

**Adjoint formulation for data kernel and error gradient when
the data is a linear functional of the field**

Bill Menke, December 26, 2020

Summary: We consider data d_i (at x_i) related to a field u by the linear functional $d_i = (h_i, u)$. Here the field u satisfies $\mathcal{U}u = f$. We show that the adjoint field λ_i part of the kernel calculation is the only part that depends on h_i , and that it does so through the adjoint field equation $\mathcal{U}^\dagger \lambda_i = h_i$. The adjoint equation and adjoint field are the same, irrespective of whether the model parameters m_j parameterize the differential operator \mathcal{U} or the source of the field f .

For differential data, $h_i = -\frac{d}{dx} \delta(x - x_i)$; that is, the adjoint source is a dipole.

Consequently, a kernel \mathbf{G} corresponding to differential data \mathbf{d} can be calculated via a change to the adjoint source. This method is different from post-facto calculation of \mathbf{G} , where one starts with a kernel for the original data, $\mathbf{d}' = \mathbf{G}'\mathbf{m}$ and then multiplies by a differential operator \mathbf{D} to get $\mathbf{d} = \mathbf{D}\mathbf{d}' = (\mathbf{D}\mathbf{G}')\mathbf{m} = \mathbf{G}\mathbf{m}$. I think that the direct method is less affected by round-off error.

Furthermore, the adjoint field calculation is the only the part of the calculation of the gradient of the total error that depends upon h_i . The adjoint equation and adjoint field are the same (though not the same as for the kernel), irrespective of whether the model parameters m_j parameterize the differential operator \mathcal{U} or the source of the field f .

(Part 1) Kernel when source depends on a model parameters m_j

Data equation $d_i = (h_i, u)$ and its derivative $\frac{dd_i}{dm_j} = \left(h_i, \frac{du}{dm_j} \right)$

Kernel equation $dd_i = \sum_j \frac{dd_i}{dm_j} dm_j$ with kernel $G_{ij} \equiv \frac{dd_i}{dm_j}$

Field eqn: $\mathcal{U} u(m) = f(m)$ and its solution $u(m) = \mathcal{U}^{-1} f(m)$

Field derivative: $\frac{du}{dm_j} = \mathcal{U}^{-1} \frac{df}{dm_j}$

Derivation of kernel:

$\frac{dd_i}{dm_j} = \left(h_i, \frac{du}{dm_j} \right) = \left(h_i, \mathcal{U}^{-1} \frac{df}{dm_j} \right) = \left(\mathcal{U}^{-1\dagger} h_i, \frac{df}{dm_j} \right) = \left(\lambda_i, \frac{df}{dm_j} \right)$ with $\mathcal{U}^\dagger \lambda_i = h_i$

so the kernel is $G_{ij} = \left(\lambda_i, \frac{df}{dm_j} \right)$

suppose $f = \sum_k m_k \delta(x - \xi_k)$ so $\frac{df}{dm_j} = \delta(x - \xi_j)$

then $G_{ij} = \left(\lambda_i, \delta(x - \xi_j) \right) = \lambda_i(\xi_j)$

Differential data: $d_i = (du/dx)|_{x_i} = \left(-\frac{d}{dx} \delta(x - x_i), u \right)$ so $h_i = -\frac{d}{dx} \delta(x - x_i)$

and adjoint equation is $\mathcal{U}^\dagger \lambda_i = -\frac{d}{dx} \delta(x - x_i)$

In the case where $d_i = W(x)(du/dx)|_{x_i}$, one could set $h_i = -W(x) \frac{d}{dx} \delta(x - x_i) - \frac{dW}{dx} \delta(x - x_i)$ since then $d_i = \left[\frac{d}{dx} (Wu) - \frac{dW}{dx} u \right] \Big|_{x_i} = \left[W \frac{du}{dx} \right] \Big|_{x_i}$

(Part 2) Kernel when differential operator depends on parameters m_j

Data eqn: $d_i = (h_i, u)$ and its derivative $\frac{dd_i}{dm_j} = \left(h_i, \frac{du}{dm_j} \right)$

