

A Data Resolution Matrix for Generalized Least Squares
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This derivation parallels the one for the model resolution matrix that's in Section 5.3 of Menke (2018).

The standard General Least Squares setup is:

$$\mathbf{Fm} = \mathbf{f} \text{ with } \mathbf{F} = \begin{bmatrix} \mathbf{C}_d^{-1/2} \mathbf{G} \\ \mathbf{C}_h^{-1/2} \mathbf{H} \end{bmatrix} \text{ and } \mathbf{f}^{\text{obs}} = \begin{bmatrix} \mathbf{C}_d^{-1/2} \mathbf{d}^{\text{obs}} \\ \mathbf{C}_h^{-1/2} \mathbf{h}^{\text{pri}} \end{bmatrix} \quad (1)$$

The solution is $\mathbf{m}^{\text{est}} = [\mathbf{F}^T \mathbf{F}]^{-1} \mathbf{F}^T \mathbf{f}^{\text{obs}}$. According to Menke (2018, their Eqn. 5.48), this solution is equivalent to;

$$\mathbf{m}^{\text{est}} = \mathbf{F}^{-g} \mathbf{f}^{\text{obs}} = [\mathbf{A}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \quad \mathbf{A}^{-1} \mathbf{H}^T \mathbf{C}_h^{-1}] \begin{bmatrix} \mathbf{d}^{\text{obs}} \\ \mathbf{h}^{\text{pri}} \end{bmatrix} \quad (2)$$

with $\mathbf{A} \equiv \mathbf{F}^T \mathbf{F} = \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{G} + \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}$.

Let the model parameters $\mathbf{m}^{(H)}$ be those predicted on the basis of the prior information alone:

$$\mathbf{m}^{(H)} = [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} \quad (3)$$

Following Menke (2018), we assume that the matrix inverse exists; it can always be made to exist by adding very weak smallness information, if necessary. These model parameters predict data $\mathbf{d}^{(H)} = \mathbf{Gm}^{(H)}$, which we will call the “prior data”. Now define two deviations, the deviation of the observed data from the prior data $\Delta \mathbf{d}^{\text{obs}} \equiv \mathbf{d}^{\text{obs}} - \mathbf{d}^{(H)}$ and the deviations of the predicted data from the prior data $\Delta \mathbf{d}^{\text{pre}} \equiv \mathbf{d}^{\text{pre}} - \mathbf{d}^{(H)}$. We will show that a data resolution matrix \mathbf{N} can be defined such that $\Delta \mathbf{d}^{\text{pre}} = \mathbf{N} \Delta \mathbf{d}^{\text{obs}}$, and furthermore, that:

$$\mathbf{N} = \mathbf{GA}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \quad (4)$$

Proof. Start with the predicted data $\mathbf{d}^{\text{pre}} = \mathbf{Gm}^{\text{est}}$ and insert the form of \mathbf{m}^{est} given in (2).

$$\mathbf{d}^{\text{pre}} = \mathbf{GA}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} + \mathbf{GA}^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}}$$

Subtract $\mathbf{d}^{(H)}$ from both sides, to obtain a deviation:

$$\Delta \mathbf{d}^{\text{pre}} \equiv \mathbf{d}^{\text{pre}} - \mathbf{d}^{(H)} = \mathbf{GA}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} + \mathbf{GA}^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} - \mathbf{d}^{(H)}$$

Replace $\mathbf{d}^{(H)}$ with $\mathbf{Gm}^{(H)}$ and insert (3):

$$\Delta \mathbf{d}^{\text{pre}} = \mathbf{GA}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} + \mathbf{GA}^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} - \mathbf{G} [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}}$$

Manipulate algebraically:

$$\begin{aligned} \Delta \mathbf{d}^{\text{pre}} &= \mathbf{GA}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} + \mathbf{GA}^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} - \mathbf{G} [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} \\ &= \mathbf{GA}^{-1} \{ \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} + \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} - \mathbf{A} [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} \} \\ &= \mathbf{GA}^{-1} \{ \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} + \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} - [\mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{G} + \mathbf{H}^T \mathbf{C}_d^{-1} \mathbf{H}] [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} \} \\ &= \mathbf{GA}^{-1} \{ \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} + \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} - [\mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{G}] [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} \\ &\quad - [\mathbf{H}^T \mathbf{C}_d^{-1} \mathbf{H}] [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} \} \\ &= \mathbf{GA}^{-1} \{ \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} + \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} - [\mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{G}] [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} - \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} \} \\ &= \mathbf{GA}^{-1} \{ \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} - [\mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{G}] [\mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{H}]^{-1} \mathbf{H}^T \mathbf{C}_h^{-1} \mathbf{h}^{\text{pri}} \} \\ &= \mathbf{GA}^{-1} \{ \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} - [\mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{G}] \mathbf{m}^{(\text{H})} \} \\ &= \mathbf{GA}^{-1} \{ \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{\text{obs}} - \mathbf{G}^T \mathbf{C}_d^{-1} \mathbf{d}^{(\text{H})} \} \\ &= \mathbf{GA}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \{ \mathbf{d}^{\text{obs}} - \mathbf{d}^{(\text{H})} \} \\ &= \mathbf{GA}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \{ \mathbf{d}^{\text{obs}} - \mathbf{d}^{(\text{H})} \} = \mathbf{N} \Delta \mathbf{d}^{\text{obs}} \quad \text{with} \quad \mathbf{N} \equiv \mathbf{GA}^{-1} \mathbf{G}^T \mathbf{C}_d^{-1} \end{aligned}$$

Q.E.D.

