

Lecture 23:**Applications of the SVD****Outline:**

- 1) Quick Review
- 2) Application 1: Total Least Squares
 - A recipe
 - Interpretation
- 3) Application 2: Pattern Recognition and Empirical Orthogonal Functions (EOF's/PCA etc.)
 - Examples: Image reconstruction and compression
 - Classification of 1-D Topography (EOF analysis)

Quick Review

SVD of a general $m \times n$ matrix A with rank r

$$\begin{bmatrix} & \\ & \\ & \end{bmatrix} = \begin{bmatrix} & \\ & \\ & \end{bmatrix} \begin{bmatrix} & \\ & \\ & \end{bmatrix} \begin{bmatrix} & \\ & \\ & \end{bmatrix}$$

$A \qquad \qquad U \qquad \qquad \Sigma \qquad \qquad V^T$

Matlab: `[U,S,V]=svd(A)`

SVD: the economy sized version

SVD of a general $m \times n$ matrix A with rank r

$$\begin{bmatrix} & \\ & \\ & \end{bmatrix} = \begin{bmatrix} & \\ & \\ & \end{bmatrix} \begin{bmatrix} & \\ & \\ & \end{bmatrix} \begin{bmatrix} & \\ & \\ & \end{bmatrix}$$

$A \qquad \qquad U \qquad \qquad \Sigma \qquad \qquad V^T$

Matlab: `[U,S,V]=svd(A,0)`

Least squares problems using the SVD

if A is $m \times n$ overdetermined then the solution $\hat{x}$ that minimizes

$$\|e\| = \|b - A\hat{x}\|$$

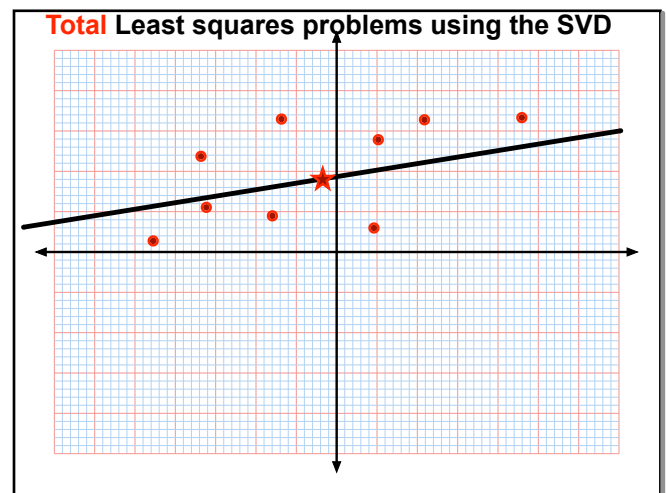
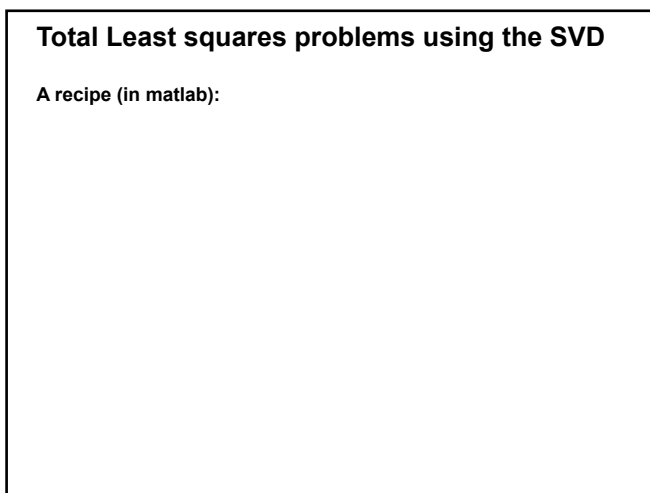
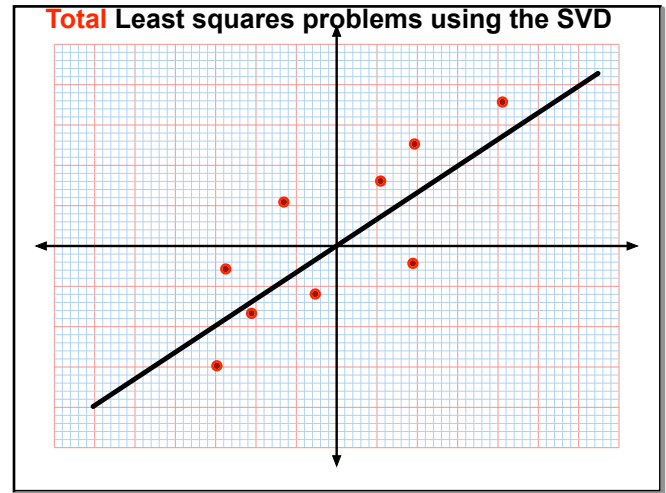
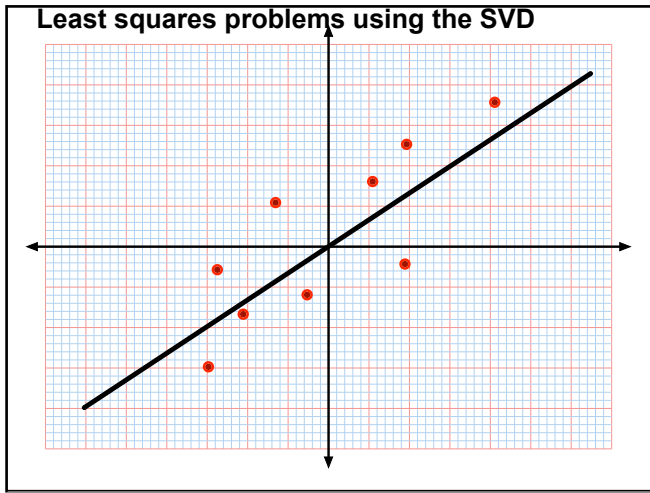
is $\hat{x} = x^+ = A^+ b$ where $A^+ = V \Sigma^+ U^T$ is the **pseudo-inverse**