Field eqn: $\mathcal{U}(m) u(m) = f$ so $u = \mathcal{U}^{-1} f$

Field derivative $du/dm_j = (d\mathcal{U}^{-1}/dm_j) f = -\mathcal{U}^{-1} (d\mathcal{U}/dm_j) \mathcal{U}^{-1} f$

$$\frac{du}{dm_j} = -\mathcal{U}^{-1} \left\{ \left(\frac{d\mathcal{U}}{dm_j} \right) u \right\}$$

Derivation of kernel:

$$\begin{aligned} \frac{dd_i}{dm_j} &= \left(h_i, \frac{du}{dm_j} \right) = - \left(h_i, \mathcal{U}^{-1} \left\{ \left(\frac{d\mathcal{U}}{dm_j} \right) u \right\} \right) = \\ &= - \left(\mathcal{U}^{-1\dagger} h_i, \left\{ \left(\frac{d\mathcal{U}}{dm_j} \right) u \right\} \right) = - \left(\lambda_i, \left\{ \left(\frac{d\mathcal{U}}{dm_j} \right) u \right\} \right) \text{ with } \mathcal{U}^\dagger \lambda_i = h_i \end{aligned}$$

suppose $\mathcal{U} = \sum_k m_k \delta(x - \xi_k) \frac{d}{dt^2} + (\text{terms not depending upon } m_k)$

then $\frac{d\mathcal{U}}{dm_j} = \delta(x - \xi_j) \frac{d}{dt^2}$ and $\left(\frac{\delta\mathcal{U}}{\delta m_j} \right) u = \ddot{u} \delta(x - \xi_j)$

$G_{ij} = \left(\lambda_i, \ddot{u} \delta(x - \xi_j) \right) = \lambda_i(\xi_j, t) \star \ddot{u}(\xi_j, t)$ (with \star signifying time correlation)

Differential data: $d_i = (d/dx)u|_{x_i} = \left(-\frac{d}{dx} \delta(x - x_i), u \right)$ so $h_i = -\frac{d}{dx} \delta(x - x_i)$

and adjoint equation is $\mathcal{U}^\dagger \lambda_i = \frac{d}{dx} \delta(x - x_i)$ (same as in Part 1).

(Part 3) Equivalence in Part 1 to Green function integral

Let's write $\frac{du}{dm_j} = \mathcal{U}^{-1} \frac{df}{dm_j}$ as $v = \mathcal{U}^{-1} \varphi$ for short

$$\mathcal{U} v(x) = \varphi(x)$$

Standard Green function setup

$$v(x_i) = \mathcal{U}_{x_i}^{-1} \varphi(x_i) = \int_x K(x_i, x) \varphi(x) dx \equiv \left(K(x_i, x), \varphi(x) \right)_x$$

With Green function satisfying $\mathcal{U}_{x_i} K(x_i, x) = \delta(x_i - x)$ (datum at x_i , source at x)

Adjoint method

$$\begin{aligned} v(x_i) &= \left(\delta(x - x_i), v(x) \right)_x = \left(\delta(x - x_i), \mathcal{U}_x^{-1} \varphi(x) \right)_x = \left(\mathcal{U}_x^{-1\dagger} \delta(x - x_i), \varphi(x) \right)_x = \\ &= \left(\lambda(x, x_i), \varphi(x) \right)_x \text{ with } \mathcal{U}_x^\dagger \lambda(x, x_i) = \delta(x - x_i) \end{aligned}$$

interchanging x with x_i in the differential equation $\mathcal{U}_{x_i}^\dagger \lambda(x_i, x) = \delta(x_i - x)$

Comparing inner products, we see that order of arguments of λ and K are reversed, so $\lambda = K^\dagger$
Comparing the differential equations, we also see that $\lambda = K^\dagger$ (see Part 4)
Thus, the result in Part 1 of $G_{ij} = (\lambda_i, \varphi)$ is just a Green function integral

