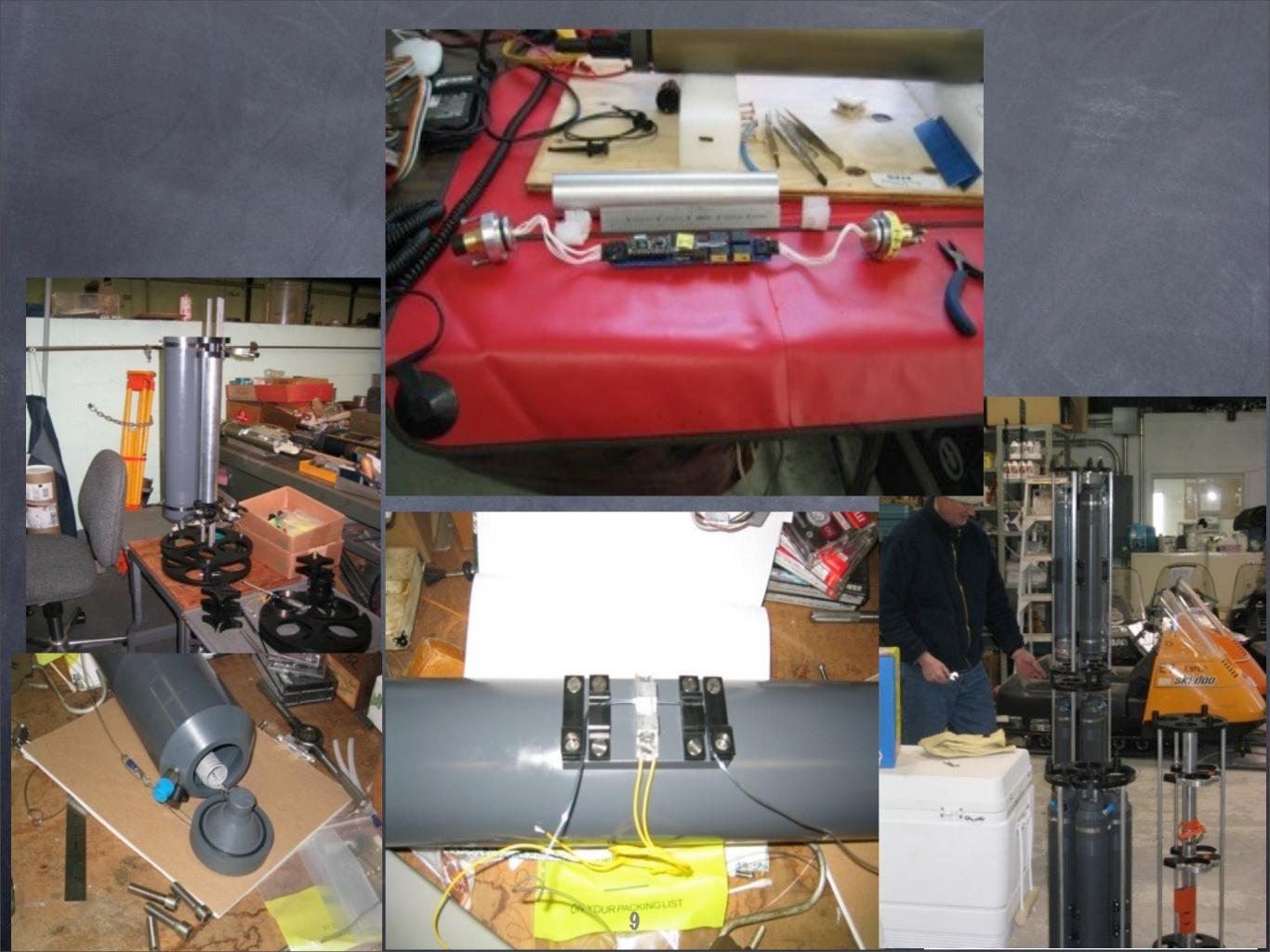
Concept #2 custom release

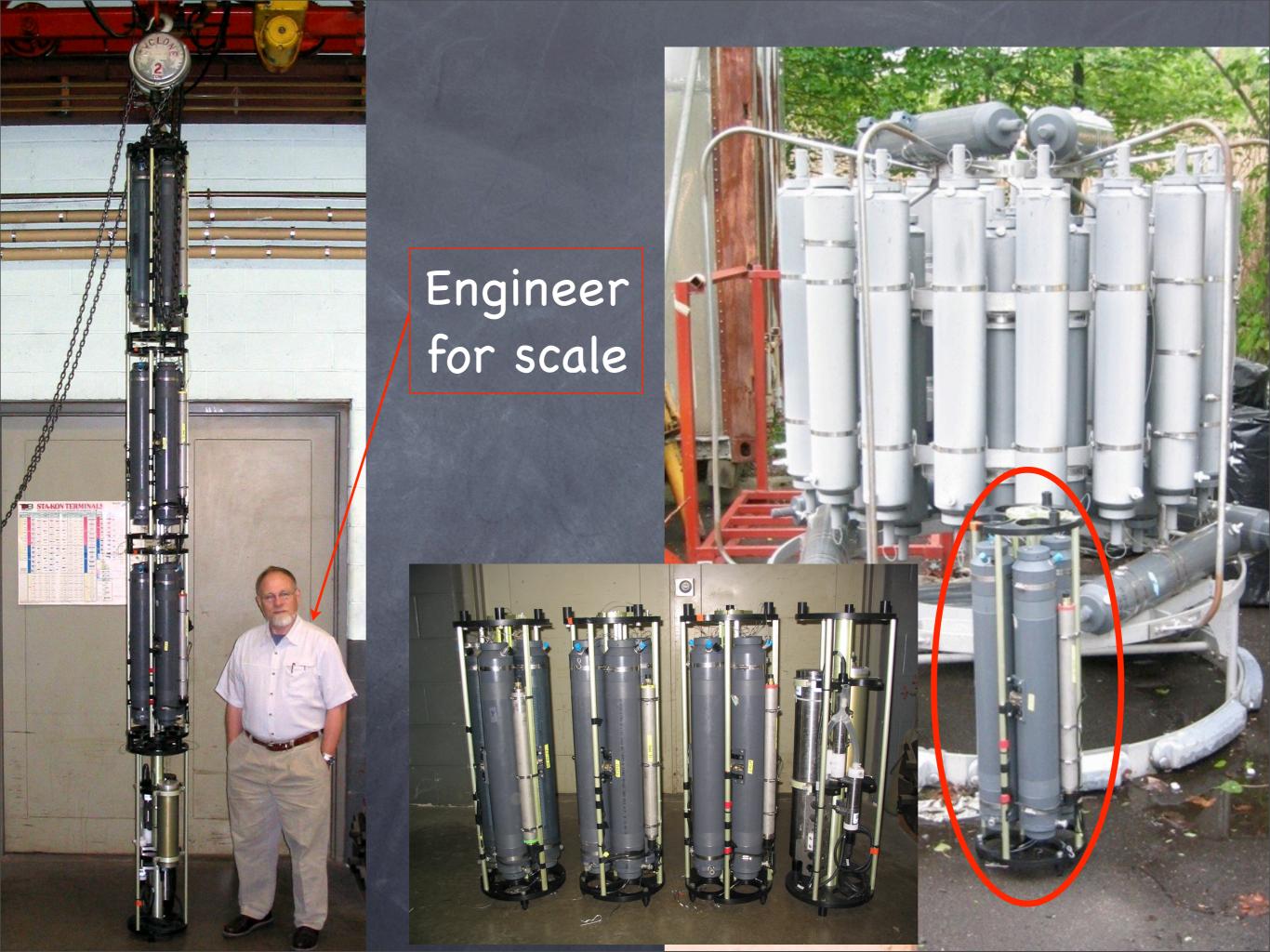




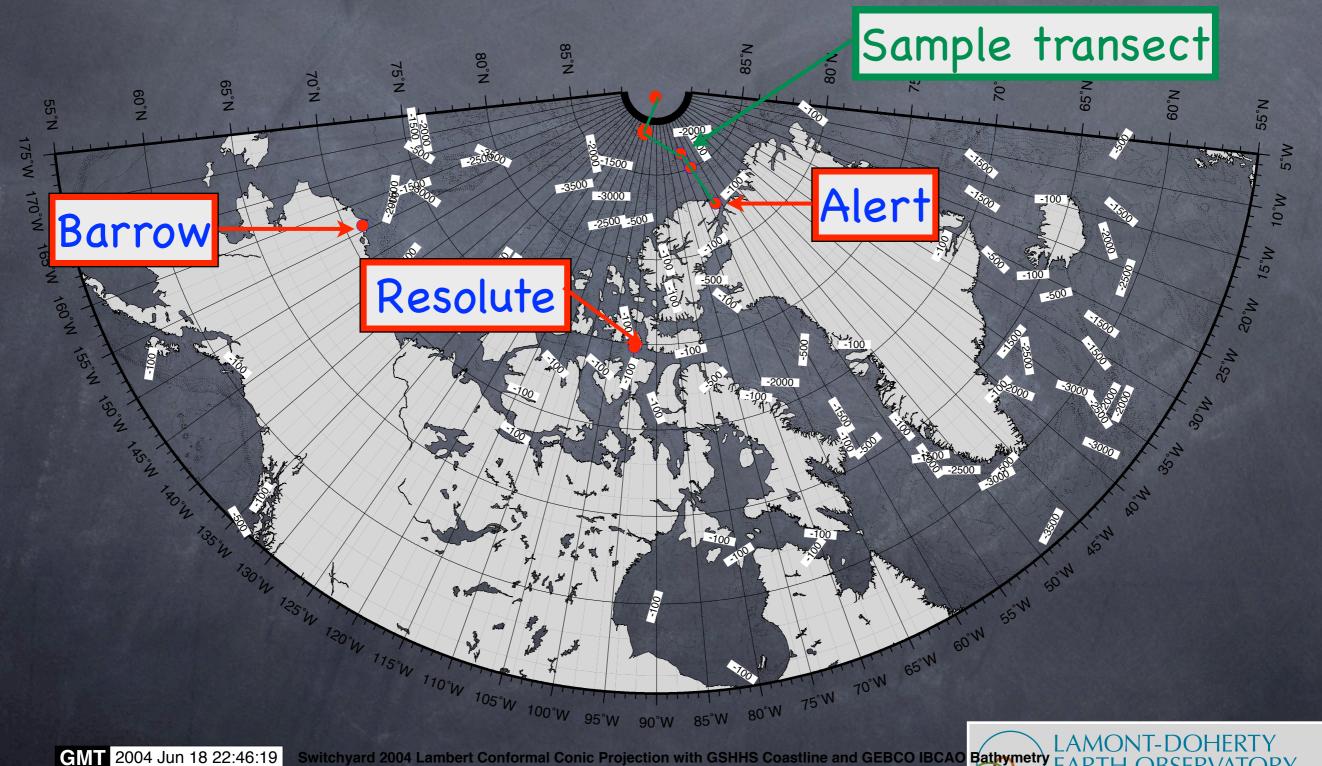








Where is Alert?





How do you get there (and back)?

- Comair + Charter:
 - New York->Ottawa->Iqaluit->Resolute
 - Then charter to Alert (via Eureka)
- US Air National Guard (109th)
 - Scotia NY -> Kangerlussuaq -> Thule ->