Comments:

1) if A is invertible $A^+ =$ _____ and $\|e\| =$ _____

2) if A is full column rank x^+ is the unique solution to

3) in general $p = A A^+ b$ is the projection of b onto _____



Total Least squares problems using the SVD

A recipe (in matlab):

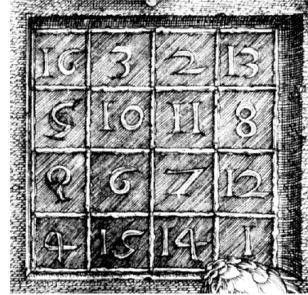
```
x=[ x1 x2 ... xm ]'; y = [ y1 y2 ... ym ]'; % set x, y data
M = [ x y ]; % set Matrix
xMean = mean(M); % center of mass of data
M = M - ones(size(x))*xMean; % de-mean data
[ U,S,V] = svd(M); % get SVD of data
u = V(:,2); % error vector
v = V(:,1); % basis for line l(t)
```

% fancy stuff for plotting etc

```
line = @(t) ones(size(t))*xMean + t*v';
X = line(t);
plot(X(:,1),X(:,2));
```

A demo

Application #2: Pattern recognition and image compression using the SVD



Detail from Durer's "Melancholia I", 1514
(359 x 371 pixel image)

The Big Picture

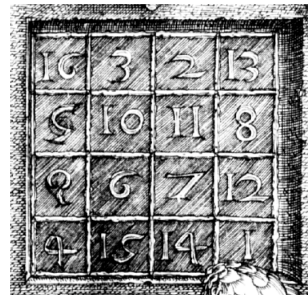


Durer's icon of Melancholy portrays the dangers of obsessive study. Note the many symbols of mathematics and alchemy. (Princeton, History 291 Web page)

http://www.metmuseum.org/toah/hd/durr/hod_43.106.1.htm

Image Compression

Given an original 359 x 371 Image:



We can write it as 359 x 371 matrix A with SVD $A=U\Sigma V^T$
where U is 359 x 359, Σ is 359 x 371 and V is 371 x 371

Image Compression

The spectral theorem for the SVD says that the matrix A can also be written as a sum of rank-1 matrices

$$A = U\Sigma V^T =$$

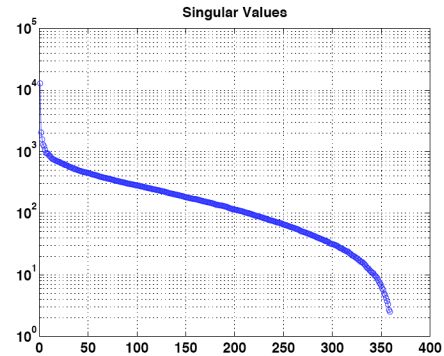
where each rank-1 matrix $u_i v_i^T$ is the size of the original image.

