#### Comparison of Several Ways to Compute Sensitivity Kernels

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## 1. Introduction

Consider a linear differential equation of the form,  $\mathcal{L}(c) u = s$ , where the field, u(x, y, z, t), and the source, s(x, y, z, t), depend on position, (x, y, z), and time, t, and where the differential operator,  $\mathcal{L}(c)$ , depends on a scalar material parameter, c. An example is a wave propagation problem, involving pressure, u, source, s, background velocity, v, and heterogeneity, cf(x, y, z)

$$\mathcal{L} = (v^2 + cf(x, y, z))\frac{\partial^2}{\partial t^2} - \nabla^2$$

Given time-dependent measurements,  $u_i^{obs}(t) = u^{obs}(x_i, y_i, z_i, t)$  at N observer positions (stations),  $(x_i, y_i, z_i)$ , the individual errors are defined as  $e_i = u_i^{obs} - u_i$ , and the total error as

$$E = \int \sum_{i} e_i^2 \, \mathrm{d}t$$

The term *sensitivity kernel* means either the partial derivative,  $\partial e_i/\partial c$  (the sensitivity of individual errors to perturbations in the material parameter) or  $\partial E/\partial c$  (the sensitivity kernel of the total error to perturbations in the material parameter), depending on context. Sensitivity kernels can be computed in a variety of ways.

Both sensitivity kernels depend on the quantity,  $\partial u_i/\partial c$ 

$$\frac{\partial e_i}{\partial c} = \frac{\partial}{\partial c} (u_i^{obs} - u_i) = -\frac{\partial u_i}{\partial c}$$
$$\frac{\partial E}{\partial c} = \frac{\partial}{\partial c} \int \sum_i e_i^2 dt = -\int \sum_i 2e_i \frac{\partial u_i}{\partial c} dt$$

The following mathematical trick helps to "hide" the stations in the formula for  $\partial E/\partial c$ . We imagine that the error,  $e = u^{obs} - u$  is known everywhere. Then,

$$\frac{\partial E}{\partial c} = -\int \sum_{i} 2e_i \frac{\partial u_i}{\partial c} dt = -\left(2q, \frac{\partial u}{\partial c}\right) \text{ with } q = \sum_{i} e_i \,\delta(x - x_i)\delta(y - y_i)\delta(z - z_i)$$

Here (.,.) is the inner product, defined as

$$(a,b) \equiv \int \iiint a \ b \ \mathrm{d}^3 x \ \mathrm{d} t$$

#### 2. Methods of computing $\partial u/\partial c$

2.1. Method A. Finite differences

Suppose that the differential equation,  $\mathcal{L}(c)u = s$  is solved twice, once for material parameter,  $c_0$ , leading to solution,  $u(c_0)$  and another for  $c_0 + \Delta c$ , leading to solution,  $u(c_0 + \Delta c)$ . The derivative,  $\partial u/\partial c$ , can be approximated as

$$\frac{\partial u_0}{\partial c} \equiv \frac{\partial u}{\partial c}\Big|_{c_0} \approx \frac{u(c_0 + \Delta c) - u(c_0)}{\Delta c}$$

And then  $\partial u_i / \partial c$  is just  $\partial u_0 / \partial c$  evaluated at  $(x_i, y_i, z_i)$ .

Superficially, this finite difference derivative hides the "interaction" that makes  $u(c_0 + \Delta c)$  different from  $u(c_0)$ . In a seismic problem, the interaction corresponds to the scattering of the wavefield off of the heterogeneity. However, the interaction can be teased out of this formula by substituting  $u = \mathcal{L}^{-1}s$ 

$$\frac{\partial u_0}{\partial c} \approx \frac{\left[\mathcal{L}(c_0 + \Delta c)\right]^{-1} - \left[\mathcal{L}(c_0)\right]^{-1}}{\Delta c} s = \frac{\partial \mathcal{L}^{-1}}{\partial c} \bigg|_{c_0} s = -\mathcal{L}_0^{-1} \frac{\partial \mathcal{L}_0}{\partial c} \mathcal{L}_0^{-1} s = -\mathcal{L}_0^{-1} \frac{\partial \mathcal{L}_0}{\partial c} u_0$$

Here, we have defined  $u_0 \equiv u(c_0)$ ,  $\mathcal{L}_0 \equiv \mathcal{L}(c_0)$  and  $\partial \mathcal{L}_0 / \partial c \equiv \partial \mathcal{L} / \partial c |_{c_0}$  and have used the rule,

$$\frac{\partial \mathcal{L}^{-1}}{\partial c} = -\mathcal{L}^{-1} \frac{\partial \mathcal{L}}{\partial c} \mathcal{L}^{-1}$$

(which is derived by differentiating  $\mathcal{LL}^{-1} = \mathcal{I}$ , where  $\mathcal{I}$  is the identity operator). Thus,  $\partial u_0 / \partial c$  satisfies a differential equation

$$\mathcal{L}_0 \frac{\partial u_0}{\partial c} \approx -\frac{\partial \mathcal{L}_0}{\partial c} u_0$$

the r.h.s. of which is the "virtual source" or the "scattering interaction".