Chartered Hawker 748 Resolute -> Alert























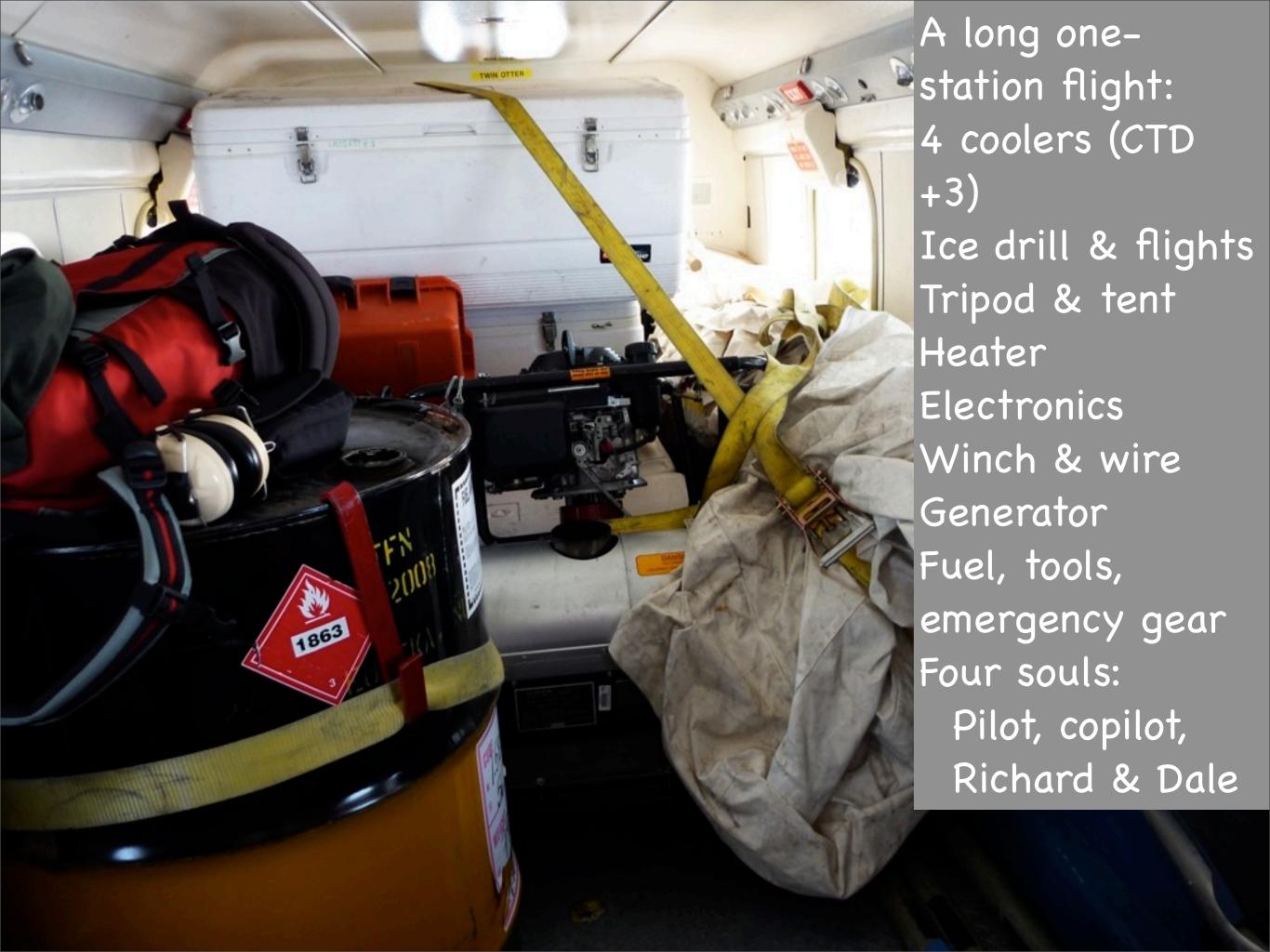


























Drawing and preserving water samples for transport to Lamont and analysis



Ice tracking buoys November 9, 2010

Year	Stations	Duration (Days)	Weather & Aircraft Days
2004	3	8	~3
2005	4	6	~2
2006	3	6	~3
2007	5	11	~4
2008	5	11	~3
2009	9	17	6
2010	4	12	7
2011			
2012			
2013			
? 2010		37	LAMON EARTH O INISTRUME