Comments:

- 1) Each of these matrices is a *mode*.
- 2) The strength of each mode is given by the singular value σ_i
- 3) Because the singular values are rank ordered $\sigma_1 \geq \sigma_2 \geq \sigma_3 \dots \geq \sigma_r \geq 0$ significant compression of the image is possible if the spectrum of singular values has only a few large values

Example: Storage for full Matrix is $359 \times 371 = 133189$ pixels
 Storage for a single mode is $359 + 371 + 1 = 731$ pixels
 Compression for a single mode is 99.45%

Spectrum of singular values for A



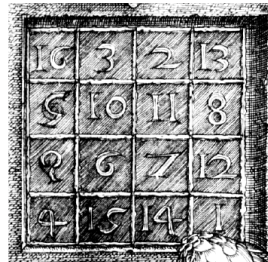
Here the spectrum is principally contained in the first ~200 modes

Mode reconstruction using Matlab

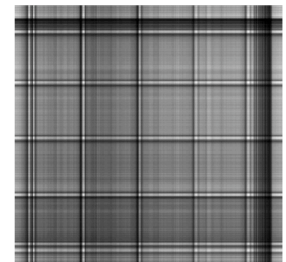
Mode reconstruction using Matlab

```
[U,S,V]=svd(A)
B=U(:,1)*S(1,1)*V(:,1)'
```

Detail from Durer's Melancolia, dated 1514., 359x371 Image



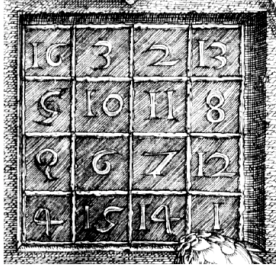
EOF reconstruction with 1 modes



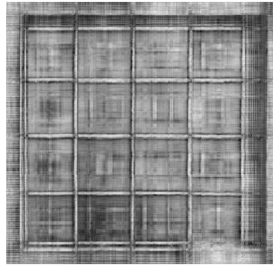
Or as a sum of the first 10 modes as

$$B = U(:, 1:10) * S(1:10, 1:10) * V(:, 1:10)'$$

Detail from Durer's Melancolia, dated 1514., 359x371 Image



EOF reconstruction with 10 modes



which only uses 5% of the storage ($10 \times 359 + 10 \times 371 + 10 = 7310$ pixels vs $359 \times 371 = 133189$ pixels).

Matlab Demo

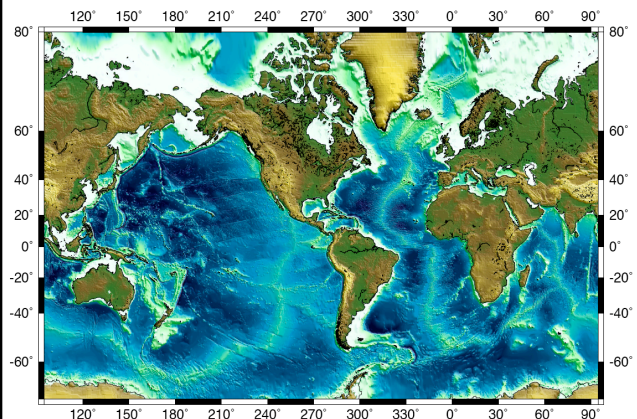
Application #3: Pattern Extraction -- a real world research example of EOFs

A Global Analysis Of Midocean Ridge Axial Topography

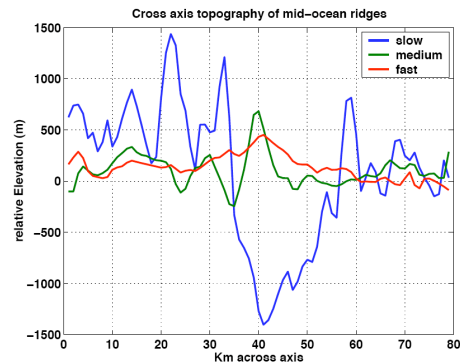
Chris Small (LDEO)

