

Q: Is The double-difference
technique capable of determining
the absolute locations of a
pair of earthquakes, presuming
that the velocity structure is
known and that the differential
traveltimes, ΔT are known every-
where on the earth's surface?

A: Yes.

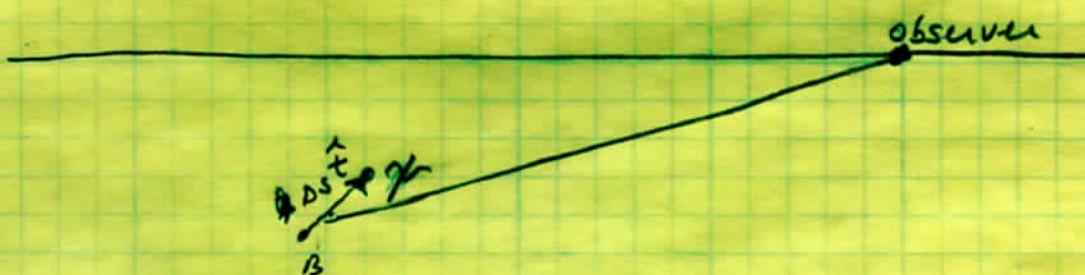
B. Menke

12-17-03

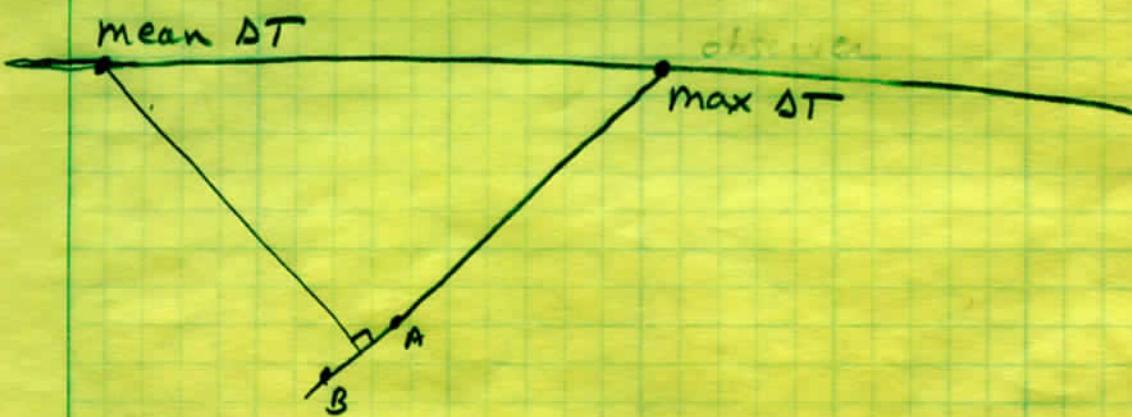
Double-Difference locations in a homogeneous Earth, Bill Menke, Dec. 16, 2003
at known velocity, v

- ① The traveltime difference between earthquakes A and B, separated by \hat{ds} is

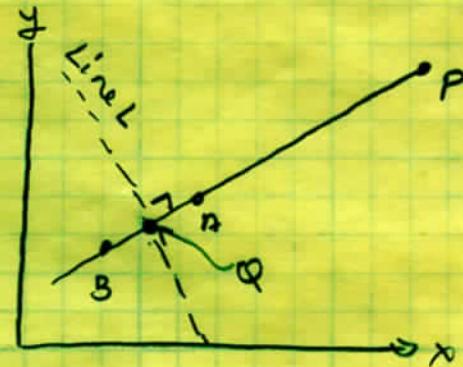
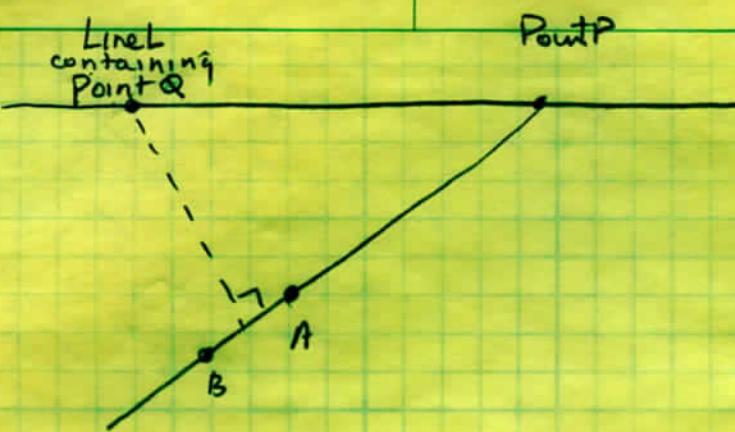
$$\Delta T = (t^B - t^A) + \frac{ds}{v} \cos \gamma$$
 where t^A, t^B are origin times.