NT-DOHERTY OBSERVATORY INSTRUMENT LABORATORY



Installed Science Equipment

- Science (TCP/IP) Ethernet Network
- Time of day (very precise) via satellite
- Navigation, Attitude & Heading (GNSS)
- Sonars (bottom mapping & currents)
- Physical properties sensors (weather, water)
- Winches+ to lower sensors and samplers
- Labs, reefers and freezers
- Visiting equipment





Navigation Sources



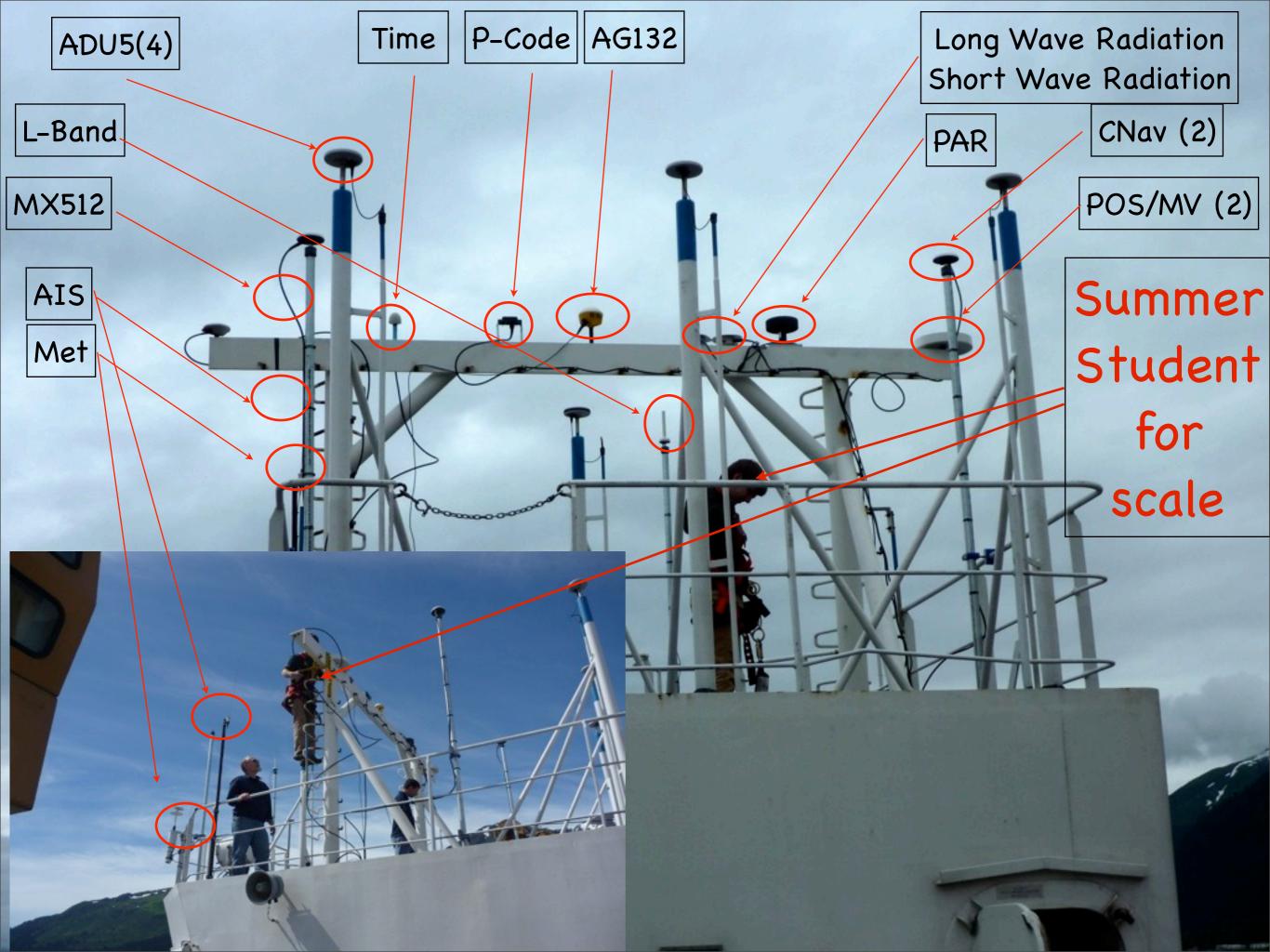


- □ Trimble Centurion P-Code
- □ Ashtech ADU-5 3D-GPS
- □ Furuno WAAS GPS

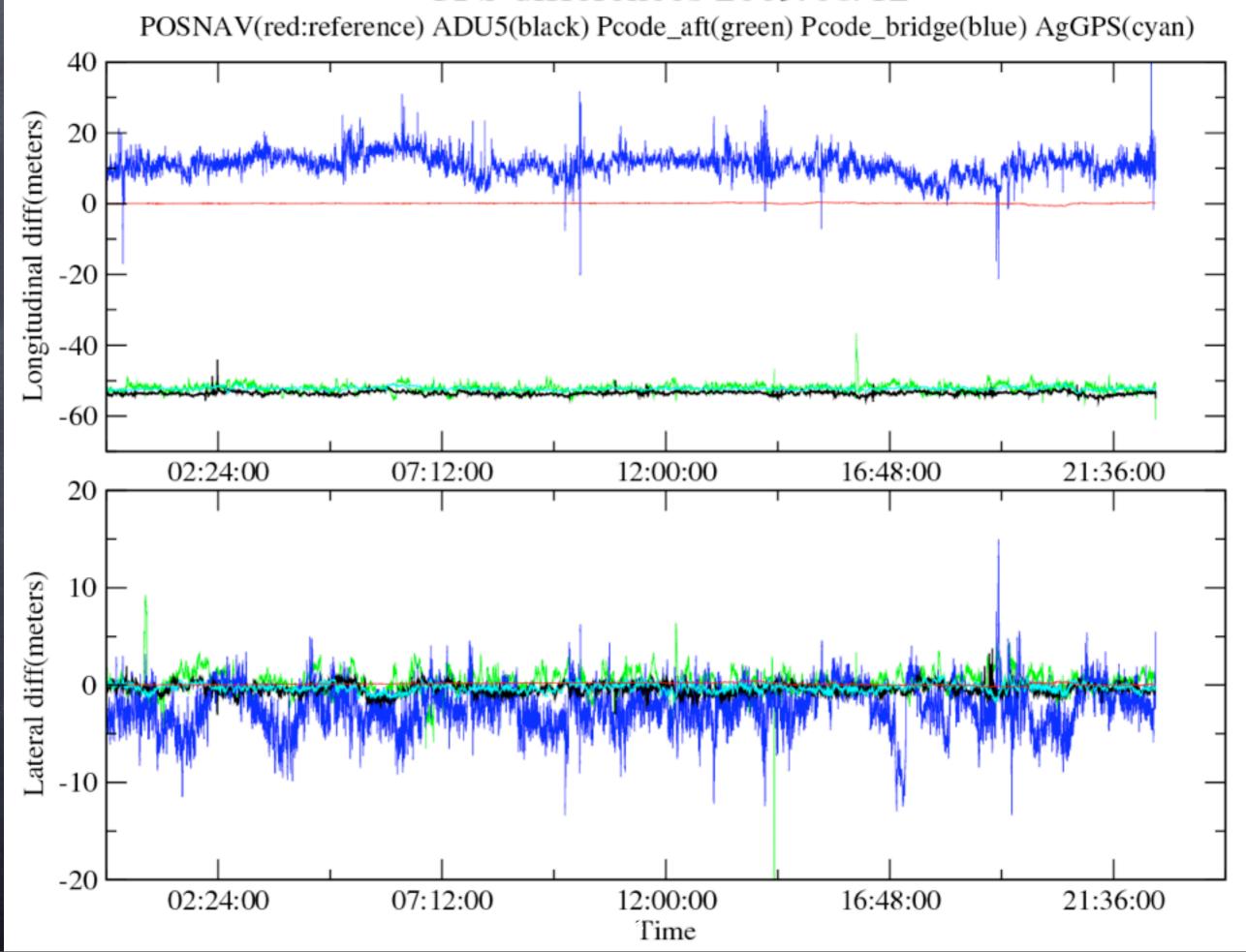
POSMV

- □ Applanix POS/MV-320 (2)
- □ Trimble AG132 DGPS
- □ Ashtech Glonass/GPS
- □ Simrad MX512 DGPS (2)
- D C-Nav GC-DGPS (2)



