Gradient of a parameter in a nonlinear differential equation: Example

Bill Menke, for Aaron Stubblefield, April 20, 2018

The nonlinear differential equation for the field u(t):

 $u' + bu + ce^{bt}u^2 = 0$ with u(t = 0) = 1

(where prime denotes differentiation with respect to t) has solution:

$$u(t) = \frac{e^{-bt}}{1+ct}$$
 and $u'(t) = \frac{-be^{-bt}}{1+ct} + \frac{-ce^{-bt}}{(1+ct)^2}$

This solution can be verified by direct substitution into the differential equation:

$$\frac{-be^{-bt}}{1+ct} + \frac{-ce^{-bt}}{(1+ct)^2} + \frac{e^{-bt}}{1+ct} + ce^{bt}\frac{e^{-2bt}}{(1+ct)^2} = \frac{-be^{-bt}}{1+ct} + \frac{e^{-bt}}{1+ct} + \frac{-ce^{-bt}}{(1+ct)^2} + \frac{ce^{-bt}}{(1+ct)^2} = 0$$

and by noting that it satisfied the boundary condition u(t) = 1 for all values of c.

Now consider the case $c = c_0 + \delta c$ and $u = u_0 + \delta u$. Since we know the solution, the partial derivative of the field with respect to the parameter *c* can be calculated directly:

$$\frac{\partial u}{\partial c} = \frac{-te^{-bt}}{(1+ct)^2} \text{ so that } u \approx u_0 + \delta u = u_0 + \frac{\partial u}{\partial c} \delta c = \frac{e^{-bt}}{(1+c_0t)} + \frac{-\delta c \ te^{-bt}}{(1+c_0t)^2}$$

The derivative can also be computed by solving the differential equation associated with the Born approximation. We insert $c = c_0 + \delta c$ and $u = u_0 + \delta u$ into the differential equation and keep only terms up to first order in small quantities:

$$u_{0}' + \delta u' + bu_{0} + b\delta u + (c_{0} + \delta c) e^{bt} (u_{0} + \delta u)^{2} \approx$$
$$u_{0}' + \delta u' + bu_{0} + b\delta u + (c_{0} + \delta c) e^{bt} (u_{0}^{2} + 2u_{0}\delta u) =$$
$$u_{0}' + bu_{0} + c_{0}e^{bt}u_{0}^{2} + \delta u' + b\delta u + \delta c e^{bt}u_{0}^{2} + 2c_{0}e^{bt}u_{0}\delta u = 0$$

Subtracting out the unperturbed equation yields a differential equation for δu :

$$\delta u' + (b + 2c_0 e^{bt} u_0) \delta u + \delta c e^{bt} u_0^2 = 0$$
 with $\delta u(t = 0) = 0$

or

$$\mathcal{L} \,\delta u = f_0 \quad with \quad \mathcal{L} \equiv \frac{\partial}{\partial t} + (b + 2c_0 e^{bt} u_0) \quad \text{and} \quad f_0 \equiv -e^{bt} u_0^2 \,\delta c$$

That the solution to this equation is:

$$\delta u = \frac{-\delta c \ t e^{-bt}}{(1+c_0 t)^2} \quad \text{and} \quad \delta u' = \frac{-\delta c \ e^{-bt}}{(1+c_0 t)^2} + \frac{b \ \delta c \ t e^{-bt}}{(1+c_0 t)^2} + \frac{2c_0 \delta c \ t e^{-bt}}{(1+c_0 t)^3}$$

can be verified by substitution:

$$\begin{split} \delta u' + b\delta u + 2c_0 e^{bt} u_0 \delta u + \delta c \; e^{bt} u_0^2 &= \\ \frac{-\delta c e^{-bt}}{(1+c_0 t)^2} + \frac{b \; \delta c \; t e^{-bt}}{(1+c_0 t)^2} + \frac{2c_0 \delta c \; t e^{-bt}}{(1+c_0 t)^3} + \frac{-b\delta c \; t e^{-bt}}{(1+c_0 t)^2} + \\ -2c_0 e^{bt} \; \frac{e^{-bt}}{(1+c_0 t)} \frac{\delta c \; t e^{-bt}}{(1+c_0 t)^2} + \delta c \; e^{bt} \; \frac{e^{-2bt}}{(1+c_0 t)^2} = \\ \frac{-\delta c e^{-bt}}{(1+c_0 t)^2} + \frac{b \; \delta c \; t e^{-bt}}{(1+c_0 t)^2} + \frac{2c_0 \delta c \; t e^{-bt}}{(1+c_0 t)^3} + \frac{-b\delta c \; t e^{-bt}}{(1+c_0 t)^2} + \\ -\frac{2c_0 \delta c \; t e^{-bt}}{(1+c_0 t)^3} + \frac{\delta c e^{-bt}}{(1+c_0 t)^2} = 0 \end{split}$$

Now suppose that we have $u^{obs}(t)$ and define and error E(c) = (e, e) with $e = u^{obs} - u$. We find,

$$\frac{\partial E}{\partial c}\Big|_{c_0} = \left(\frac{\partial u}{\partial c}, -2e_0\right) = \left(\frac{\partial}{\partial c}\left(\mathcal{L}^{-1}f_0\right), -2e_0\right) = \left(\mathcal{L}^{-1}\frac{\partial f_0}{\partial c}, -2e_0\right) =$$

$$(e^{bt}u_0^2, -2\mathcal{L}^{-1\dagger}e_0) = (-2e^{bt}u_0^2, \mathcal{L}^{-1\dagger}e_0) = (-2e^{bt}u_0^2, \lambda)$$

with $\mathcal{L}^{\dagger}\lambda = e_0$ and noting that $\partial f_0 / \partial c = \partial f_0 / \partial \delta c$, since c_0 is constant.