- ② The maximum ΔT occurs when the line to the observer is parallel to \hat{t} . The mean $(t^B - t^A)$ when \perp to \hat{t}



- ③ In 3D, the max ΔT is a line that intersects the earth's surface at a point. The mean ΔT is a plane that intersects the surface at a line.



4). Let's assume ΔT is known everywhere on the surface of the earth (including sides,

$$\text{so } \Delta T_{\max} = (t^B - t^A) + \frac{\Delta s}{v}, \quad \Delta T_{\min} = (t^B - t^A) - \frac{\Delta s}{v}$$

and $\Delta T_{\text{mean}} = (t^B - t^A)$ can be measured.

$$\text{note } \frac{\Delta s}{v} = (\Delta T_{\max} - \Delta T_{\min})/2$$

Then

Point P: where $\Delta T(x, y, z=0)$ is max

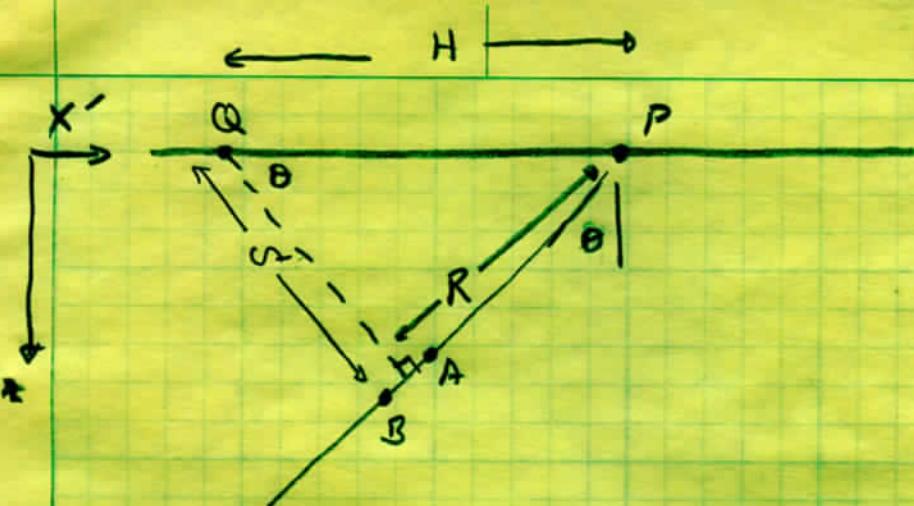
Line L: where $\Delta T(x, y, z=0) = \frac{1}{2}(\Delta T_{\max} + \Delta T_{\min})$

Point Q: point on L closest to P.

note That The distance H from Q to P is known

5) Note That $\Delta T(x, y, z=0)$ has mirror symmetry about line \overline{QP} . So The problem is 2D in a coordinate system aligned so $x' \parallel$ to \overline{QP} .

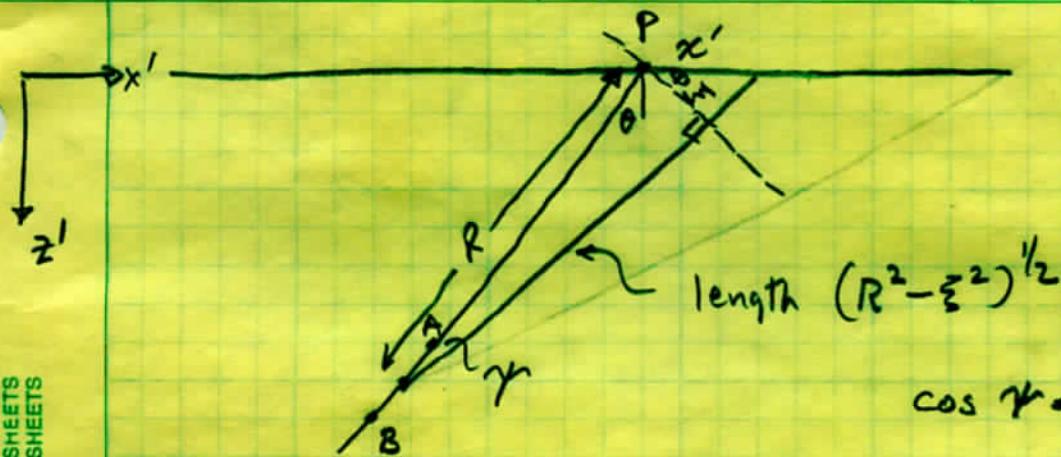
(3)