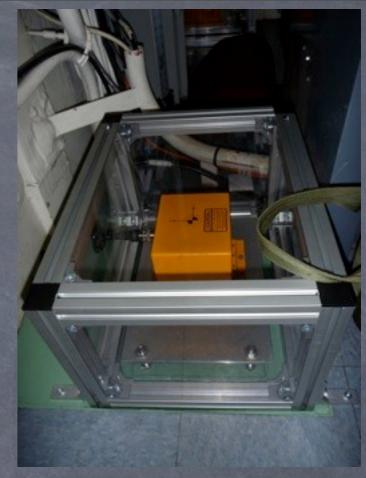


GPS differences 2009/08/12



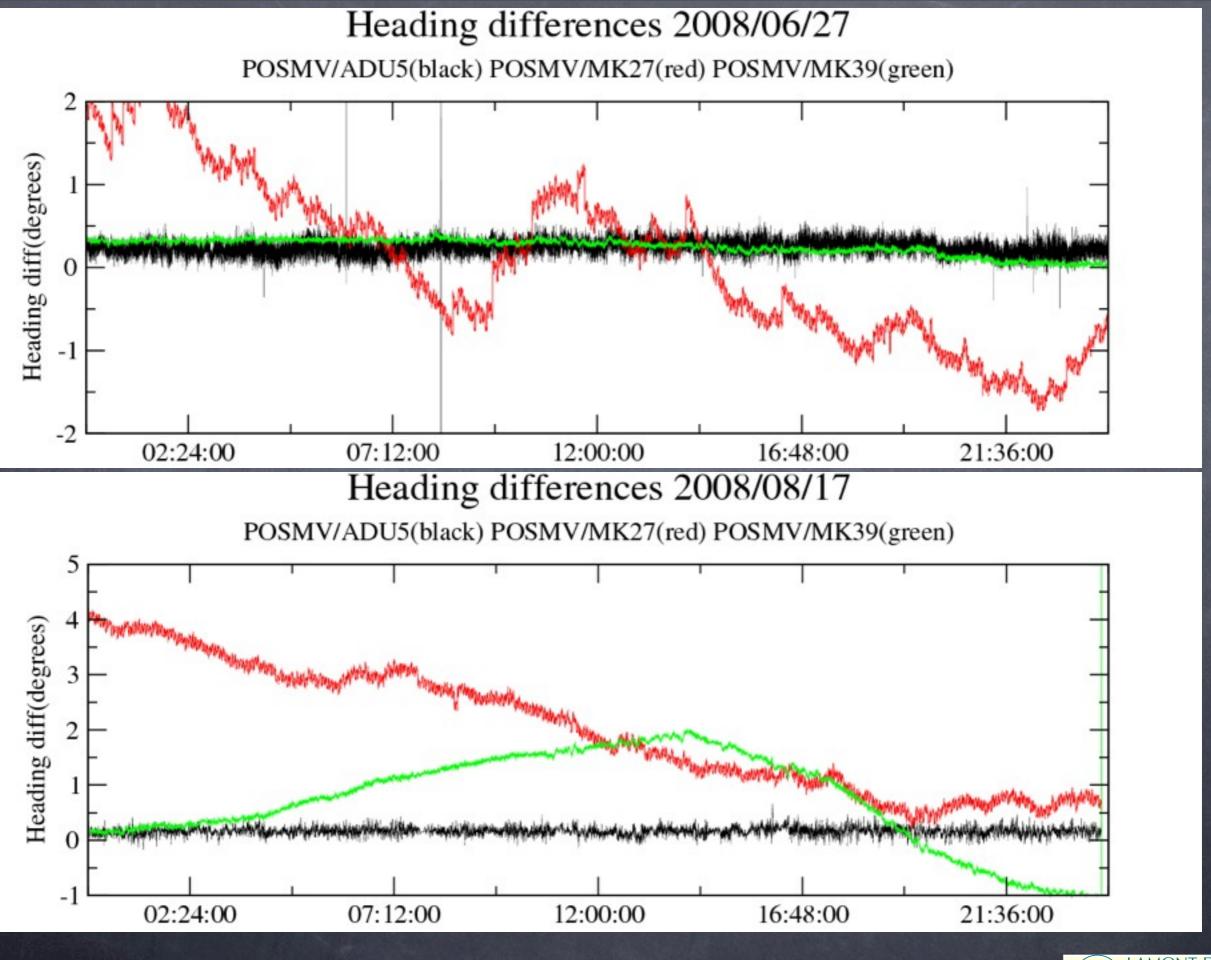


Attitude & Heading



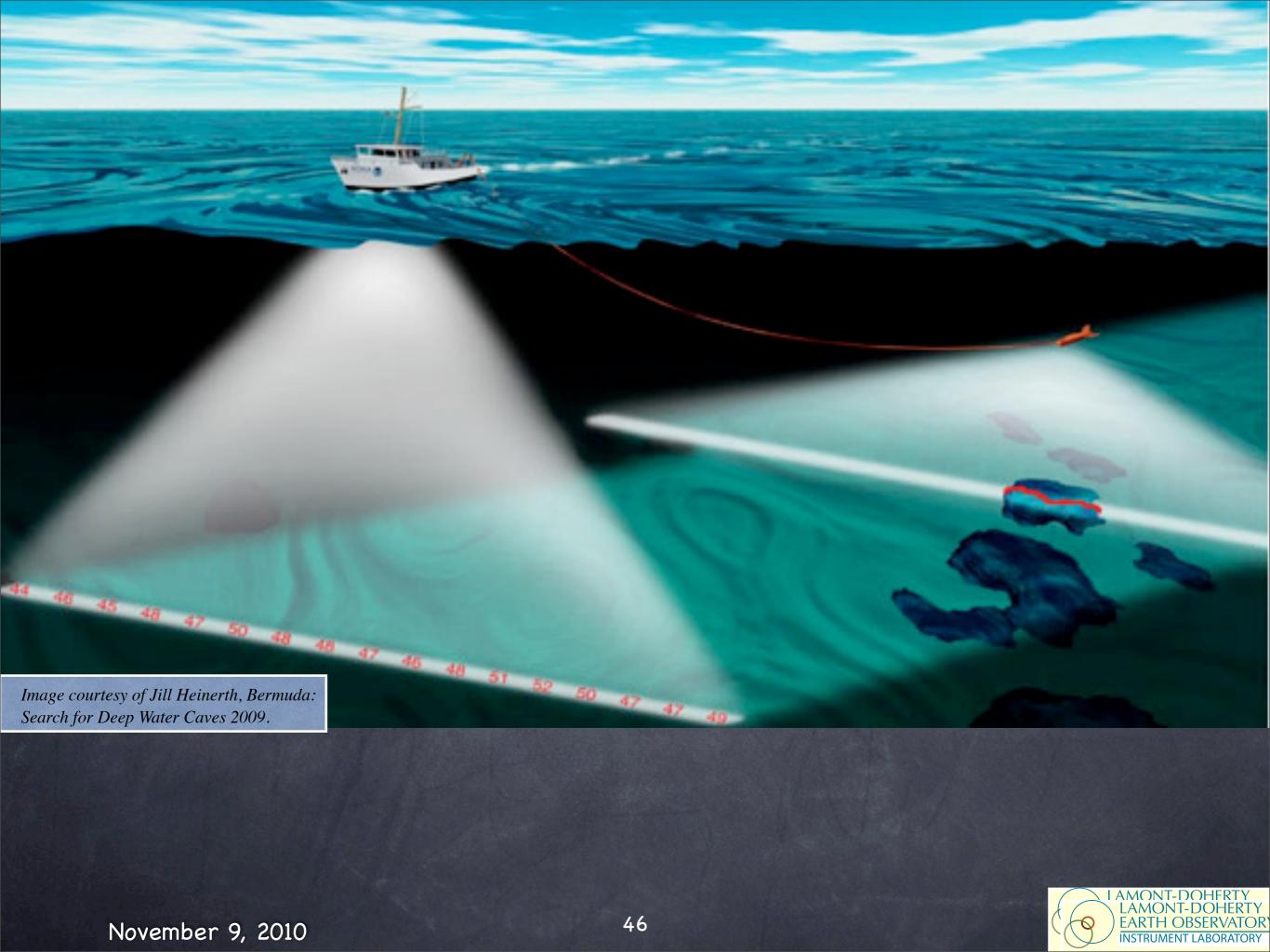
- □ Applanix POS/MV-320 (primary) (2) GNSS aided Inertial navigation system
- □ Thales (Ashtech) ADU5 (part of IBS/VMS)
- □ Sperry MK-27F gyrocompass
- □ Sperry MK-39 Mod3A gyrocompass

