

Force equivalent to an initial condition for a second order linear differential equation

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1. We consider the 2nd order linear differential equation:

$$\mathcal{L}y = \left\{ \frac{d}{dt}p(t) \frac{d}{dt} + p(t) \right\} yp(t) = f(t)$$

defined on the interval (T_1, T_2) . The Green function $G(t, \tau)$, satisfies $\mathcal{L}G(t, \tau) = \delta(t - \tau)$ and homogenous boundary conditions.

2. \mathcal{L} is self-adjoint, as

$$\left(\frac{d}{dt}p(t) \frac{d}{dt} + p(t) \right)^\dagger = \left(\frac{d}{dt} \right)^\dagger (p(t))^\dagger \left(\frac{d}{dt} \right)^\dagger + (p(t))^\dagger = \frac{d}{dt}p(t) \frac{d}{dt} + p(t)$$

as d/dt is anti-self-adjoint and $p(t)$ is self-adjoint. It follows that

$$(v, \mathcal{L}u)_t = (u, \mathcal{L}v)_t \quad \text{with} \quad (a, b)_t = \int_{T_1}^{T_2} ab \, dt$$

for any two solutions, u and v .

3. The Green function satisfies the reciprocity relationship $G(t, \tau) = G(\tau, t)$. Inserting the Green function for source at τ_1 and τ_2 :

$$\begin{aligned} (G(t, \tau_2), \delta(t - \tau_1))_t &= (G(t, \tau_1), \delta(t - \tau_2))_t \\ G(\tau_1, \tau_2) &= G(\tau_2, \tau_1) \end{aligned}$$

4. Green's identity for two solutions, u and v is

$$\int_{T_1}^{T_2} (u \mathcal{L}v - v \mathcal{L}u) \, dt = (p u v_t - p u_t v)_{T_1}^{T_2}$$

with $u_t \equiv du/dt$ and $v_t \equiv dv/dt$. It is derived by applying integration by parts

$$\begin{aligned} &\int_{T_1}^{T_2} (u \mathcal{L}v - v \mathcal{L}u) \, dt = \\ &\int_{T_1}^{T_2} \left(u \frac{d}{dt} p v_t + u p v - v \frac{d}{dt} p u_t - v p u \right) \, dt \\ &= \int_{T_1}^{T_2} \left(u \frac{d}{dt} (p v_t) - v \frac{d}{dt} (p u_t) \right) \, dt \end{aligned}$$

$$\begin{aligned}
&= (p u v_t - p u_t v)|_{T_1}^{T_2} - \int_{T_1}^{T_2} (p u_t v_t - p u_t v_t) dt \\
&= (p u v_t - p u_t v)|_{T_1}^{T_2}
\end{aligned}$$

5. A formula for the solution involving initial conditions:

$$\begin{aligned}
&y(t = T_1) \quad \text{and} \quad y_t(t = T_1) \\
&y(t = T_2) = 0 \quad \text{and} \quad y_t(t = T_2) = 0
\end{aligned}$$

is obtained by equating $u = y$ and $v = G(t, \tau)$

$$\begin{aligned}
&\int_{t=T_1}^{t=T_2} (u \mathcal{L}v - v \mathcal{L}u) dt = p(t)(u(t)v_t(t) - u_t(t)v(t)) \Big|_{t=T_1}^{t=T_2} \\
&\int_{t=T_1}^{t=T_2} (y \delta(t - \tau) - G(t, \tau) f(t)) dt = p(t)[y(t)G_t(t, \tau) - y_t G(t, \tau)] \Big|_{t=T_1}^{t=T_2} \\
&y(\tau) - \int_{t=T_1}^{t=T_2} G(t, \tau) f(t) dt = p(t)[y(t)G_t(t, \tau) - y_t G(t, \tau)] \Big|_{t=T_1}^{t=T_2} \\
&y(\tau) = \int_{t=T_1}^{t=T_2} G(t, \tau) f(t) dt + p(t)[y(t)G_t(t, \tau) - y_t G(t, \tau)] \Big|_{t=T_1}^{t=T_2} \\
&y(\tau) = \int_{t=T_1}^{t=T_2} G(t, \tau) f(t) dt - p(t)[y_t G(t, \tau) - y(t)G_t(t, \tau)] \Big|_{t=T_1}^{t=T_2}
\end{aligned}$$

Now swap the names of t and τ

$$y(t) = \int_{\tau=T_1}^{\tau=T_2} G(\tau, t) f(\tau) d\tau - p(\tau)[y_\tau G(\tau, t) - y(\tau)G_\tau(\tau, t)] \Big|_{\tau=T_1}^{\tau=T_2}$$

Apply reciprocity, noting $G_\tau(\tau, t) = \frac{\partial}{\partial \tau} G(\tau, t) = \frac{\partial}{\partial \tau} G(t, \tau)$

$$\begin{aligned}
&y(t) = \int_{\tau=T_1}^{\tau=T_2} G(t, \tau) f(\tau) d\tau - p(\tau)[y_\tau G(t, \tau) - y(\tau)G_\tau(\tau, t)] \Big|_{\tau=T_1}^{\tau=T_2} \\
&y(t) = \int_{\tau=T_1}^{\tau=T_2} G(t, \tau) f(\tau) d\tau - p(\tau) \left[y_\tau(\tau)G(t, \tau) - y(\tau) \frac{\partial G(t, \tau)}{\partial \tau} \right] \Big|_{\tau=T_1}^{\tau=T_2}
\end{aligned}$$

This results agrees with (12.1.5) of Copley (2015). By assumption, only the lower boundary condition contributes

$$y(t) = \int_{\tau=T_1}^{\tau=T_2} G(t, \tau) f(\tau) d\tau + p(\tau = T_1) \left[y_\tau(\tau = T_1)G(t, \tau = T_1) - y(\tau = T_1) \frac{\partial G(t, \tau = T_1)}{\partial \tau} \right]$$

6. Inserting the force

$$f(\tau) = A\delta(\tau - (T_1 + \varepsilon)) + B \frac{\partial}{\partial \tau} \delta(\tau - (T_1 + \varepsilon))$$

with $\varepsilon \ll (T_2 - T_1)$ into the Green function integral, and integrating

$$\int_{\tau=T_1}^{\tau=T_2} G(t, \tau) f(\tau) d\tau = AG(t, T_1) - B \frac{\partial G(t, \tau = T_1)}{\partial \tau}$$

7. With the choices

$$A = p(\tau = T_1)y_\tau(\tau = T_1) \quad \text{and} \quad B = p(\tau = T_1)y(\tau = T_1)$$

the force is equivalent to the boundary condition. Thus the boundary conditions at T_1 can be replaced by a virtual force acting at time $T_1 + \varepsilon$

Copley, L., 2015, Chapter 12, Non-Homogeneous Boundary Value Problems: Green's Functions, in Mathematics for the Physical Sciences, De Gruyter Open Poland, www.degruyter.com/document/doi/10.2478/9783110409475.12/html