- 22-141 50 SHEETS
22-142 100 SHEETS
22-144 200 SHEETS
CAMPAD*
6. While points Q and P are known, the orientation θ of line \overline{BAP} , and the length, R , are unknown (since the earthquakes have unknown location).
 7. Since $\triangle QBP$ is right, R and S are functions of θ : $\sin \theta = R/H$ or $R = R(\theta) = H \sin \theta$
 $\cos \theta = S/H$, $S = S(\theta) = H \cos \theta$. So there is really only one unknown, θ .
 8. The second derivative $\frac{\partial^2 \Delta T}{\partial x^2} \Big|_{x'=P}$ can be measured.
 For fixed θ it will clearly decrease as R increases. That is, as the earthquakes are farther from P . It must therefore contain information about R .

9. The derivative in the ξ direction is :

(4)



$$\cos \gamma = \frac{(R^2 - \xi^2)^{1/2}}{R}$$

$$\begin{aligned} \Delta T &= (t^B - t^A) + \frac{\Delta s}{v} \cos \gamma \\ &= (t^B - t^A) + \frac{\Delta s}{v} \frac{(R^2 - \xi^2)^{1/2}}{R} \end{aligned}$$

$$\frac{\partial \Delta T}{\partial \xi} = -\frac{\Delta s}{vR} \left(\frac{1}{2} (-2\xi) (R^2 - \xi^2)^{-1/2} \right) = -\frac{\Delta s}{vR} \xi (R^2 - \xi^2)^{-1/2}$$

$$\frac{\partial^2 \Delta T}{\partial \xi^2} = -\frac{\Delta s}{vR} \left\{ (R^2 - \xi^2)^{-1/2} + \left(\frac{1}{2} (-2\xi) \right) (-2) (R^2 - \xi^2)^{-3/2} \right\}$$

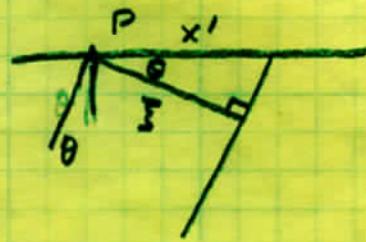
$$\left. \frac{\partial^2 \Delta T}{\partial \xi^2} \right|_{\xi=0} = -\frac{\Delta s}{vR^2}$$

$\xi=0$
(at P)

(5)

10. The derivative in the x' direction is

$$\cos\theta = \frac{s}{x_1}$$



$$\bar{s} = \cos\theta x'$$

$$\frac{ds}{dx'} = \cos\theta$$

$$\frac{\partial^2}{\partial x'^2} = \frac{\partial s}{\partial x'} \frac{\partial}{\partial s} = \cos\theta \frac{\partial}{\partial s}$$

$$\frac{\partial^2}{\partial x'^2} = \cos^2\theta \frac{\partial^2}{\partial s^2}$$

so

$$\frac{\partial^2 \Delta T}{\partial x'^2} = \cos^2\theta \frac{\partial^2 \Delta T}{\partial s^2} = -\cos^2\theta \frac{\Delta s}{VR^2}$$

but $R = H \sin\theta$ (from 7) so

$$\frac{\partial^2 \Delta T}{\partial x'^2} = -\frac{\cos^2\theta \Delta s}{H^2 \sin^2\theta V}$$