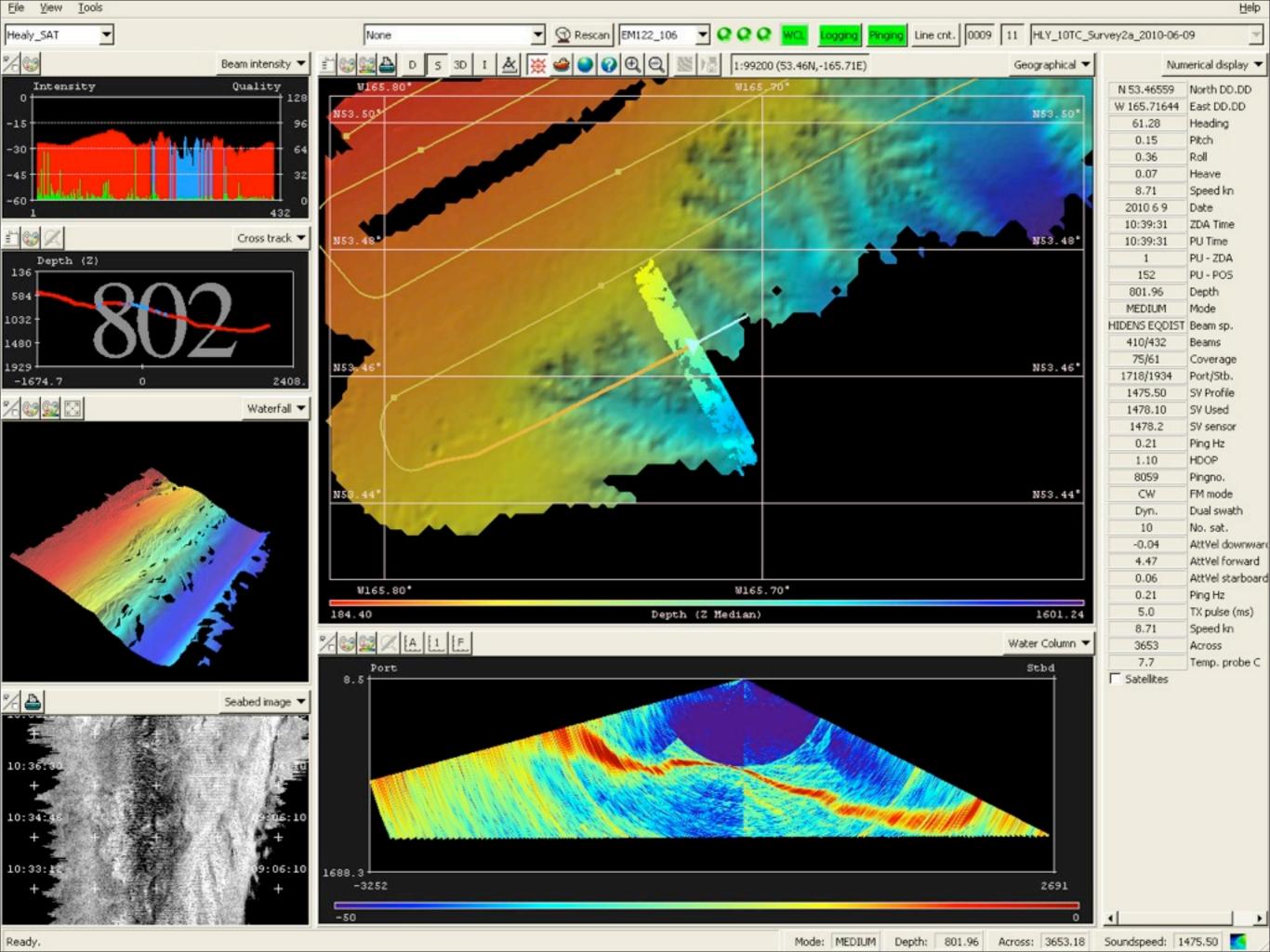


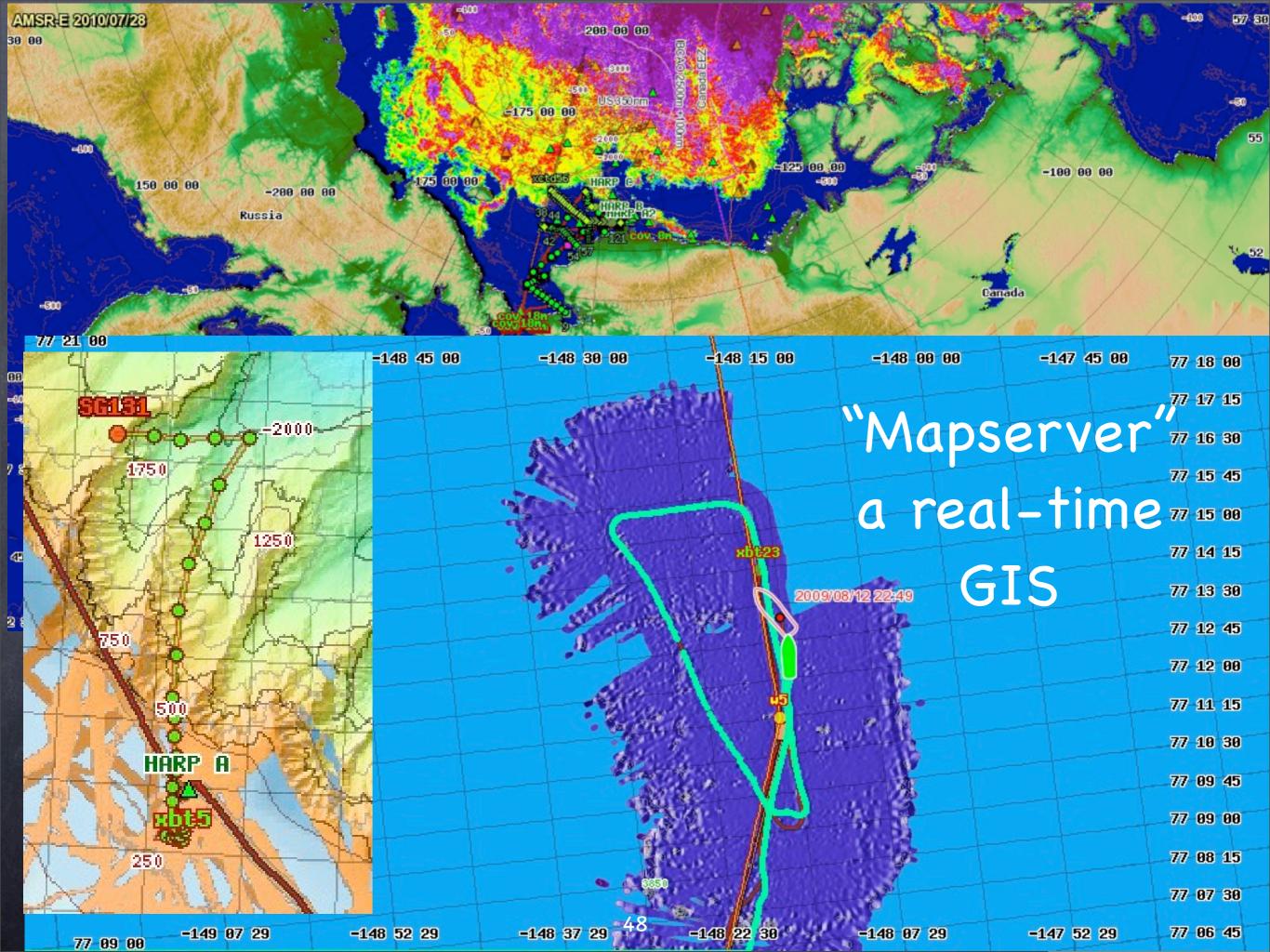


Sonars

- Kongsberg EM122 multibeam sonar (maps the shape & reflectivity of the seafloor and water column)
- Knudsen 320B subbottom profiler (senses sediment layers below the bottom)
- Two Acoustic Doppler Current Profilers (measures ocean current relative to the ship)







Data

Gravity Meter

```
bgm221 2009:218:12:52:54.7920 04:025486 00
bgm221 2009:218:12:52:55.7820 04:025351 00
bgm221 2009:218:12:52:56.7820 04:025367 00
bgm221 2009:218:12:52:57.7858 04:025337 00
```

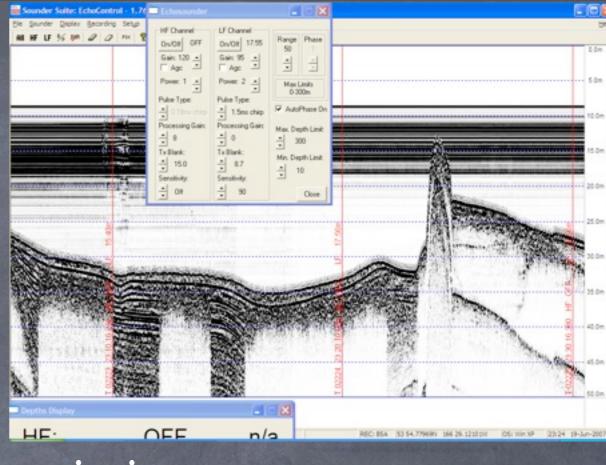
POS/MV-320

```
2009:224:23:40:06.1274
                                   $PASHR, 234006.002, 351.85, T, -0.82, -0.06, 0.00, 0.018, 0
posnav
                                   $PRDID, -0.06, -0.82, 351.85*7F
        2009:224:23:40:06.1854
posnav
                                   $INGST, 234006.002, , 2.3, 1.1, 5.5, 2.7, 1.4, 6.9*56
        2009:224:23:40:06.2454
posnav
                                   $INGGA, 234006.002, 7716.20000, N, 14816.39637, W, 1, 10, 0
        2009:224:23:40:06.3034
posnav
        2009:224:23:40:06.3035
                                   $INHDT, 351.9, T*2B
posnav
                                   $INVTG, 353.7, T, , M, 3.0, N, 5.6, K*72
        2009:224:23:40:06.3334
posnav
                                   $INZDA, 234007.0019, 12, 08, 2009, , *7C
        2009:224:23:40:07.0693
posnav
```



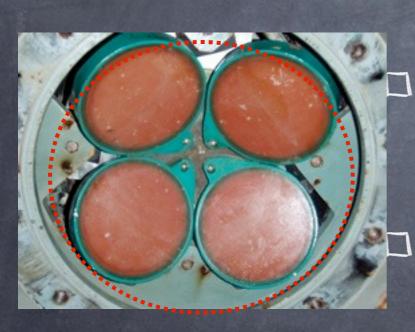
Subbottom Profiler

- □ Knudsen 320B/R
 - D CW and FM modulated transmission
 - □ 3 to 6 KHz subbottom
 - □ 12 KHz echo sounder
 - Only one set of transducer arrays for each frequency
 - □ No 12 KHz w/ multibeam





Acoustic Doppler Current Profilers (ADCP)





RDI OS75 Ocean Surveyor (76.8 kHz)

RDI OS150 Ocean (new for 2010) Surveyor (153.6 kHz)