2.2 Method B. Born approximation

We consider unperturbed and perturbed differential equations:

$$\mathcal{L}(c_0) u(c_0) = s$$
$$\mathcal{L}(c_0 + \Delta c) u(c_0 + \Delta c) = s$$

We expand both  $\mathcal{L}(c_0 + \Delta c)$  and  $u(c_0 + \Delta c)$  in Taylor series

$$\left(\mathcal{L}_0 + \frac{\partial \mathcal{L}_0}{\partial c} \Delta c\right) \left(u_0 + \frac{\partial u}{\partial c} \Delta c\right) = s$$

Multiply out and discard the higher order term

$$\mathcal{L}_0 u_0 + \mathcal{L}_0 \frac{\partial u}{\partial c} \Delta c + \frac{\partial \mathcal{L}_0}{\partial c} \Delta c u_0 = s$$

Subtract the unperturbed equation

$$\mathcal{L}_0 \frac{\partial u}{\partial c} \Delta c + \frac{\partial \mathcal{L}_0}{\partial c} \Delta c u_0 = 0$$

And rearrange, yielding the same formula as before.

$$\frac{\partial u_0}{\partial c} \equiv \frac{\partial u}{\partial c}\Big|_{c_0} = -\mathcal{L}_0^{-1} \frac{\partial \mathcal{L}_0}{\partial c} u_0$$

# 2.3. Method C, direct differentiation

We differentiate

$$u(c) = \mathcal{L}^{-1}(c)s$$

to get

$$\frac{\partial u}{\partial c} = \frac{\partial \mathcal{L}^{-1}}{\partial c}s = -\mathcal{L}^{-1}\frac{\partial \mathcal{L}_0}{\partial c}\mathcal{L}^{-1}s = -\mathcal{L}^{-1}\frac{\partial \mathcal{L}}{\partial c}u$$

or

$$\frac{\partial u_0}{\partial c} = -\mathcal{L}_0^{-1} \frac{\partial \mathcal{L}_0}{\partial c} u_0$$

Reassuringly, all three methods give identical results.

3. Methods of computing  $\partial E / \partial c$ 

3.1 Direct methods

Step A. Compute  $u_0$  everywhere by solving  $\mathcal{L}_0 u_0 = s$ , and sample it to get its values at the receivers.

Step B. Compute  $\partial u_0 / \partial c$  everywhere, either by finite differences or by solving

$$\mathcal{L}_0 \frac{\partial u_0}{\partial c} \approx -\frac{\partial \mathcal{L}_0}{\partial c} u_0$$

and sample it to get its values at the receivers.

Step C. Perform the integrals/summation

$$\frac{\partial E}{\partial c} = -\int \sum_{i} 2e_{i} \frac{\partial u_{i}}{\partial c} \, \mathrm{d}t$$

Irrespective of details, two differential equations must be solved and one integration/summation must be performed to compute  $\partial E/\partial c$ . In practice, the heterogeneities are described by many (say *M*) *c*s, so that 2*M* solutions and 1*M* integrations/summations must be performed.

### 3.2 Adjoint method

Step A. Substitute

$$\frac{\partial u_0}{\partial c} = -\mathcal{L}_0^{-1} \frac{\partial \mathcal{L}_0}{\partial c} u_0 \quad \text{into} \quad \frac{\partial E}{\partial c} = -\left(2q, \frac{\partial u_0}{\partial c}\right)$$

to get

$$\frac{\partial E_0}{\partial c} = \left(2q, \mathcal{L}_0^{-1} \frac{\partial \mathcal{L}_0}{\partial c} u_0\right)$$

Step B. Use the adjoint method to move  $\mathcal{L}_0^{-1}$  to other side of inner product

$$\frac{\partial E_0}{\partial c} = \left(2\mathcal{L}_0^{\dagger - 1}q, \frac{\partial \mathcal{L}_0}{\partial c}u_0\right)$$

Here, we have used fact that adjoint of an inverse is the inverse of an adjoint.

Step C. Now define,  $\lambda \equiv \mathcal{L}_0^{\dagger - 1} q$  so that the "adjoint field"  $\lambda$  satisfies the adjoint differential equation

$$\mathcal{L}_0^{\dagger} \lambda \equiv q$$

and solve this equation for  $\lambda$ .

Step D. Perform the inner product

$$\frac{\partial E_0}{\partial c} = \left(2\lambda, \frac{\partial \mathcal{L}_0}{\partial c}u_0\right)$$

This looks complicated, so why do people do it? The answer is all the information about the heterogeneity is in the  $\partial \mathcal{L}_0 / \partial c$  factor. Irrespective of the number of heterogeneities, you need perform only two solutions of differential equations, one for  $u_0$  and one for  $\lambda$ . You still need to perform *M* inner products, one for each distinct  $\partial \mathcal{L}_0 / \partial c$ , but that's the easy part.

In summary, the adjoint method provides a method for computing  $\partial E_0/\partial c$  than is much more computationally efficient than direct methods.