or Δ^2

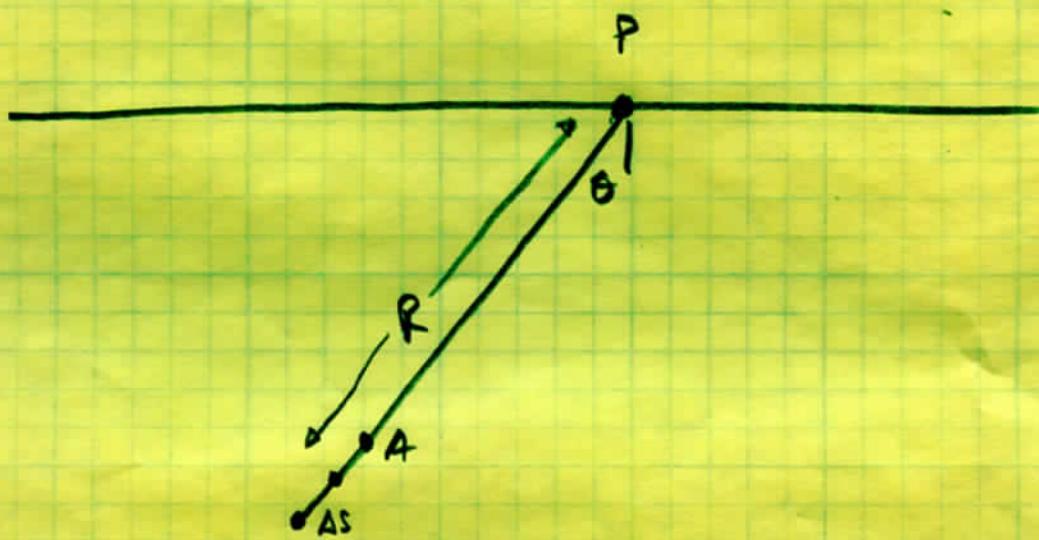
$$\tan^2\theta = \left(\frac{\Delta s}{V}\right) \frac{1}{H^2} / \frac{\partial^2 \Delta T}{\partial x'^2}$$

Note that r.h.s. contains only known quantities, so θ known

(6)

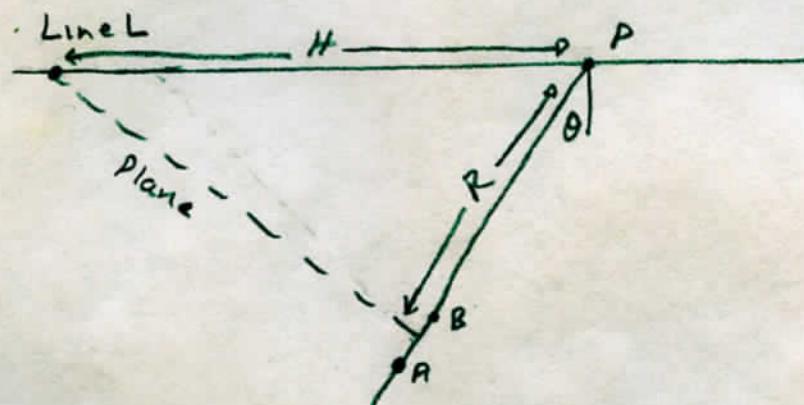
12. So measurements of DT on the surface of the earth suffice to estimate P , θ , R , ΔS .

We can thus locate earthquakes A and B

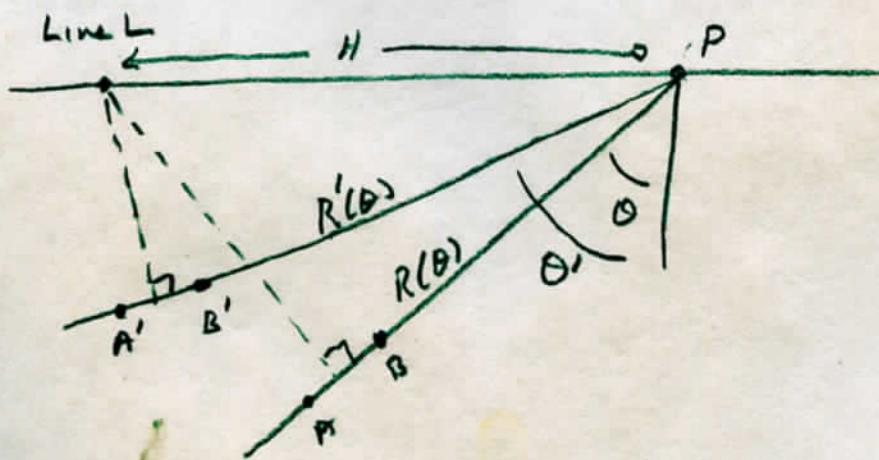


Double-Difference locations, Attendum, W Meake, 12-17-03
Generalization
Methodology to a vertically stratified earth, $v(z)$

1. In the homogeneous earth, the directions of mean differential traveltime were a plane that intersected the earth's surface at Line, L.