Science Seawater System & TSG*

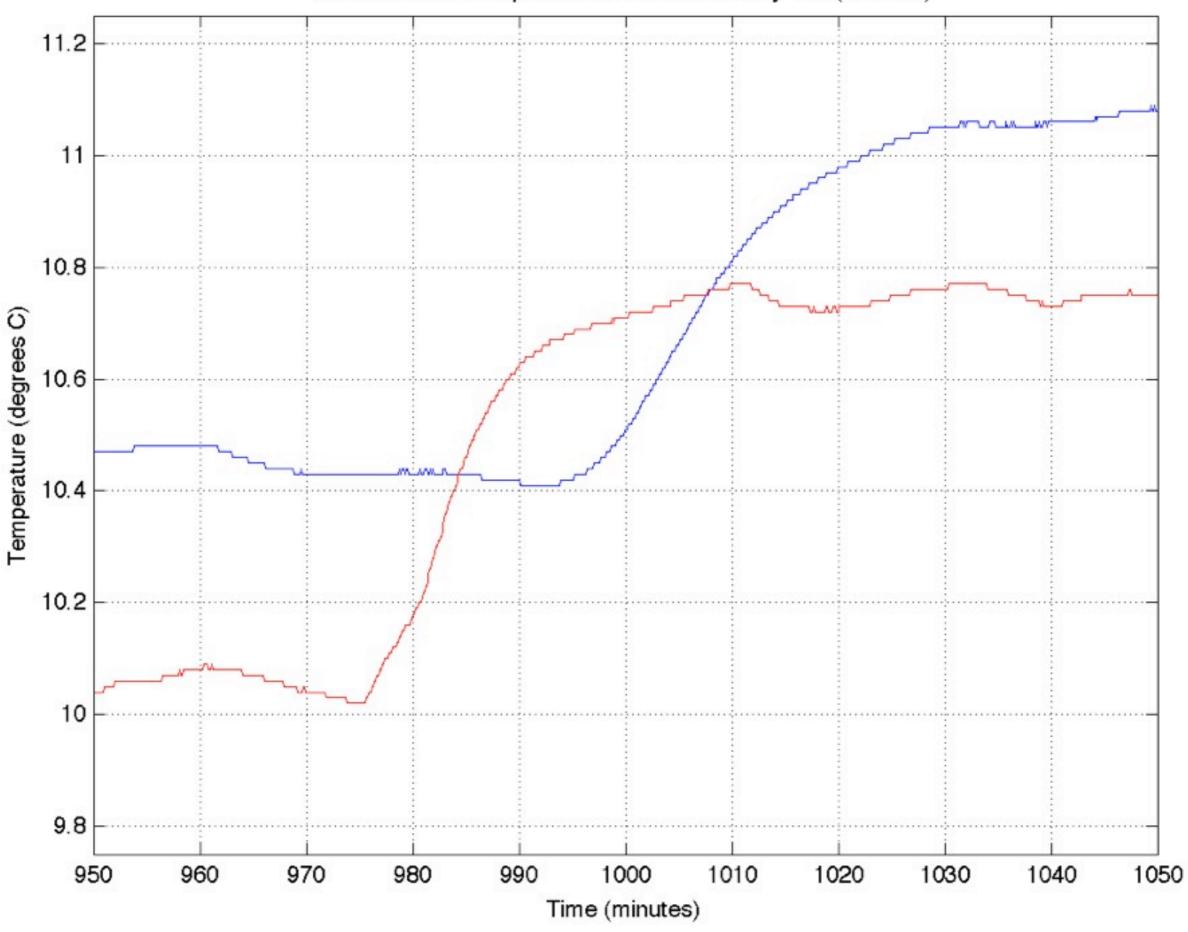
- □ Sea-Bird Electronics SBE-45, DO, flourometer
- □ Biochem Lab
- ☐ Remote temperature probe (SBE-3) near the intake
 - □ About the time lag....