(Part 4) Standard proof for relationship between Green function of original and adjoint equations

$$\begin{aligned}(u, \mathcal{U}v) &= (\mathcal{U}^\dagger u, v) \text{ with } u = G^\dagger(x, z) \text{ and } v = G(x, y) \\ \text{and } \mathcal{U}^\dagger G^\dagger(x, z) &= \delta(x - z) \text{ and } \mathcal{U}G(x, y) = \delta(x - y) \\ (G^\dagger(x, z), \delta(x - y)) &= (\delta(x - z), G(x, y)) = 0 \\ G^\dagger(y, z) &= G(z, y)\end{aligned}$$

(Part 5) Gradient of total error, following Part 1.

$$\begin{aligned}E &= (e, e) \text{ so } \frac{dE}{dm_j} = 2 \left(e, \frac{de}{dm_j} \right) \\ e &= d^{obs} - d \text{ so } \frac{de}{dm_j} = -\frac{dd}{dm_j} \\ -\frac{1}{2} \frac{dE}{dm_j} &= \left(e, \frac{dd}{dm_j} \right)_{x_i} = \left(e, \left(h(x_i, x), \mathcal{U}_x^{-1} \frac{df}{dm_j} \right)_{x'} \right)_{x_i} \\ \text{using rule } \left(a(x_i), (B(x_i, x), c(x))_{x'} \right)_{x_i} &= \left(\left(a(x_i), B^\dagger(x, x_i) \right)_{x_i}, c(x) \right)_x \text{ (see Part 6)} \\ -\frac{1}{2} \frac{dE}{dm_j} &= \left(\left(h^\dagger(x, x_i), e(x_i) \right)_{x_i}, \mathcal{U}_x^{-1} \frac{df}{dm_j} \right) = \\ &= \left(\mathcal{U}_x^{-1\dagger} \left(e, h^\dagger(x_i, x) \right)_{x_i}, \frac{df}{dm_j} \right)_x = \left(\lambda, \frac{df}{dm_j} \right)_x \text{ with } \mathcal{U}_x^\dagger \lambda = \left(e, h^\dagger(x_i, x) \right)_{x_i} \\ \frac{dE}{dm_j} &= -2 \left(\lambda, \frac{df}{dm_j} \right)_x\end{aligned}$$

(Part 6) Standard proof of rule

$$\begin{aligned}\left(a(x_i), (B(x_i, x), c(x))_{x'} \right)_{x_i} &= \left(\left(B^\dagger(x, x_i), a(x_i) \right)_{x_i}, c(x) \right)_x \\ \int_{x_i} a(x_i) \left(\int_x B(x_i, x) c(x) dx \right) dx_i &= \int_x \left(\int_{x_i} B(x_i, x) a(x_i) dx_i \right) c(x) dx = \\ &= \int_x \left(\int_{x_i} B^\dagger(x, x_i) a(x_i) dx_i \right) c(x) dx \text{ with } B^\dagger(x, x_i) = B(x_i, x)\end{aligned}$$

(Part 7) Gradient of total error, following Part 2.

$$-\frac{1}{2} \frac{dE}{dm_j} = \left(e, \frac{dd}{dm_j} \right)_{x_i} = \left(e, \left(h(x_i, x), \mathcal{U}^{-1} \left\{ \left(\frac{d\mathcal{U}}{dm_j} \right) u \right\} \right)_{x'} \right)_{x_i} =$$

$$\begin{aligned}
&= \left(\mathcal{U}^{-1\top} \left(e, h^\top(x_i, x) \right)_{x_i}, \left\{ \left(\frac{d\mathcal{U}}{dm_j} \right) u \right\}_x \right) = \\
&= \left(\lambda, \left\{ \left(\frac{d\mathcal{U}}{dm_j} \right) u \right\}_x \right) \quad \text{with} \quad \mathcal{U}_x^\top \lambda = \left(e, h^\top(x_i, x) \right)_{x_i}
\end{aligned}$$