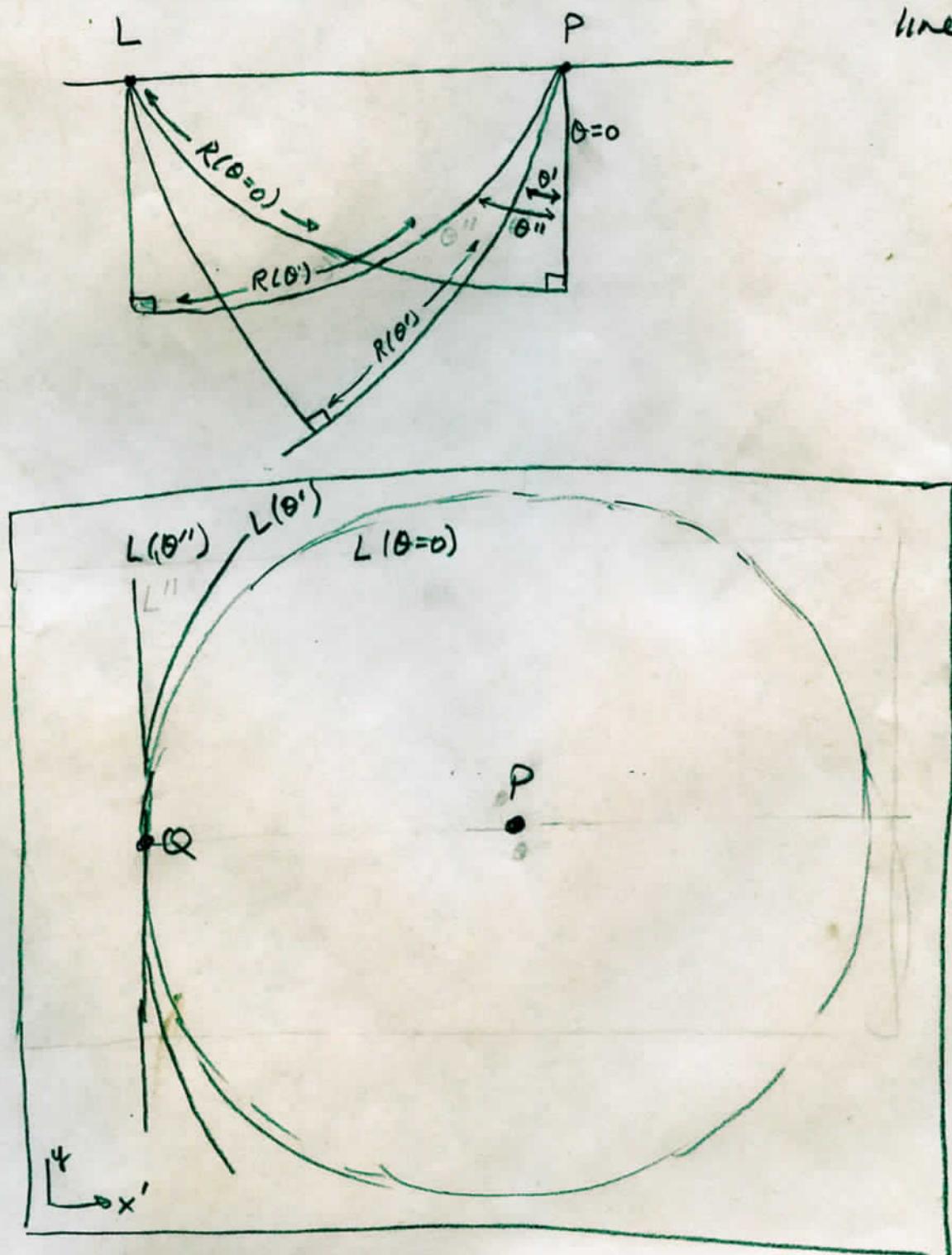
This allowed multiple choices of θ all to match a given position of L.



so The distance H did not determine the range, R.

(2)

2. When v varies with depth, z , the pattern of mean differential times is not a line, but rather a curve on the surface of the earth. The shape of this curve is different for different θ 's. (Note the problem still has minor symmetry about a line PQ).



So the shape of $L(\theta)$ is different for each θ . Thus a measurement of L determines θ , and hence $R(\theta)$. Unlike the homogenous case, calculation of $\frac{\partial^2 T}{\partial x^2}$ is not needed to locate the pair of conjugates.

3. This result carries over to the general $v(x, y, z)$ case, except that the differential traveltime is no longer symmetric about the line PQ . (Q now defined as the point of closest approach of L to P).