GEOPHYSICAL JOURNAL INTERNATIONAL 116 (1): 64-84 JAN 1994

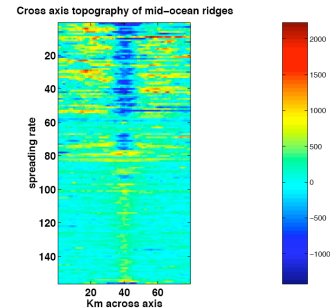
Application #3: Pattern Extraction -- a real world research example of EOFs



The data: cross axis topography profiles from different spreading rates



Form a matrix A (179×80) of elevation vs. distance across the ridge



and again take the SVD $A = U\Sigma V^T$. Here U is the same size as A and Σ and V are both square 80×80 matrices.

EOF analysis

Now the rows of V^T form an orthonormal basis for the row space of A
i.e. each profile (row of A) can be written as a linear combination of the rows of V^T or

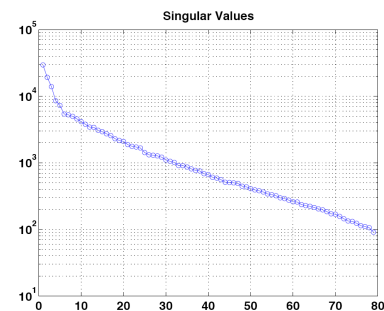
$$A = CV^T$$

Inspection of the SVD shows that $C = U\Sigma$.

Here, the rows of V^T are known as *Empirical Orthogonal Functions* or EOFs.

EOF analysis

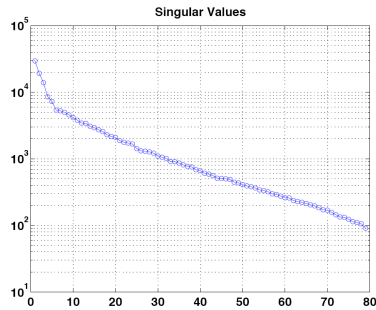
If the spectrum of Singular values contains a few large values and a long tail of very small values, it may be possible to reconstruct the rows of A with only a small number of EOFs. The spectrum for this data looks like



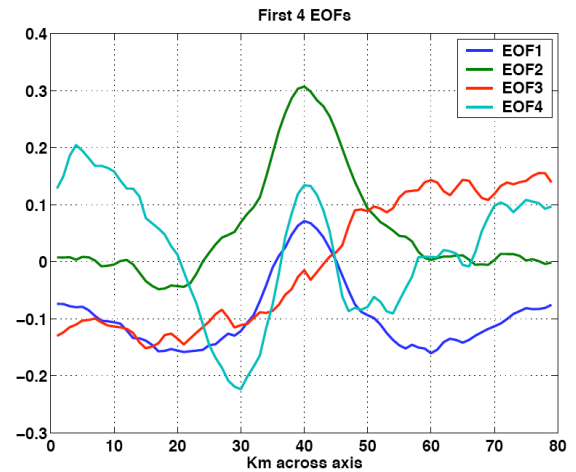
Here much of the information is included in the first 4 EOF's

EOF analysis

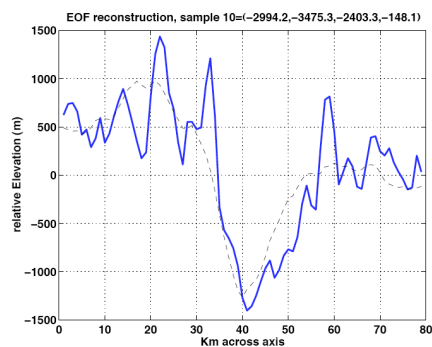
If the spectrum of Singular values contains a few large values and a long tail of very small values, it may be possible to reconstruct the rows of A with only a small number of EOFs. The spectrum for this data looks like



Here much of the information is included in the first 4 EOF's

First 4 EOF's

And we can reconstruct individual profiles as combinations of the first 4 EOF's. For example here is one for a *slow* spreading rate

**Intermediate spreading rate**