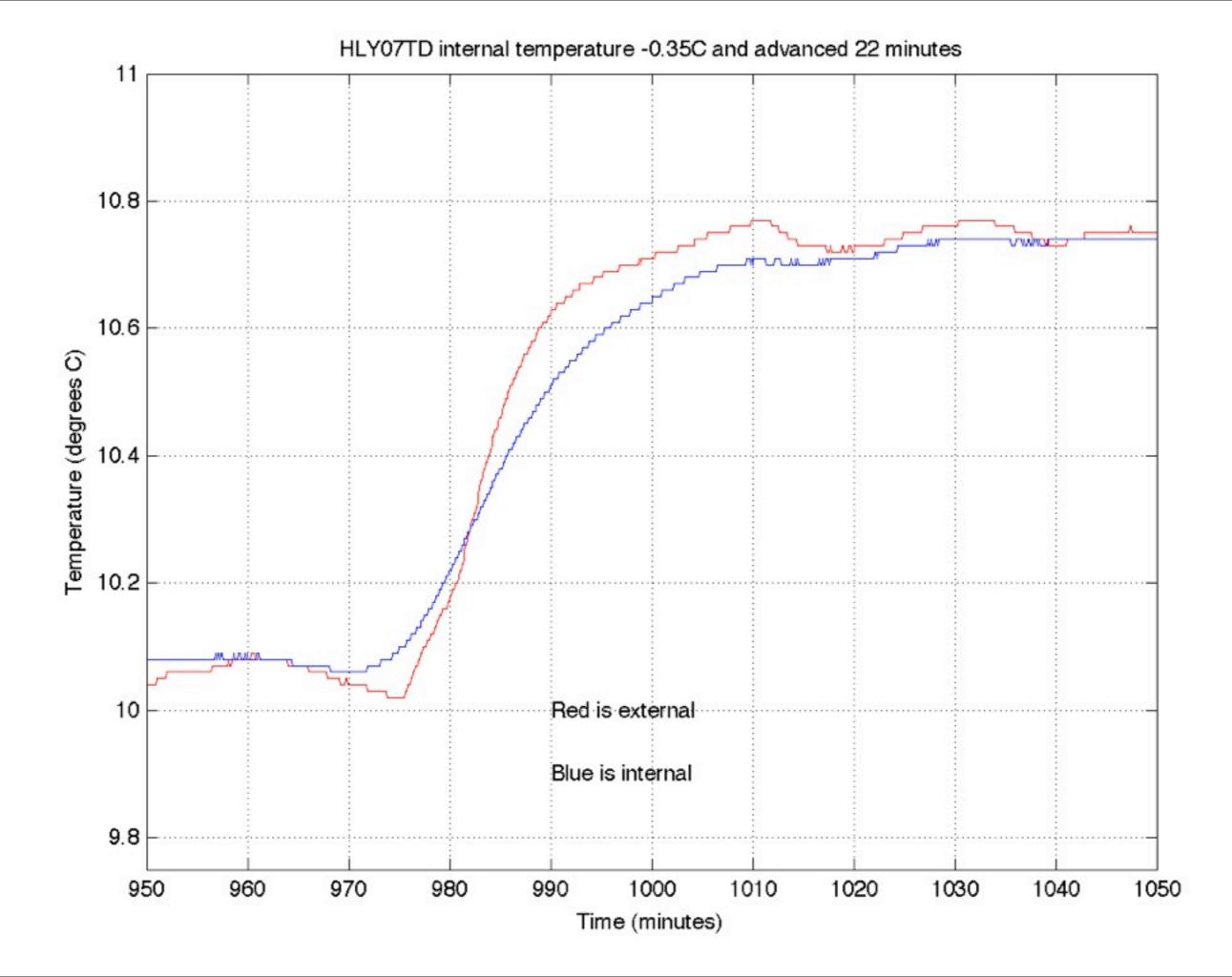
* Thermosalinograph

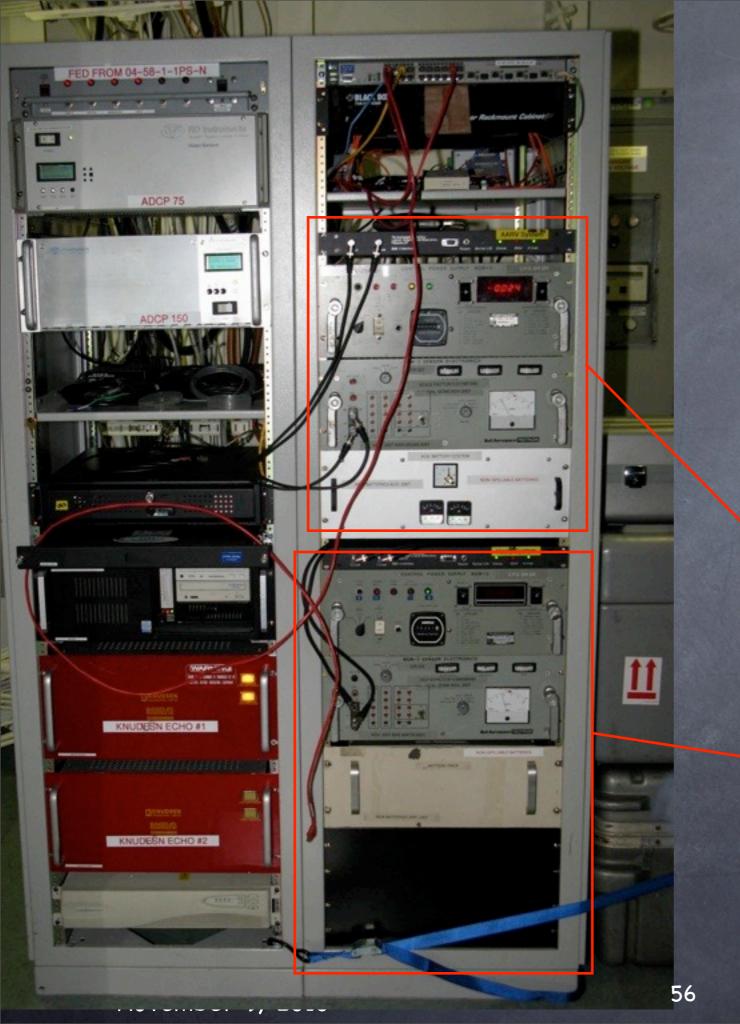


Time (minutes)

HLY07TD TSG temperature difference for day 174 (June 23)







Gravity

- Bell BGM-3 Marine Gravity Meter (x2)
- In IC/Gyro (by the lower gym)





Weather

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- □ Wind speed & Direction
- □ Temperature
- ☐ Humidity
- PAR, LW, SW radiation
- Atmospheric Pressure
- □ Terascan



High quality meteorological measurements from ships is hard, and harder from icebreakers is hard, BUT: high latitude weather observations are rare and important so we try harder.

Water sampling





Water sampling rosette SBE "911" CTD



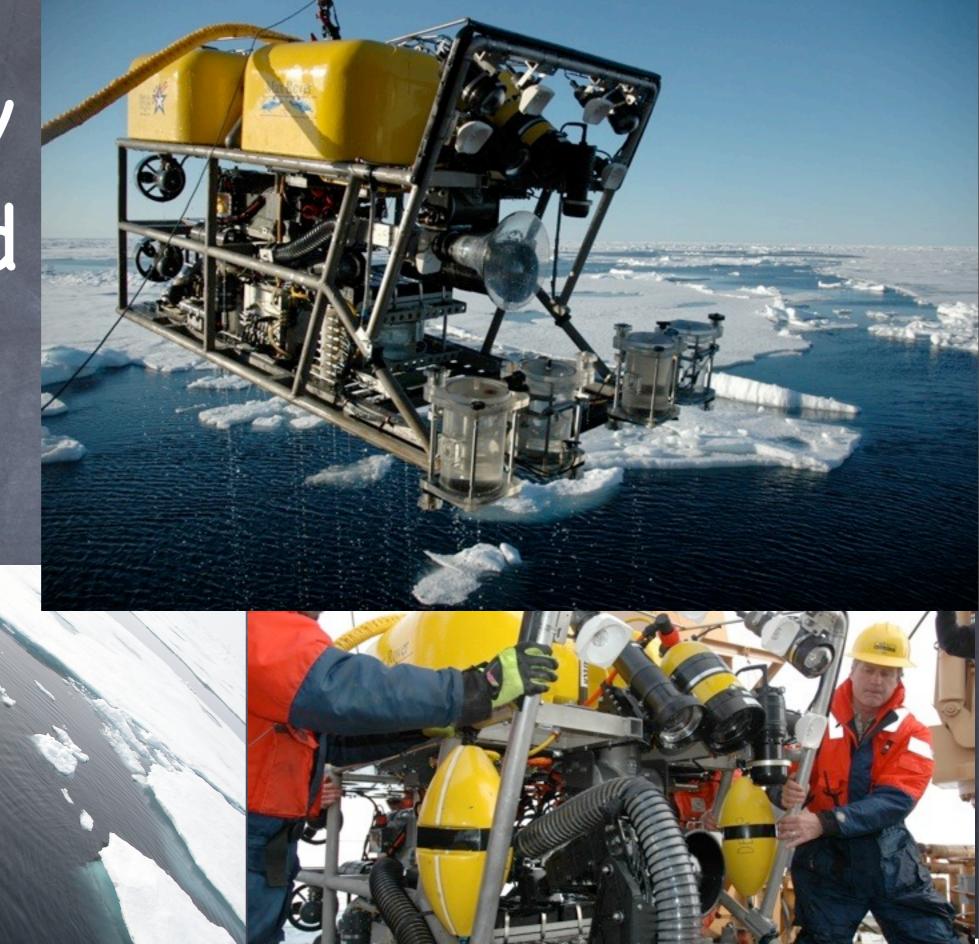


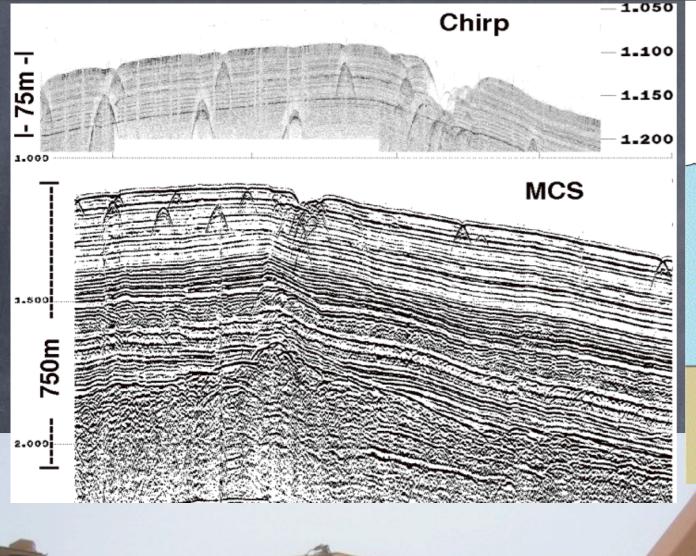


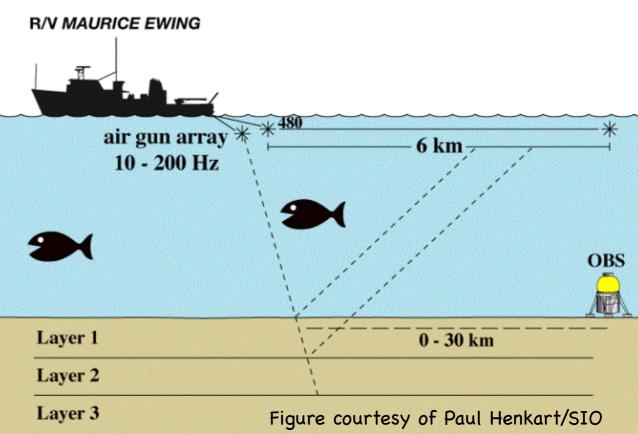
Visiting Science Equipment

- Remotely Operated Vehicles (ROV) and Autonomous Underwater Vehicles (AUV)
- Towed sonars
- Deep seafloor sounding systems (seismic)
- Nets, cores, grabs samplers, dredges
- Ice profilers (EM, radar, laser)
- Gravity meters (now permanent)
- Gliders, moorings, transponder navigation

Remotely
Operated
Vehicle







Multichannel Seismic Profiling



Healy Acknowledgements

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- This work does not represent the opinion or position of any organization.

This talk represents the work of many individuals including engineers, technicians, aircraft and ship crews, and scientists from many organizations and institutions world wide

It is dedicated to the makers and the doers who make these things happen, particularly those who aren't with us any more.

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